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## 1.4. Document Organization

This document contains the following chapters:

[Chapter 1: “Introduction”](#) provides a scope for this document, target audience, contact and support information, and text conventions.

[Chapter 2: “Overview”](#) provides an overview of the document.

[Chapter 3: “Mechanical Dimensions”](#)

[Chapter 4: “Electrical Connections”](#) deals with the pin out configuration and layout.

[Chapter 5: “Hardware Commands”](#) How to operate on the module via hardware.

[Chapter 6: “Power supply”](#) Power supply requirements and general design rules.

[Chapter 7: “Antenna”](#) The antenna connection and board layout design are the most important parts in the full product design

[Chapter 8: “Logic Level specifications”](#) Specific values adopted in the implementation of logic levels for the modules.

[Chapter 9: “Serial ports”](#) The serial port on the modules is the core of the interface between the module and OEM hardware

[Chapter 10: “Audio Section overview”](#) Refers to the audio blocks of the Base Band Chip of the modules.

[Chapter 11: “General Purpose I/O”](#) How the general purpose I/O pads can be configured.

[Chapter 12: “GPS Features \(GE864-GPS only\)”](#)

[Chapter 13: “DAC and ADC Converter”](#) How the DAC and ADC pads can be configured.

[Chapter 14: “Mounting the GE/GC864-QUAD V2 AND GE864-GPS on the application board”](#) Recommendations and specifics on how to mount the modules on the user’s board.

[Chapter 15: “Packing System”](#): deals about the GE/GC864 family packaging systems

[Chapter 16: “Conformity Assessment Issues”](#): refer the compliance with reference standards

[Chapter 17: “Safety Recommendations”](#): contains recommendations for proper and safe user

[Chapter 18: “Document History”](#):





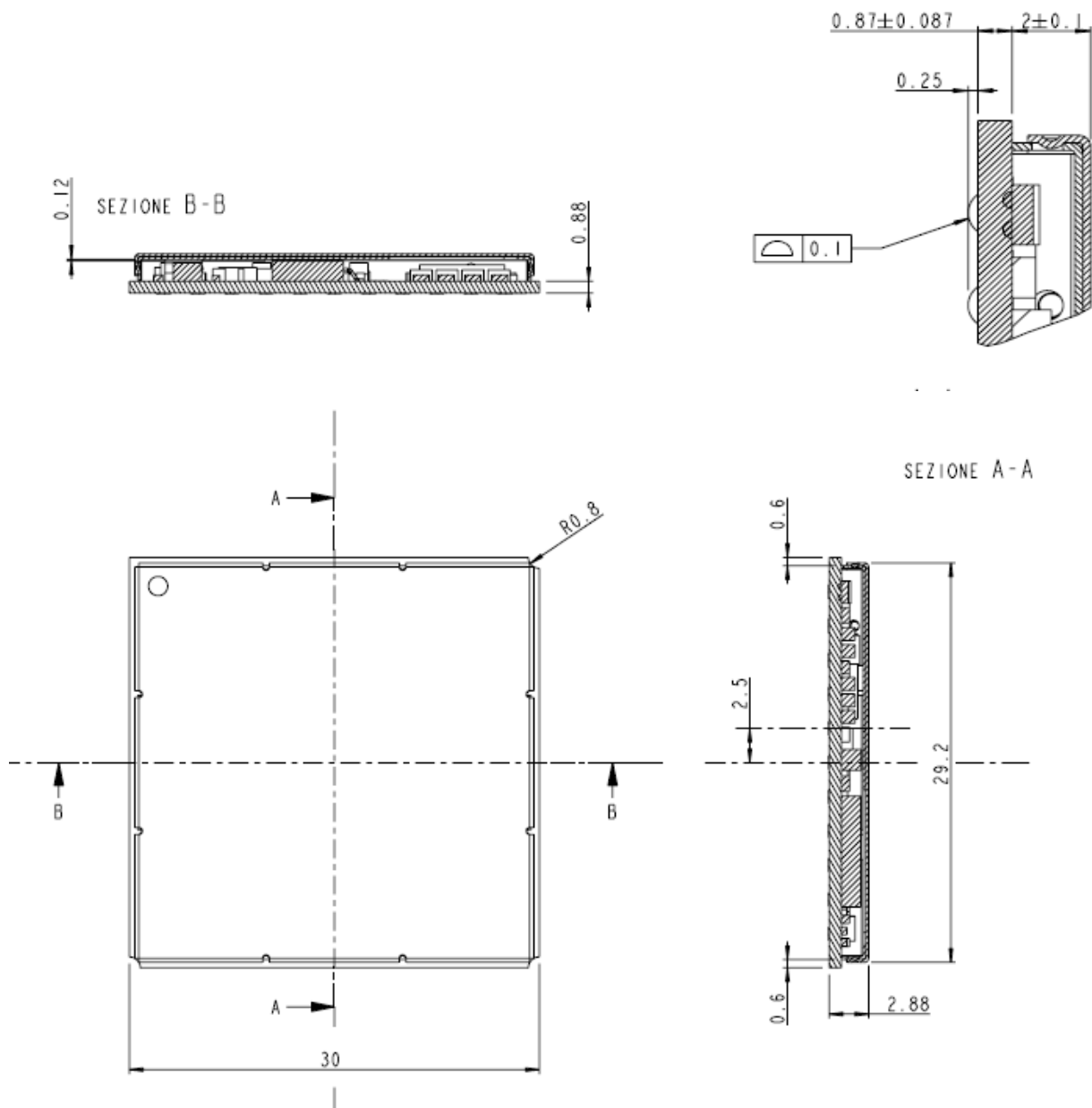


### 3. GE864-QUAD V2/GPS Mechanical Dimensions

#### 3.1. GE864-QUAD V2/GPS

The Telit GE864-QUAD V2/GPS modules overall dimensions are:

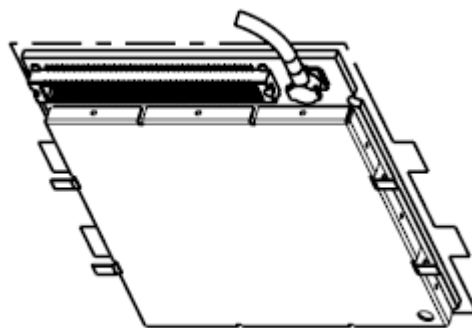
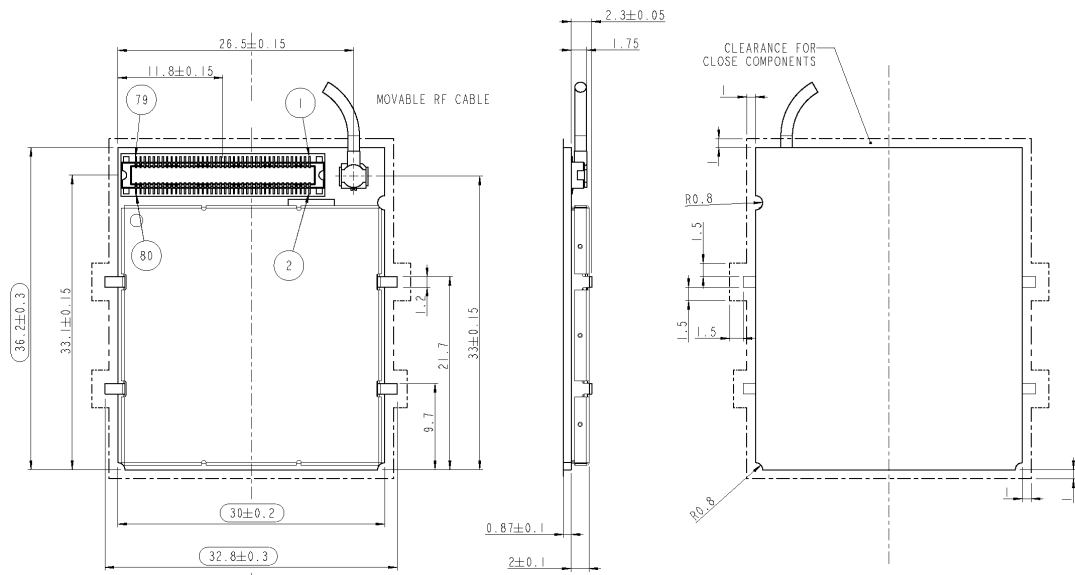
- Length: 30 mm
- Width: 30 mm
- Thickness : 2,9 mm
- Weight: 4.2g



### 3.2. GC864-QUAD V2

The Telit GC864-QUAD V2 module overall dimensions are:

- Length: 36.2 mm
- Width: 30 mm
- Thickness: 3.2 mm
- Weight: 4.8g









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Ball	Signal	I/O	Function	Internal PULL UP	Type
C7	DAC_OUT	AO	Digital/Analog converter output		D/A
J11	ADC_IN1	AI	Analog/Digital converter input		A/D
H11	ADC_IN2	AI	Analog/Digital converter input		A/D
<b>Miscellaneous Functions</b>					
A2	RESET#	I	Reset input		
D8	STAT_LED	O	Status indicator led		CMOS 1.8V
E2	VRTC	AO	VRTC		Power
J5	ON_OFF#	I	Input command for switching power ON or OFF (toggle command). The pulse to be sent to the GE864-QUAD V2 must be equal or greater than 1 second.	Pull up 47K	Pull up to VBATT
L8	PWRMON	O	PWRMON		CMOS 2.8V
L4	GSM Antenna	O	Antenna output – 50 ohm		RF
D5	VAUX <sup>(1)</sup>	AO	Auxiliary 2.8V Output		Power
<b>Telit GPIO / DVI</b>					
C1	GPIO_01	I/O	GPIO_01		CMOS 2.8V
E6	GPIO_02 / JDR	I/O	GPIO_02 / JDR		CMOS 2.8V
C2	GPIO_03	I/O	GPIO_03		CMOS 2.8V
B3	GPIO_04 / TX_DISABLE	I/O	GPIO_04 / TX_DISABLE		CMOS 2.8V
K8	GPIO_05 / RFTXMON	I/O	Telit GPIO05 Configurable GPIO / Transmitter ON monitor		CMOS 2.8V
B5	GPIO_06 / ALARM	I/O	Telit GPIO06 Configurable GPIO / ALARM		CMOS 2.8V
L9	GPIO_07 / BUZZER	I/O	Telit GPIO07 Configurable GPIO / Buzzer		CMOS 2.8V
K11	GPIO_08	I/O	GPIO_08		CMOS 2.8V
C9	GPIO_09	I/O	GPIO_09		CMOS 2.8V
H3	GPIO_10 / DVI_TX	I/O	GPIO_10 / DVI_TX - DVI audio <sup>(1)</sup>		CMOS 2.8V
K7	DVI_RX	I/O	DVI_RX - DVI audio <sup>(1)</sup>		CMOS 2.8V
D7	DVI_CLK	I/O	DVI_CLK - DVI audio <sup>(1)</sup>		CMOS 2.8V
H5	DVI_WA0	I/O	DVI_WA0 - DVI audio <sup>(1)</sup>		CMOS 2.8V
<b>GPS<sup>(2)</sup> (only for GE864-GPS)</b>					
A7	GPS_EXT_LNA_EN <sup>(2)</sup>	O	External LNA Enable		CMOS 1.8V (GPS)
C8	GPS_PPS <sup>(2)</sup>	O	Pulse Per Second		CMOS 1.8V (GPS)
E10	GPS_RX <sup>(2)</sup>	I	Serial Data Input		CMOS 2.8V (GPS)
F8	GPS_TX <sup>(2)</sup>	O	Serial Data Output		CMOS 2.8V (GPS)
G2	GPS_WAKEUP <sup>(2)</sup>	O	Wake up output		CMOS 2.8V (GPS)
J4	GPS_ON_OFF <sup>(2)</sup>	I	GPS Power Control		CMOS 1.8V (GPS)
A10	GPS Antenna <sup>(2)</sup>	O	Antenna output – 50 ohm		RF
C6 <sup>(1)(2)</sup>	-	-	Diagnostic (to be connected to Vaux through a pull-up resistor <sup>(2)(3)</sup> )		
G6 <sup>(1)(2)</sup>	-	-	Diagnostic (to be connected to ground <sup>(2)(3)</sup> )		
<b>Power Supply</b>					
J1	VBATT	-	Main power supply		Power
K1	VBATT	-	Main power supply		Power
J2	VBATT	-	Main power supply		Power
K2	VBATT	-	Main power supply		Power
A1	GND	-	Ground		Power



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Ball	Signal	I/O	Function	Internal PULL UP	Type
A11	GND	-	Ground		Power
D6	GND	-	Ground		Power
F1	GND	-	Ground		Power
F11	GND	-	Ground		Power
H1	GND	-	Ground		Power
H2	GND	-	Ground		Power
J3	GND	-	Ground		Power
K3	GND	-	Ground		Power
K4	GND	-	Ground		Power
K5	GND	-	Ground		Power
K6	GND	-	Ground		Power
L1	GND	-	Ground		Power
L2	GND	-	Ground		Power
L3	GND	-	Ground		Power
L6	GND	-	Ground		Power
L11	GND	-	Ground		Power
A8	GND <sup>(2)</sup>	-	Ground <sup>(2)</sup>		Power
B8	GND <sup>(2)</sup>	-	Ground <sup>(2)</sup>		Power
B9	GND <sup>(2)</sup>	-	Ground <sup>(2)</sup>		Power
B10	GND <sup>(2)</sup>	-	Ground <sup>(2)</sup>		Power
B11	GND <sup>(2)</sup>	-	Ground <sup>(2)</sup>		Power
<b>RESERVED</b>					
A3	-	-	Reserved		
A4	-	-	Reserved		
A5	-	-	Reserved		
A6	-	-	Reserved		
A9	-	-	Reserved		
B1	-	-	Reserved		
B2	-	-	Reserved		
B4	-	-	Reserved		
C3	-	-	Reserved		
C4	-	-	Reserved		
C5	-	-	Reserved		
D1	-	-	Reserved		
D2	-	-	Reserved		
D3	-	-	Reserved		
E1	-	-	Reserved		
E3	-	-	Reserved		
E4	-	-	Reserved		
E5	-	-	Reserved		
E8	-	-	Reserved		
F2	-	-	Reserved		









### 4.1.2. BGA Balls Layout

TOP VIEW

	A	B	C	D	E	F	G	H	J	K	L
1	GND	-	GPIO_01	-	-	GND	-	GND	VBATT	VBATT	GND
2	RESET*	-	GPIO_03	-	VRTC	-	GPS_WAK EUP <sup>1</sup>	GND	VBATT	VBATT	GND
3	-	GPIO_04 / TX_DISABLE	-	-	-	-	-	GPIO_10 / DVI_TX	GND	GND	GND
4	-	-	-	SIMVCC	-	-	-	SERVICE	GPS_ON_ OFF <sup>1</sup>	GND	GSM Antenna
5	-	GPIO_06 / ALARM	-	VAUX <sup>1</sup>	-	-	-	DVI_WA0	ON_OFF*	GND	-
6	-	C125 / RING	Diagnostic	GND	GPIO_02 / JDR	C106 / CTS	Diagnostic	-	-	GND	GND
7	GPS_EXT LNA_EN <sup>3</sup>	C108 / DTR	DAC_OUT	DVI_CLK	C103 / TXD	C105 / RTS	-	-	-	DVI_RX	-
8	GND <sup>1</sup>	GND <sup>1</sup>	GPS_PPS <sup>1</sup>	STAD_ LED	-	GPS_TX <sup>1</sup>	MIC_HF+	C104 / RXD	MIC_MT+	GPIO_05 / RFTXMON	PWRMON
9	-	GND <sup>1</sup>	GPIO_09	C109 / DCD	SIMRST	AXE	MIC_MT-	EAR_MT-	MIC_HF-	-	GPIO_07 / BUZZER
10	GPS Antenna <sup>1</sup>	GND <sup>1</sup>	SIMCLK	SIMIO	GPS_RX <sup>1</sup>	RX_AUX	EAR_MT+	EAR_HF+	EAR_HF-	-	-
11	GND <sup>1</sup>	GND <sup>1</sup>	SIMIN	TX_AUX	C107 / DSR	GND	-	ADC_IN2	ADC_IN1	GPIO_08	GND

(1) Available only on GE864-GPS (in case of GE864-QUAD V2 it has to be considered RESERVED)







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Pin	Signal	I/O	Function	Internal Pull up	Type
			TX_TRACE). The pin shall be tied low to enable the feature only in case of a SW Update activity. It is required, for debug purpose, to be connected to a test pad on the final application.		
<b>Prog. / Data + Hw Flow Control</b>					
25	C103/TXD	I	Serial data input (TXD) from DTE		CMOS 2.8V
26	C104/RXD	O	Serial data output (RXD) to DTE		CMOS 2.8V
27	C107/DSR	O	Output for Data set ready signal (DSR) to DTE		CMOS 2.8V
28	C106/CTS	O	Output for Clear to send signal (CTS) to DTE		CMOS 2.8V
29	C108/DTR	I	Input for Data terminal ready signal (DTR) from DTE		CMOS 2.8V
30	C125/RING	O	Output for Ring indicator signal (RI) to DTE		CMOS 2.8V
31	C105/RTS	I	Input for Request to send signal (RTS) from DTE		CMOS 2.8V
32	C109/DCD	O	Output for Data carrier detect signal (DCD) to DTE		CMOS 2.8V
<b>DAC and ADC</b>					
37	ADC_IN1	AI	Analog/Digital converter input		A/D
38	ADC_IN2	AI	Analog/Digital converter input		A/D
39	ADC_IN3	AI	Analog/Digital converter input		A/D
40	DAC_OUT	AO	Digital/Analog converter output		D/A
<b>Miscellaneous Functions</b>					
45	STAT_LED	O	Status indicator led		CMOS 1.8V
46	GND	-	Ground		Ground
49	PWRMON	O	Power ON Monitor		CMOS 2.8V
53	ON/OFF*	I	Input command for switching power ON or OFF (toggle command). The pulse to be sent to the GC864-QUAD V2 must be equal or greater than 1 second.	47K $\Omega$	Pull up to VBATT
54	RESET*	I	Reset input		
55	VRTC	AO	VRTC Backup capacitor		Power
<b>Telit GPIO / DVI</b>					
36	DVI_CLK	-	DVI_CLK (Digital Voice Interface Clock)		CMOS 2.8V
59	TGPIO_04/TXCNTL	I/O	Telit GPIO4 Configurable GPIO / RF Transmission Control		CMOS 2.8V
63	TGPIO_10/DVI_TX	I/O	Telit GPIO10 Configurable GPIO / DVI_TX (Digital Voice Interface)		CMOS 2.8V
65	DVI_RX	I/O	DVI_RX (Digital Voice Interface)		CMOS 2.8V
66	TGPIO_03	I/O	Telit GPIO3 Configurable GPIO		CMOS 2.8V
67	TGPIO_08	I/O	Telit GPIO8 Configurable GPIO		CMOS 2.8V
68	TGPIO_06 / ALARM	I/O	Telit GPIO6 Configurable GPIO / ALARM		CMOS 2.8V
70	TGPIO_01	I/O	Telit GPIO1 Configurable GPIO		CMOS 2.8V
71	DVI_WAO	I/O	DVI_WAO (Digital Voice Interface)		CMOS 2.8V
73	TGPIO_07 / BUZZER	I/O	Telit GPIO7 Configurable GPIO / Buzzer		CMOS 2.8V
74	TGPIO_02 / JDR	I/O	Telit GPIO02 I/O pin / Jammer detect report		CMOS 2.8V
76	TGPIO_09	I/O	Telit GPIO9 Configurable GPIO		CMOS 2.8V
78	TGPIO_05/RFTXMON	I/O	Telit GPIO05 Configurable GPIO / Transmitter ON monitor		CMOS 2.8V







**NOTE:**

If not used, almost all pins must be left disconnected. The only exceptions are the following pins:

Pin	Signal	Function
1	VBATT	Main power supply
2	VBATT	Main power supply
3	VBATT	Main power supply
4	VBATT	Main power supply
5	GND	Ground
6	GND	Ground
7	GND	Ground
46	GND	Ground
25	C103/TXD	Serial data input (TXD) from DTE
26	C104/RXD	Serial data output to DTE
31	C105/RTS	Input for Request to send signal (RTS) from DTE
53	ON/OFF*	Input command for switching power ON or OFF (toggle command).
54	RESET*	Reset input
23	RX_TRACE	RX Data for debug monitor
24	TX_TRACE	TX Data for debug monitor
47	SERVICE	SERVICE connection

**4.2.2. GC864-QUAD V2 Antenna Connector**

The GC864-QUAD V2 module is equipped with a 50 ohm RF connector from Murata, GSC type P/N MM9329-2700B.

The counterpart suitable is Murata MXTK92 Type or MXTK88 Type.

Moreover, the GC864-QUAD V2 has the antenna pads on the back side of the PCB. This allows the manual soldering of the coaxial cable directly on the back side of the PCB. However, the soldering is not an advisable solution for a reliable connection of the antenna.



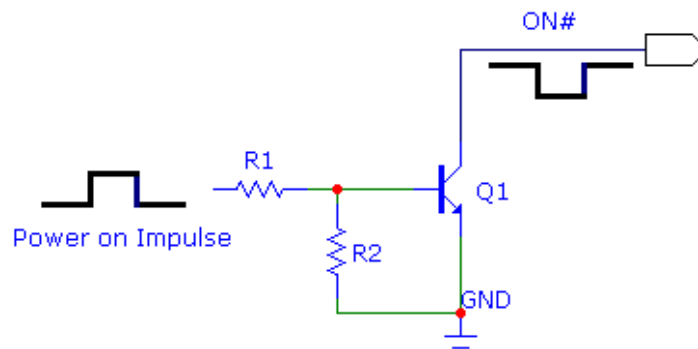
## 5. Hardware Commands

### 5.1. Turning ON the GE/GC864-QUAD V2 and GE864-GPS

To turn ON the GE/GC864-QUAD V2 AND GE864-GPS the pad ON# must be tied low for at least 1 second and then released. Pulse duration less than 1000ms should also start the power on procedure, but this is not guaranteed.

When the power supply voltage is lower than 3.4V the pad ON# must be tied low for at least 5 seconds.

The maximum current that can be drained from the ON# pad is 0.1 mA.  
A simple circuit to do it is:



**NOTE:**

Don't use any pull up resistor on the ON# line, it is internally pulled up. Using pull up resistor may bring to latch up problems on the module, power regulator and improper power on/off of the module. The line ON# must be connected only in open collector configuration.



**NOTE:**

In this document all the lines that are inverted, hence have active low signals are labeled with a name that ends with a "#".





**TIP:**

To check if the device has powered on, the hardware line PWRMON should be monitored. After 1000ms the line raised up the device could be considered powered on.

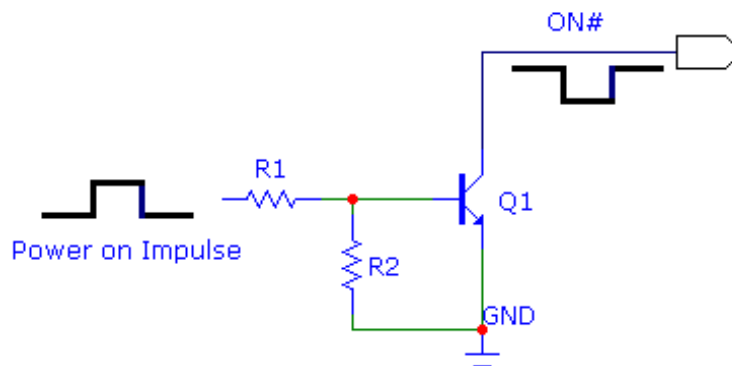


**NOTE:**

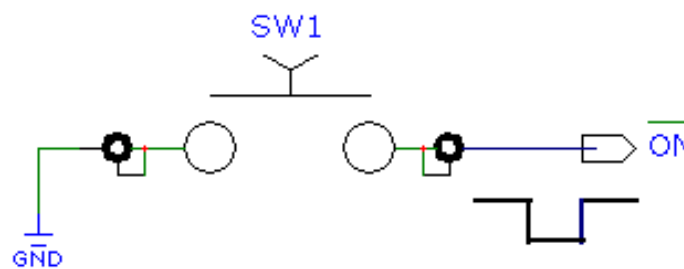
When the power supply voltage is lower than 3.4V, to turn ON the module, the pad ON# must be tied low for at least 5 seconds.

For example:

- 1- Let us assume you need to drive the ON# pad with a totem pole output from +1.8V up to 5V microcontroller:

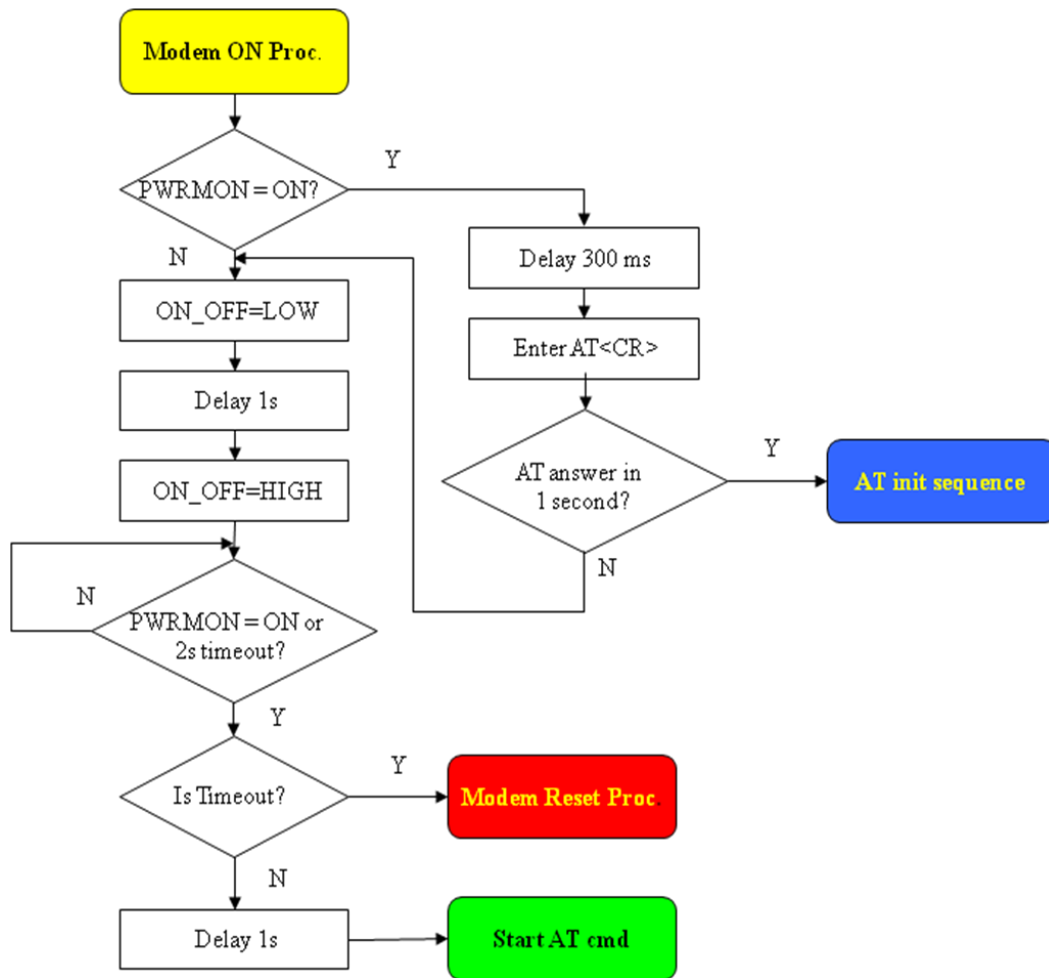


- 2- Let us assume you need to drive the ON# pad directly with an ON/OFF button:



A flow chart showing the proper turn on procedure is displayed below:





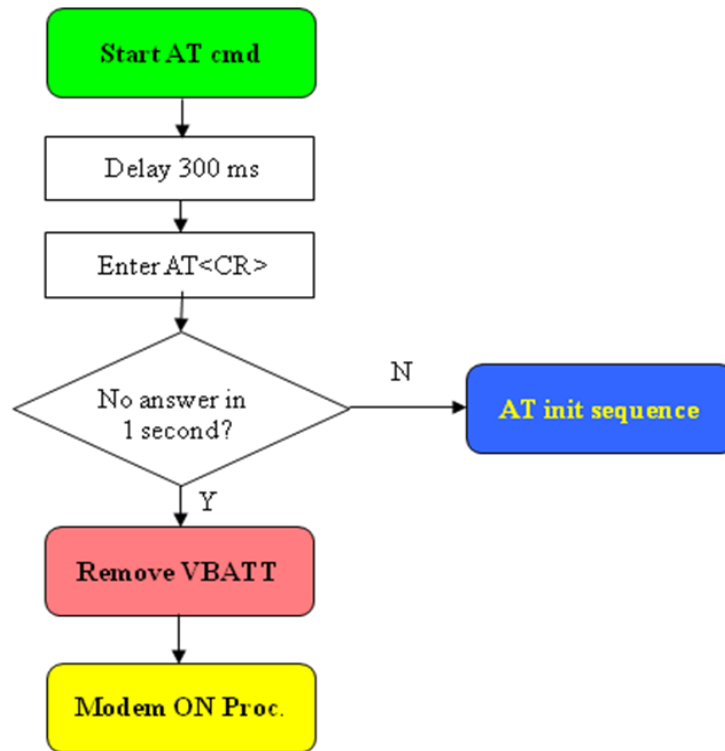
**NOTE:**

In order to avoid a back powering effect it is recommended to avoid having any HIGH logic level signal applied to the digital pins of the module when is powered OFF or during an ON/OFF transition.





A flow chart showing the AT commands managing procedure is displayed below:



## 5.2. Turning OFF the GE/GC864-QUAD V2 and GE864 GPS

The turning off of the device can be done in two ways:

- via AT command (see Software User Guide AT#SHDN)
- by tying low pin ON#

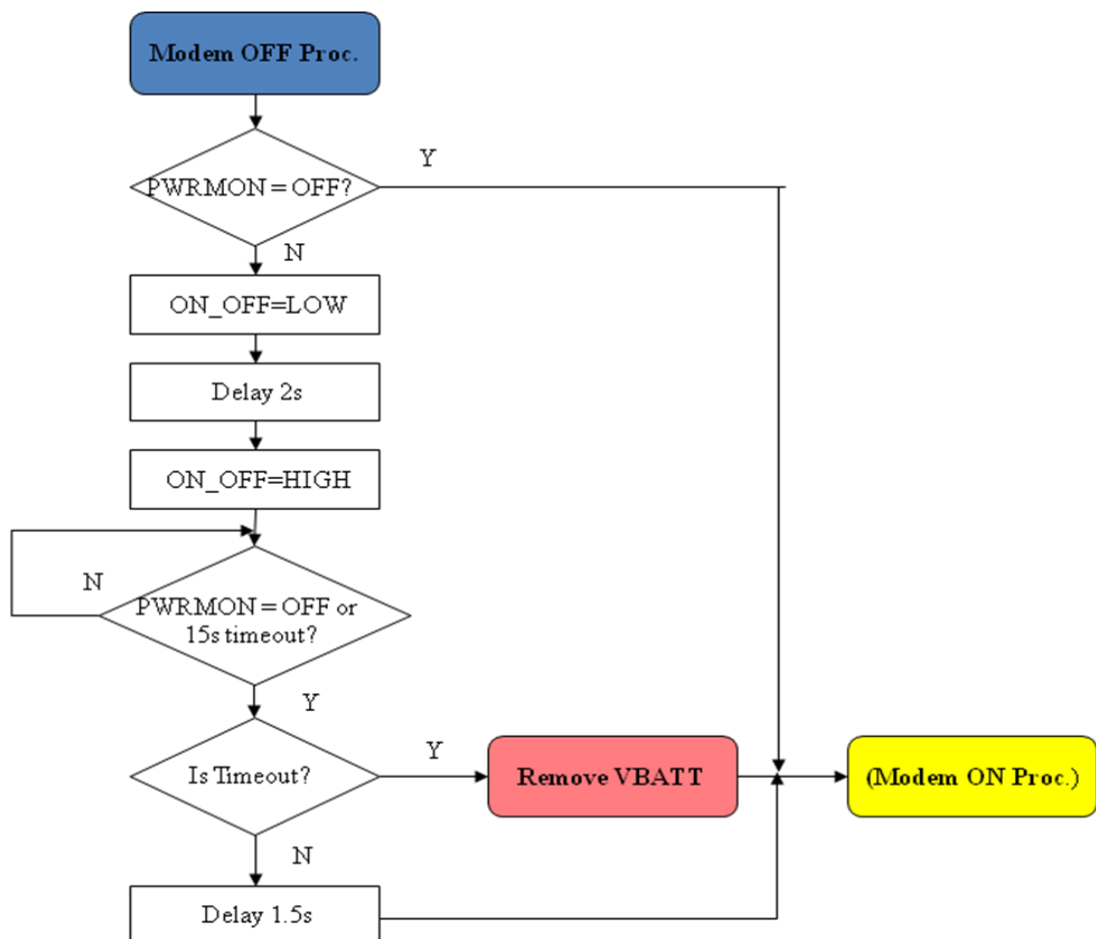
Either ways, when the device issues a detach request to the network informing that the device will not be reachable any more.

To turn OFF the module the pad ON# must be tied low for at least 2 seconds and then released.

The same circuitry and timing for the power on shall be used.

The device shuts down after the release of the ON# pad.

The following flow chart shows the proper turnoff procedure:





**TIP:**

To check if the device has been powered off, the hardware line PWRMON must be monitored. The device is powered off when PWRMON goes low.



**NOTE:**

In order to avoid a back powering effect it is recommended to avoid having any HIGH logic level signal applied to the digital pins of the module when is powered OFF or during an ON/OFF transition.



## 5.3. Hardware Unconditional Restart



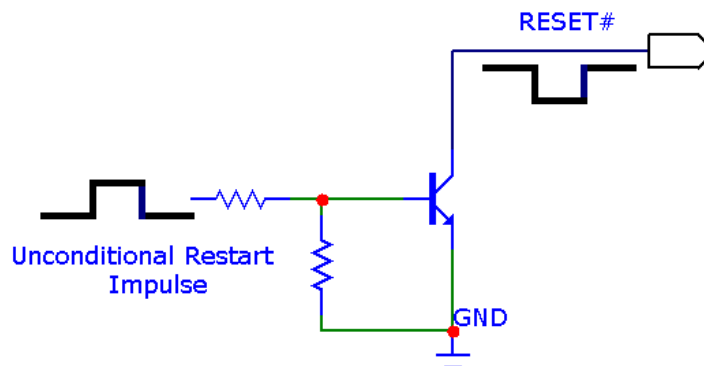
### WARNING:

The hardware unconditional Restart must not be used during normal operation of the device since it does not detach the device from the network. It shall be kept as an emergency exit procedure to be done in the rare case that the device gets stacked waiting for some network or SIM responses.

To unconditionally restart the module, the pad RESET# must be tied low for at least 200 milliseconds and then released.

The maximum current that can be drained from the RESET# pad is 0.15 mA.

A simple circuit to do it is:



### NOTE:

Do not use any pull up resistor on the RESET# line or any totem pole digital output. Using pull up resistor may bring to latch up problems on the module power regulator and improper functioning of the module. The line RESET# must be connected only in open collector configuration.

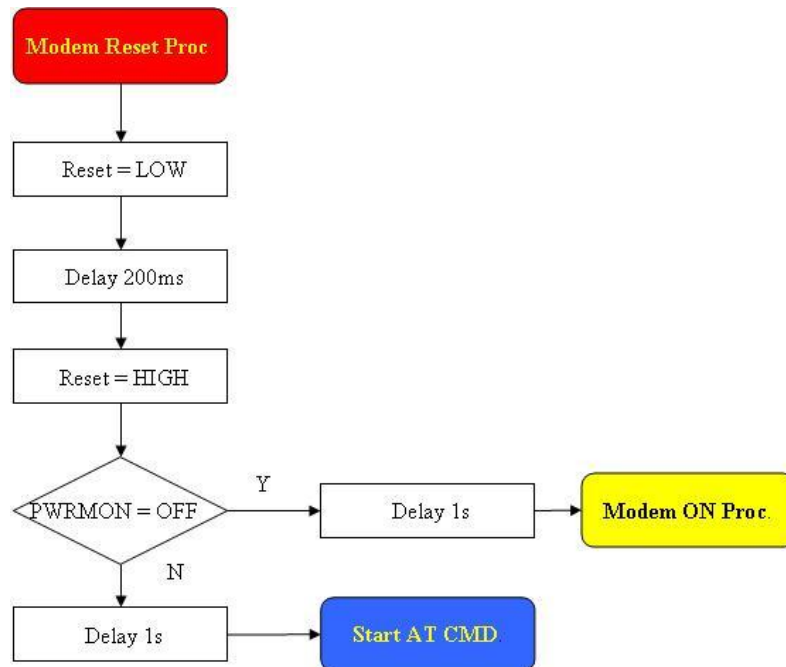




**TIP:**

The unconditional hardware Restart must always be implemented on the boards and must be used by the software as an emergency exit procedure.

The following flow chart shows the proper RESET procedure:



**NOTE:**

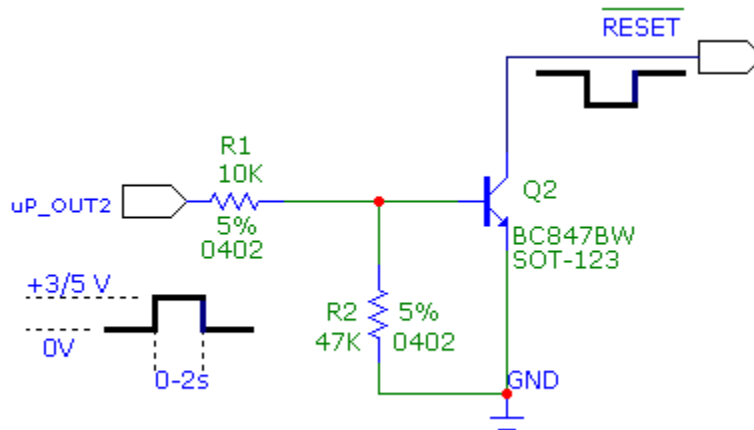
In order to avoid a back powering effect it is recommended to avoid having any HIGH logic level signal applied to the digital pins of the module when is powered OFF or during an ON/OFF transition.





For example:

Let us assume you need to drive the RESET# pad with a totem pole output from +1.8V up to 5V microcontroller



This signal is internally pulled up so the pin can be left floating if not used.







## 6.2. Power Consumption

The table below shows the power consumption of the GSM/GPRS section in different working modes (common for all the modules):

GE\GC864-QUAD V2 and GE864-GPS (GPS OFF)		
Mode	Average (mA)	Mode description
<b>SWITCHED OFF</b>		
Switched Off	<62 uA	Module supplied but Switched Off
<b>IDLE mode</b>		
AT+CFUN=1	16.0	Normal mode: full functionality of the module
AT+CFUN=4	16.0	Disabled TX and RX; module is not registered on the network
AT+CFUN=0 or =5	3.9	Paging Multiframe 2
	2.5	Paging Multiframe 3
	2.4	Paging Multiframe 4
	1.5	Paging Multiframe 9
<b>CSD TX and RX mode</b>		
GSM900 CSD PL5	240	GSM VOICE CALL
DCS1800 CSD PL0	175	
<b>GPRS (class 10) 1TX</b>		
GSM900 PL5	225	GPRS Sending data mode
DCS1800 PL0	160	
<b>GPRS (class 10) 2TX</b>		
GSM900 PL5	420	GPRS Sending data mode
DCS1800 PL0	290	

For the GE864-GPS, the additional current consumption of the GPS section in different operating modes is:

GE864-GPS (GPS ON) -Additional current -		
Mode	Average (mA)	Mode description
<b>HIBERNATE</b>	<0.045	only RTC and RAM supplied
<b>Acquisition mode</b>	45	
<b>Tracking mode</b>	37	



The GSM system is made in a way that the RF transmission is not continuous, else it is packed into bursts at a base frequency of about 216 Hz, the relative current peaks can be as high as about 2A. Therefore the power supply has to be designed in order to withstand with these current peaks without big voltage drops; this means that both the electrical design and the board layout must be designed for this current flow.

If the layout of the PCB is not well designed a strong noise floor is generated on the ground and the supply; this will reflect on all the audio paths producing an audible annoying noise at 216 Hz; if the voltage drop during the peak current absorption is too much, then the device may even shutdown as a consequence of the supply voltage drop.



**TIP:**

The electrical design for the Power supply should be made ensuring it will be capable of a peak current output of at least 2A.

## 6.3. General Design Rules

The principal guidelines for the Power Supply Design embrace three different design steps:

- the electrical design
- the thermal design
- the PCB layout.

### 6.3.1. Electrical Design Guidelines

The electrical design of the power supply depends strongly from the power source where this power is drained. We will distinguish them into three categories:

- +5V input (typically PC internal regulator output)
- +12V input (typically automotive)
- Battery

#### 6.3.1.1. +5V input Source Power Supply Design Guidelines

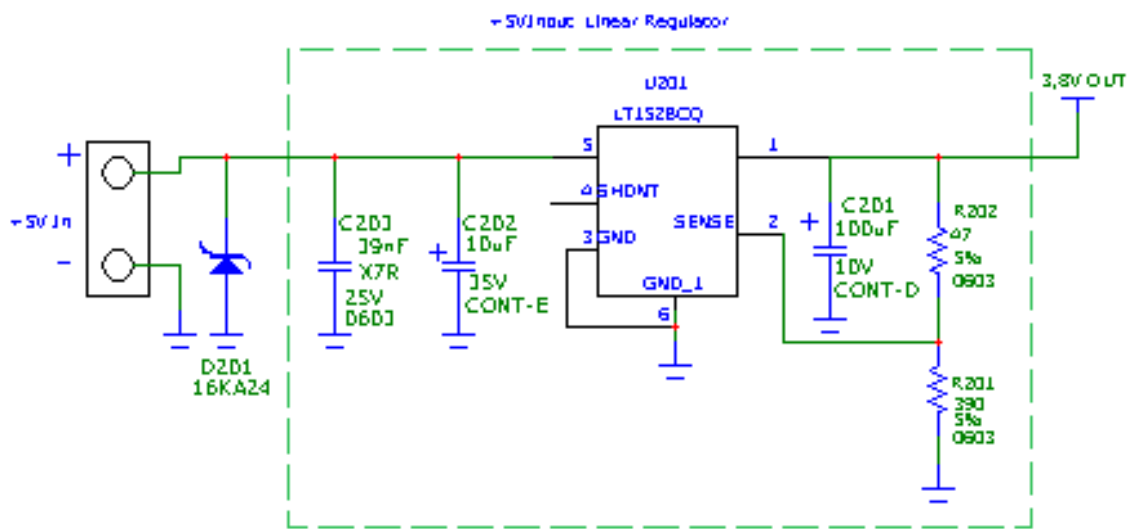
- The desired output for the power supply is 3.8V, hence there is no big difference between the input source and the desired output. A linear regulator can be used. A switching power supply will not be suited because of the low drop out requirements.
- When using a linear regulator, a proper heat sink shall be provided in order to dissipate the power generated.
- A Bypass low ESR capacitor of adequate capacity must be provided in order to cut the current absorption peaks close to the module, a 100µF tantalum capacitor is usually suited.
- Make sure the low ESR capacitor on the power supply output (usually a tantalum one) is rated at least 10V.





- A protection diode can be inserted close to the power input, in order to save the module from power polarity inversion.

An example of linear regulator with 5V input is:



### 6.3.1.2. +12V input Source Power Supply Design Guidelines

- The desired output for the power supply is 3.8V, hence, due to the big difference between the input source and the desired output, a linear regulator is not suited and shall not be used. A switching power supply will be preferable because of its better efficiency especially with the 2A peak current load represented by the module.
- When using a switching regulator, a 500kHz (or more) switching frequency regulator is preferable, because of its smaller inductor size and its faster transient response. This allows the regulator to respond quickly to the current peaks absorption.
- In any case the frequency and switching design selection is related to the application to be developed, due to the fact that the switching frequency could also generate EMC interferences.
- As far as car PB battery, the input voltage can rise up to 15.8V. This must be kept in mind when choosing components: all components in the power supply must withstand this voltage.

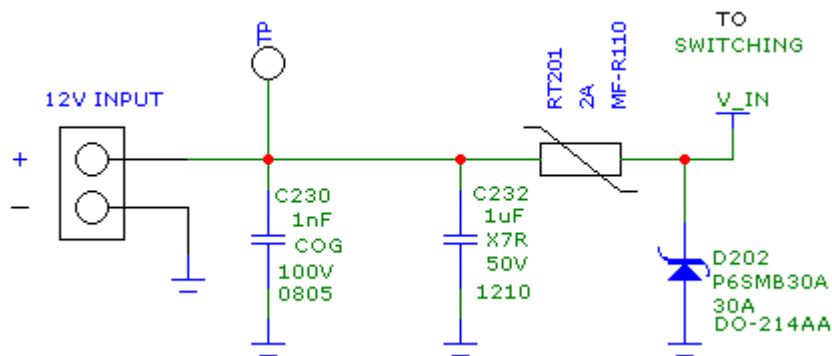


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- A Bypass low ESR capacitor of adequate capacity must be provided, in order to cut the current absorption peaks. A 100 $\mu$ F tantalum capacitor is typically used.
- Make sure the low ESR capacitor on the power supply output (usually a tantalum one) is rated at least 10V.
- As far as car applications, a spike protection diode must be inserted close to the power input, in order to clean the supply from spikes.
- A protection diode can be inserted close to the power input, in order to save the module from power polarity inversion. This can be the same diode used for spike protection.

An example of switching regulator with 12V input is in the schematic below (split in 2 parts):











### 6.3.4. Parameters for ATEX Applications

In order to integrate the Telit's modules into an ATEX application, the appropriate reference standard IEC EN xx and integrations shall be followed.

Below are listed parameters and useful information to integrate the module in your application:

#### GE864-QUAD V2

- Total capacity: 27.45 uF
- Total inductance: 55.20 nH
- No voltage upper than supply voltage is present in the module.
- No step-up converters are present in the module.

#### GC864-QUAD V2

- Total capacity: 27.45 uF
- Total inductance: 55.20 nH
- No voltage upper than supply voltage is present in the module.
- No step-up converters are present in the module.

#### GE864-GPS

- Total capacity: 33.26 uF
- Total inductance: 233 nH
- No voltage upper than supply voltage is present in the module.
- No step-up converters are present in the module.





### 7.1.2. GE864-QUAD V2/GPS GSM Antenna – PCB line Guidelines

When using the Telit GE864-QUAD V2 or GE864-GPS module, since there's no antenna connector on the module, the antenna must be connected to the GE864-QUAD V2 or GE864-GPS through the PCB with the antenna pad.

In the case that the antenna is not directly developed on the same PCB, hence directly connected at the antenna pad of the GE864-QUAD V2 or GE864-GPS, then a PCB line is needed in order to connect with it or with its connector.

This line of transmission shall fulfill the following requirements:

ANTENNA LINE ON PCB REQUIREMENTS	
<b>Impedance</b>	50 ohm
<b>Max Attenuation</b>	0,3 dB
<b>No coupling with other signals allowed</b>	
<b>Cold End (Ground Plane) of antenna shall be equipotential to the GE864-QUAD V2 ground pins</b>	

This transmission line should be designed according to the following guidelines:

- Ensure that the antenna line impedance is 50 ohm;
- Keep the antenna line on the PCB as short as possible, since the antenna line loss shall be less than 0,3 dB;
- Antenna line must have uniform characteristics, constant cross section, avoid meanders and abrupt curves;
- Keep, if possible, one layer of the PCB used only for the Ground plane;
- Surround (on the sides, over and under) the antenna line on PCB with Ground, avoid having other signal tracks facing directly the antenna line track;
- The ground around the antenna line on PCB has to be strictly connected to the Ground Plane by placing vias once per 2mm at least;
- Place EM noisy devices as far as possible from GE864-QUAD V2 antenna line;
- Keep the antenna line far away from the GE864-QUAD V2 or GE864-GPS power supply lines;
- If you have EM noisy devices around the PCB hosting the GE864-QUAD V2 or GE864-GPS, such as fast switching ICs, take care of the shielding of the antenna line by burying it inside the layers of PCB and surround it with Ground planes, or shield it with a metal frame cover.
- If you don't have EM noisy devices around the PCB of GE864-QUAD V2 or GE864-GPS, by using a strip-line on the superficial copper layer for the antenna line, the line attenuation will be lower than a buried one;

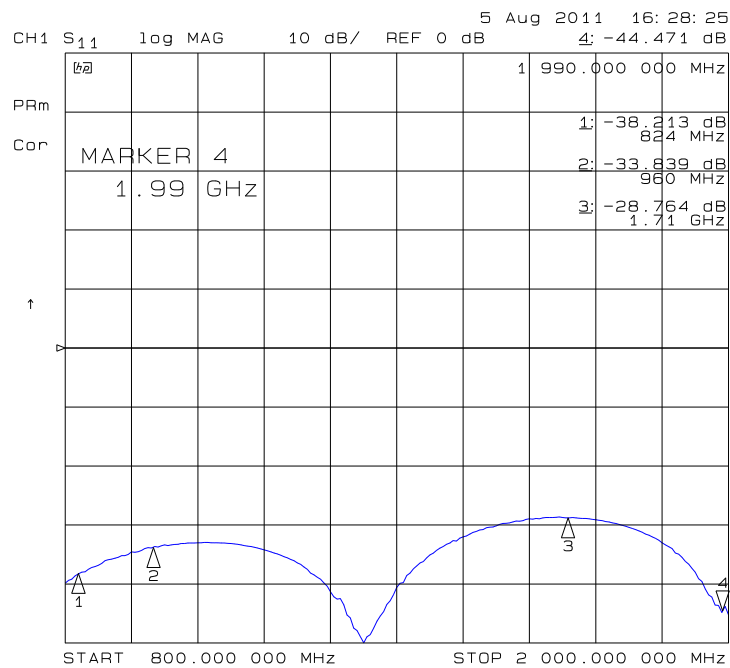




## 7.2.2. Transmission line measurements

HP8753E VNA (Full-2-port calibration) has been used in this measurement session. A calibrated coaxial cable has been soldered at the pad corresponding to GE864-QUAD V2 or GE864-GPS RF output; a SMA connector has been soldered to the board in order to characterize the losses of the transmission line including the connector itself. During Return Loss / impedance measurements, the transmission line has been terminated to 50  $\Omega$  load.

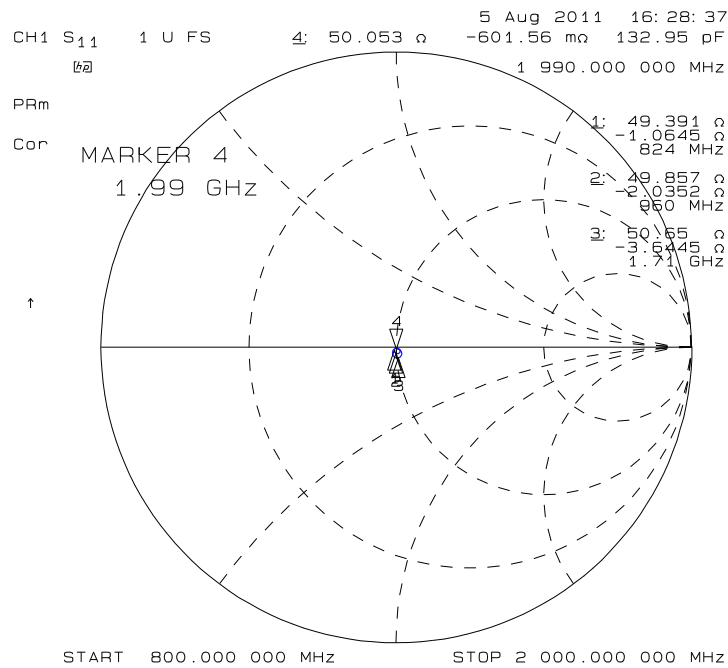
Return Loss plot of line under test is shown below:





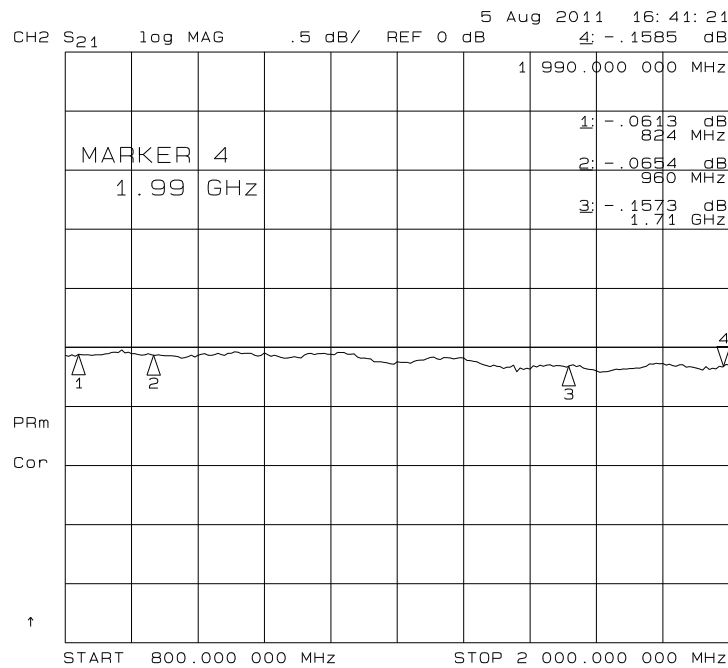
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Line input impedance (in Smith Chart format, once the line has been terminated to 50 Ω load) is shown in the following figure:



Insertion Loss  
SMA connector is shown below:

of G-CPW line plus











## 8.1. Reset Signal

Signal	Function	I/O	Ball/Pin Number
RESET	Reset	I	A2 on GE864-QUAD V2/GPS 54 on GC864-QUAD V2

RESET is used to reset the GE/GC864-QUAD V2 and GE864-GPS modules. Whenever this signal is pulled low, the GE/GC864-QUAD V2 and GE864-GPS are reset. When the device is reset it stops any operation. After the release of the reset GE/GC864-QUAD V2 and GE864-GPS are unconditionally shut down, without doing any detach operation from the network where it is registered. This behavior is not a proper shut down because any GSM device is requested to issue a detach request on turn off. For this reason the Reset signal must not be used to normally shutting down the device, but only as an emergency exit in the rare case the device remains stuck waiting for some network response.

The RESET is internally controlled on start-up to achieve always a proper power-on reset sequence, so there is no need to control this pin on start-up. It may only be used to reset a device already on that is not responding to any command.




---

### NOTE:

Do not use this signal to power off GC/GE864-QUAD V2 and GE864-GPS . Use the ON/OFF signal to perform this function or the AT#SHDN command.

---

### Reset Signal Operating Levels:

Signal	Min	Max
RESET Input high	2.0V*	2.2V
RESET Input low	0V	0.2V

\* this signal is internally pulled up so the pin can be left floating if not used.

If unused, this signal may be left unconnected. If used, then it **must always be connected with an open collector transistor**, to permit to the internal circuitry the power on reset and under voltage lockout functions.



## 9. Serial Ports

The serial port on the Telit GE864/GC864-QUAD V2 and GE864-GPS is the core of the interface between the module and OEM hardware.

2 serial ports are available on the GE864-QUAD/GC864-QUAD V2 modules:

- MODEM SERIAL PORT (Main, ASC0)
- MODEM SERIAL PORT 2 (Auxiliary, ASC1)

While another serial port is available on the GE864-QUAD V2/GPS module:

- GPS SERIAL PORT (NMEA)

### 9.1. MODEM SERIAL PORT

Several configurations can be designed for the serial port on the OEM hardware, but the most common are:

- RS232 PC com port
- microcontroller UART @ 2.8V – 3V (Universal Asynchronous Receive Transmit)
- microcontroller UART@ 5V or other voltages different from 2.8V

Depending from the type of serial port on the OEM hardware a level translator circuit may be needed to make the system work. The only configuration that does not need a level translation is the 2.8V UART.

The serial port on the GE/GC864-QUAD V2 and GE864-GPS a +2.8V UART with all the 7 RS232 signals. It differs from the PC-RS232 in the signal polarity (RS232 is reversed) and levels. The levels for the GE864-QUAD V2 UART are the CMOS levels:

#### Absolute Maximum Ratings –Not Functional

Parameter	Min	Max
Input level on any digital pad when on	-0.3V	+3.1V
Input voltage on analog pads when on	-0.3V	+3.0 V





**Operating Range – Interface levels (2.8V CMOS)**

Level			GPS signals	
	Min	Max	Min	Max
Input high level	2.1V	3.1V	1.82V	2.8V
Input low level	0V	0.5V	0V	0.98V
Output high level	2.2V	3.0V	2.4V	
Output low level	0V	0.35V		0.4V

The table below shows the signals of the GE/GC864-QUAD V2 AND GE864-GPSserial port:

RS232 Pin Number	Signal	GE864-QUAD V2 Pad Number	GC864-QUAD V2 Pad Number	Name	Usage
1	DCD – dcd_uart	D9	32	Data Carrier Detect	Output from the GE864-QUAD V2 that indicates the carrier presence
2	RXD – tx_uart	H8	26	Transmit line *see Note	Output transmit line of GE864-QUAD V2 UART
3	TXD – rx_uart	E7	25	Receive line *see Note	Input receive of the GE864-QUAD V2 UART
4	DTR – dtr_uart	B7	29	Data Terminal Ready	Input to the GE864-QUAD V2 that controls the DTE READY condition
5	GND	A1, F1, H1 L1, H2, L2, J3, K3 ....	5,6,7	Ground	ground
6	DSR – dsr_uart	E11	27	Data Set Ready	Output from the GE864-QUAD V2 that indicates the module is ready
7	RTS – rts_uart	F7	31	Request to Send	Input to the GE864-QUAD V2 that controls the Hardware flow control
8	CTS – cts_uart	F6	28	Clear to Send	Output from the GE864-QUAD V2 that controls the Hardware flow control
9	RI – ri_uart	B6	30	Ring Indicator	Output from the GE864-QUAD V2 that indicates the incoming call condition



**NOTE:**

According to V.24, RX/TX signal names are referred to the application side, therefore on the GE/GC864-QUAD V2 AND GE864-GPSside these signal are on the opposite direction: TXD on the application side will be connected to the receive line (here named TXD/RX\_uart ) of the GE/GC864-QUAD V2 AND GE864-GPSserial port and viceversa for RX



**TIP:**

For a minimum implementation, only the TXD and RXD lines can be connected, the other lines can be left open provided a software flow control is implemented.







**NOTE:**

In order to avoid a back powering effect it is recommended to avoid having any HIGH logic level signal applied to the digital pins of the module when is powered OFF or during an ON/OFF transition.

## 9.2. GE864-GPS Secondary Ports

### 9.2.1. Modem Serial Port 2 (GPS Control)

This port is the only communication interface with the GPS part. It is available on the following pins:

BALL	NAME	DESCRIPTION	TYPE
D11	TX_AUX	TX Data for GPS control	CMOS 2.8V
F10	RX_AUX	RX Data for GPS control	CMOS 2.8V

Please note that in order for GPS to be controlled by the GSM section, the GPS UART and some GPS control signals **have to be connected externally** to the GSM section according to the following table (see also chapter 12):

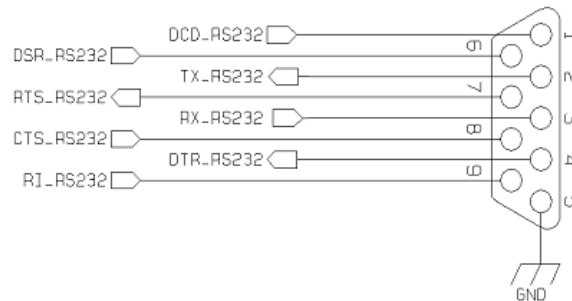
BALL	NAME		NAME	BALL
D11	TX_AUX	↔	GPS_RX	E10
F10	RX_AUX	↔	GPS_TX	F8
B3	GPIO4		GPS_ON_OFF	J4





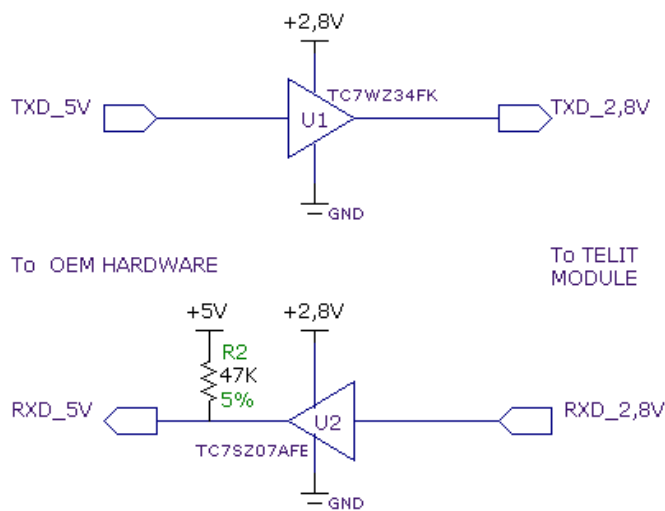


The RS232 serial port lines are usually connected to a DB9 connector with the following layout:



## 9.4. 5V UART Level Translation

If the OEM application uses a microcontroller with a serial port (UART) that works at a voltage different from 2.8 – 3V, then a circuitry has to be provided to adapt the different levels of the two set of signals. As for the RS232 translation there are a multitude of single chip translators. For example a possible translator circuit for a 5V TRANSMITTER/RECEIVER can be:



### TIP:

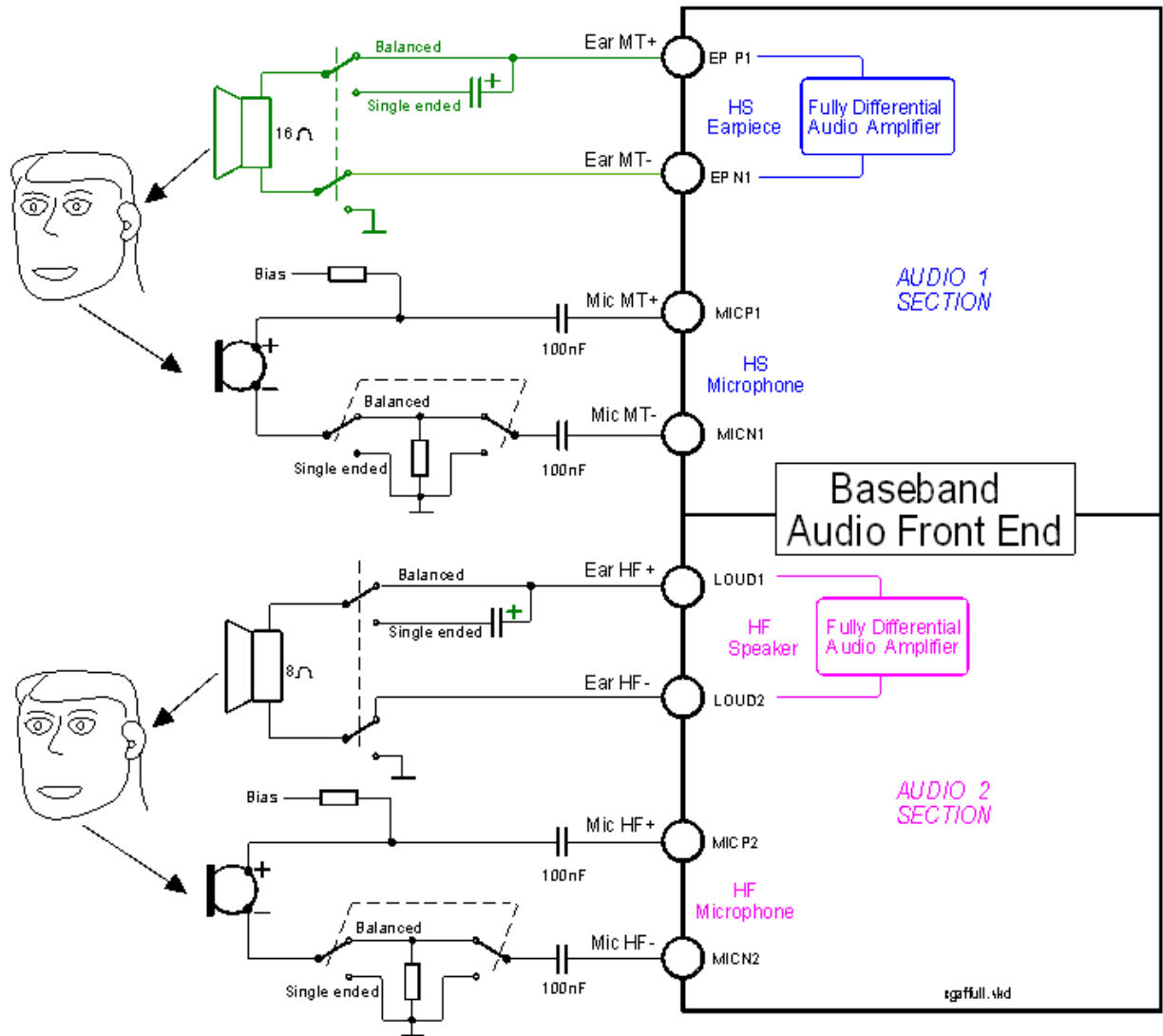
Note that the TC7SZ07AE has open drain output; therefore the resistor R2 is mandatory.











GE864-QUAD V2 Audio Front End Block Diagram



## 10.2. Electrical Characteristics



**TIP:**

Being the microphone circuitry the more noise sensitive, its design and layout must be done with particular care. Both microphone paths are balanced and the OEM circuitry must be balanced designed to reduce the common mode noise typically generated on the ground plane. However the customer can use the unbalanced circuitry for its particular application.

### 10.2.1. Input Lines Characteristics

“MIC_MT” and “MIC_HF” differential microphone paths	
Line Coupling	AC*
Line Type	Balanced
Differential input voltage	$\leq 1,03V_{pp}$ @ $Mic G=0dB$
Gain steps	7
Gain increment	6dB per step
Coupling capacitor	$\geq 100nF$
Differential input resistance	50K $\Omega$
Input capacitance	$\leq 10pF$



**(\*) WARNING :**

AC means that the signals from the microphone have to be connected to input lines of the module through capacitors which value has to be  $\geq 100nF$ . Not respecting this constraint, the input stages will be damaged.



**WARNING:**

when particular OEM application needs a *Single Ended Input* configuration, it is forbidden connecting the unused input directly to Ground, but only through a 100nF capacitor. Don't forget that the useful input signal will be halved in *Single Ended Input* configuration.





“EAR_MT” Output Lines	
line coupling	AC single-ended DC differential
0dBFS normalized gain	3,7 V <sub>pp</sub> differential
output load resistance	≥ 16 Ω @ -12dBFS
internal output resistance	4Ω (typical)
signal bandwidth	150 - 4000 Hz @ -3 dB
maximal full scale differential output voltage	3,7 V <sub>pp</sub> (typical) R <sub>load</sub> =open circuit
differential output voltage	925mV <sub>pp</sub> / R <sub>load</sub> =16Ω @ -12dBFS
volume increment	2 dB per step
volume steps	10

“EAR_HF” Output Lines	
line coupling	AC single-ended DC differential
output load resistance	≥ 8 Ω
signal bandwidth	150 - 4000 Hz @ -3 dB
maximal output power @ battery voltage ≥ 3,6V	0.35 W <sub>rms</sub> /8 Ω
volume increment	2 dB per step
volume steps	10









## 11.2. Using a GPIO Pad as INPUT

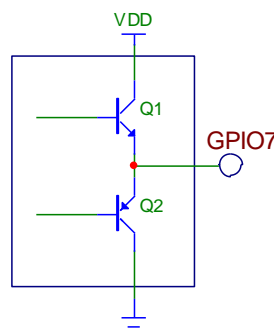
The GPIO pads, when used as inputs, can be connected to a digital output of another device and report its status, provided this device has interface levels compatible with the 2.8V CMOS levels of the GPIO.

If the digital output of the device to be connected with the GPIO input pad has interface levels different from the 2.8V CMOS, then it can be buffered with an open collector transistor with a 47K pull up to 2.8V, this pull up must be switched off when the module is in off condition.

## 11.3. Using a GPIO Pad as OUTPUT

The GPIO pads, when used as outputs, can drive 2.8V CMOS digital devices or compatible hardware. When set as outputs, the pads have a push-pull output and therefore the pull-up resistor may be omitted.

The illustration below shows the base circuit of a push-pull stage:



## 11.4. Using the RF Transmission Control GPIO4

The GPIO4 pin, when configured as RF Transmission Control Input, permits to disable the Transmitter when the GPIO is set to Low by the application.

In the design is necessary to add a resistor 47K pull up to 2.8V, this pull up must be switched off when the module is in off condition.

## 11.5. Using the RFTXMON Output GPIO5

The GPIO5 pin, when configured as RFTXMON Output, is controlled by the GE/GC 864 QUAD V2 module and will rise when the transmitter is active and fall after the transmitter activity is completed.



There are 2 different modes for this function:

1) Active during all the calls:

For example, if a call is started, the line will be HIGH during all the conversation and it will be again LOW after hanged up.

The line rises up 300ms before first TX burst and will became again LOW from 500ms to 1s after last TX burst.

2) Active during all the TX activity:

The GPIO is following the TX bursts

Please refer to the AT User interface manual for additional information on how to enable this function.

## 11.6. Using the Alarm Output GPIO6

The GPIO6 pad, when configured as Alarm Output, is controlled by the module and will rise when the alarm starts and fall after the issue of a dedicated AT command.

This output can be used to power up the module controlling micro controller or application at the alarm time, giving you the possibility to program a timely system wake-up to achieve some periodic actions and completely turn off either the application and the module during sleep periods, dramatically reducing the sleep consumption to few  $\mu$ A.

In battery-powered devices this feature will greatly improve the autonomy of the device.



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### NOTE:

During RESET the line is set to HIGH logic level.

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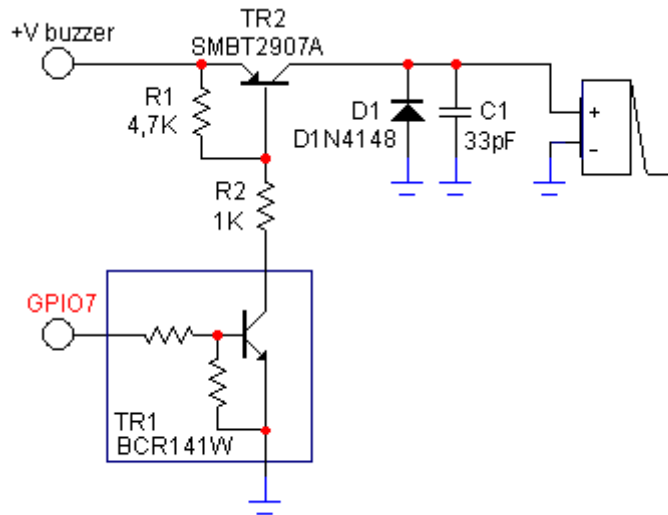
## 11.7. Using the Buzzer Output GPIO7

The GPIO7 pad, when configured as Buzzer Output, is controlled by the GE/GC 864 QUAD V2 module and will drive with appropriate square waves a Buzzer driver.

This permits to your application to easily implement Buzzer feature with ringing tones or melody played at the call incoming, tone playing on SMS incoming or simply playing a tone or melody when needed by your application.



A sample interface scheme is included below to give you an idea of how to interface a Buzzer to the GPIO7:



**NOTE:**

To correctly drive a buzzer a driver must be provided, its characteristics depend on the Buzzer and for them refer to your buzzer vendor.

## 11.8. Using the Temperature Monitor Function

### 11.8.1. Short Description

The Temperature Monitor is a function of the module that permits to control its internal temperature and if properly set (see the #TEMPMON command on AT Interface guide) it raise to High Logic level a GPIO when the maximum temperature is reached.



## 11.8.2. Allowed GPIO

The AT#TEMPMON set command could be used with one of the following GPIO:

Ball GE864	Pin GC864	Signal	I/O	Function	Type	Input / output current	Default state	ON_OF F state	During Reset state	Note
C1	70	TGPIO_01	I/O	GPIO01 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0	0	
E6	74	TGPIO_02 / JDR	I/O	GPIO02 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0	0	Alternate function (JDR)
C2	66	TGPIO_03	I/O	GPIO03 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0	0	
B3	59	TGPIO_04 / TXCNTRL	I/O	GPIO04 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0	0	Alternate function (RF Transmission Control)
K8	78	TGPIO_05 / RFTXMON	I/O	GPIO05 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0	0	Alternate function (RFTXMON)
B5	68	TGPIO_06 / ALARM	I/O	GPIO06 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0	0	Alternate function (ALARM)
L9	73	TGPIO_07 / BUZZER	I/O	GPIO07 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0	0	Alternate function (BUZZER)
K11	67	TGPIO_08	I/O	GPIO08 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0	0	
C9	76	TGPIO_09	I/O	GPIO09 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0	0	
H3	63	TGPIO_10 / DVI_TX	I/O	GPIO10 Configurable GPIO	CMOS 2.8V	1uA / 1mA	INPUT	0	0	Alternate function (DVI_TX)



### NOTE:

If the set command is enable the alternate function is not usable.







## 11.10. RTC Bypass Out

The VRTC pin brings out the Real Time Clock supply, which is separate from the rest of the digital part, allowing having only RTC going on when all the other parts of the device are off. To this power output a backup capacitor can be added in order to increase the RTC autonomy during power off of the battery. NO Devices must be powered from this pin.

## 11.11. External SIM Holder Implementation

Please refer to the related User Guide (SIM Holder Design Guides, 80000NT10001a).

## 11.12. VAUX Power Output (only for GE864-GPS)

A regulated power supply output is provided in order to supply small devices from the module.

This output is always active when the module is powered by VBATT.

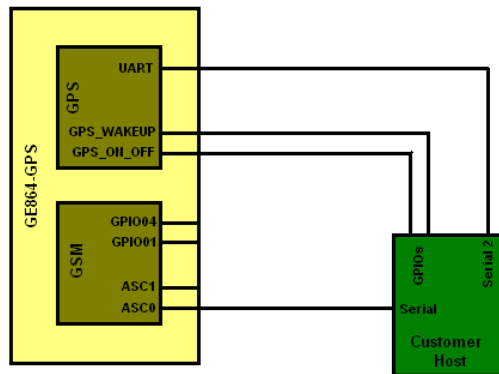
The operating range characteristics of the supply are:

### Operating Range – VAUX1 power supply

	Min	Typical	Max
Output voltage	2.74V	2.80V	2.86V
Output current			100mA
Output bypass capacitor (inside the module)			1 $\mu$ F







## 12.2. PPS GPS Output

### 12.2.1. Description

The Time Mark output GPS\_PPS provides a one pulse-per-second signal to the user specific application. The GPS\_PPS pulse is available at any time as soon as a fix is done. This signal is a positive logic, CMOS level output pulse that transitions from logic 'low' condition to logic 'high' at a 1 Hz rate.

### 12.2.2. Pulse Characteristics

The signal is available on BGA Ball C8 on GE864-GPS and on pin 24 of PL101 on EVK2 Adapter board.

Type: Output CMOS 1.8V

Duration: Typically 1us




---

#### NOTE:

The signal is available only when the receiver provides a valid Navigation solution.

---





### 13.1.2. Enabling DAC

The AT command below is available to use the DAC function:

**AT#DAC[=<enable>[,<value>]]**

<value> – scale factor of the integrated output voltage (0–1023, with 10 bit precision), and it must be present if <enable>=1.

Refer to SW User Guide or AT Commands Reference Guide for the full description of this function.

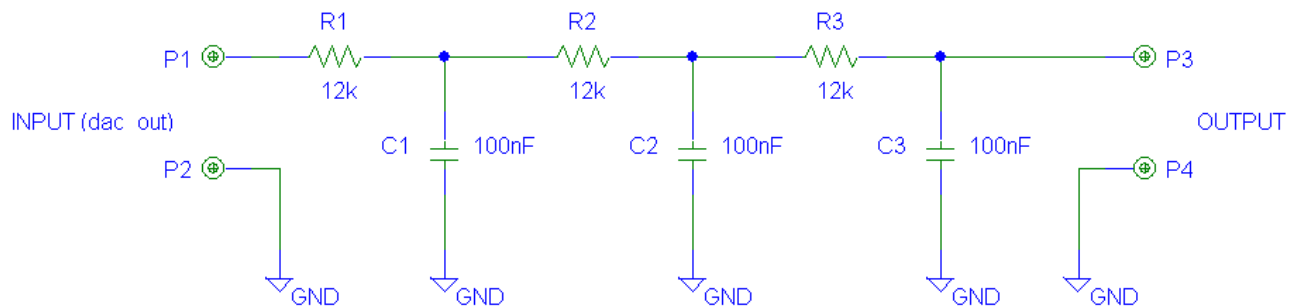
Refer to SW User Guide or AT Commands Reference Guide for the full description of this function.



**NOTE:**

The DAC frequency is selected internally. D/A converter must not be used during POWERSAVING.

### 13.1.3. Low Pass Filter Example





## 13.2. ADC Converter

### 13.2.1. Description

Ball GE864	Pin GC864	Signal	I/O	Function
<b>ADC Converters</b>				
J11	37	ADC_IN1	AI	Analog/Digital converter input
H11	38	ADC_IN2	AI	Analog/Digital converter input
N/A*	39	ADC_IN3	AI	Analog/Digital converter input

The GC864-QUAD V2 module provides three Analog to Digital Converters, while the GE864-QUAD V2 and GE864-GPS provide two Analog to Digital Converters.

The on board A/Ds are 11-bit converter. They are able to read a voltage level in the range of 0÷2 volts applied on the ADC pin input, store and convert it into 11 bit word.

	Min	Max	Units
Input Voltage range	0	2	Volt
AD conversion	-	11	bits
Resolution	-	< 1	mV

### 13.2.2. Using ADC Converter

The AT command below is available to use the ADC function:

**AT#ADC=1,2**

The read value is expressed in mV.

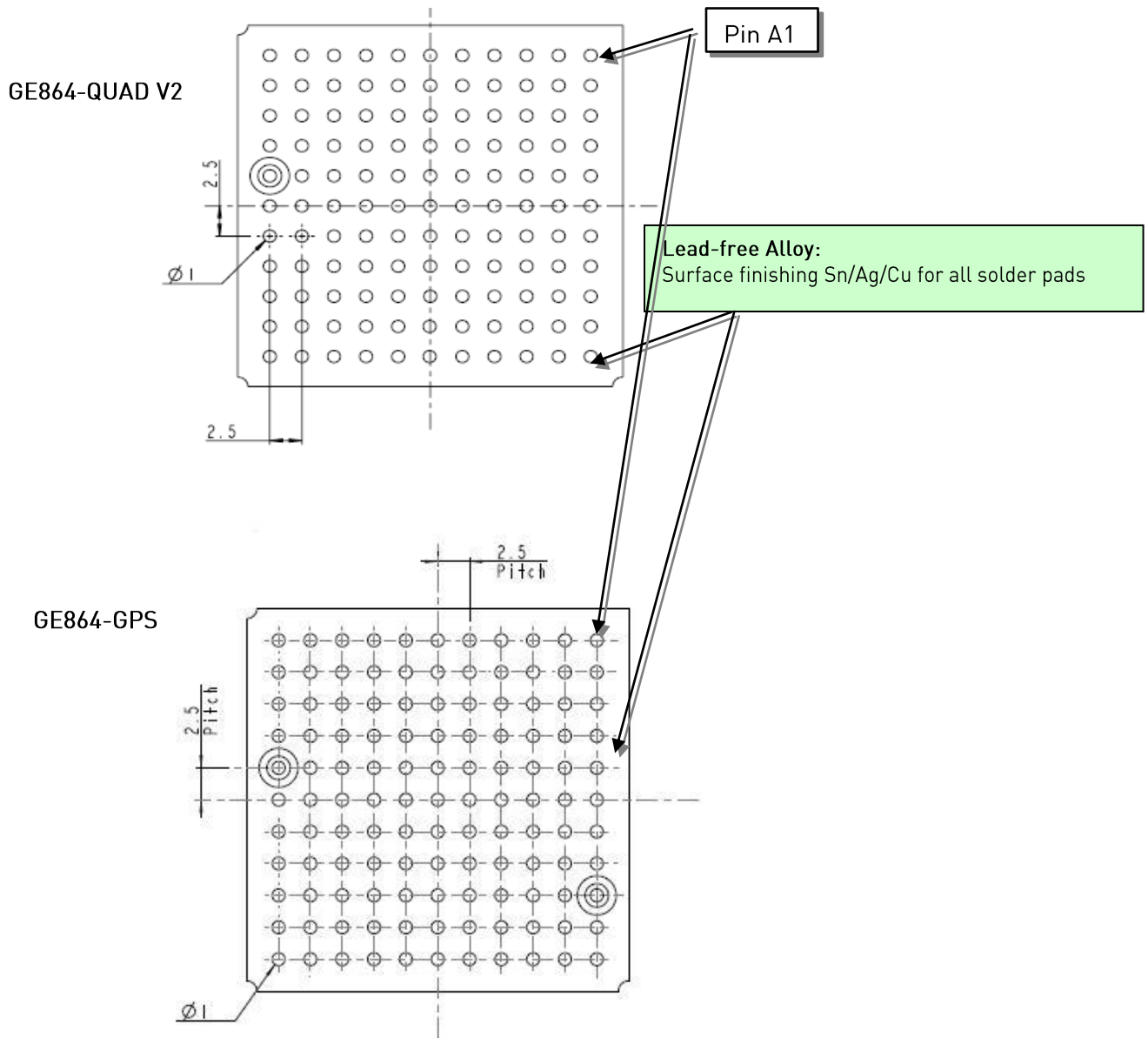
Refer to SW User Guide or AT Commands Reference Guide for the full description of this function.



## 14. Assembling the GE/GC864-QUAD V2 AND GE864-GPS on the Board

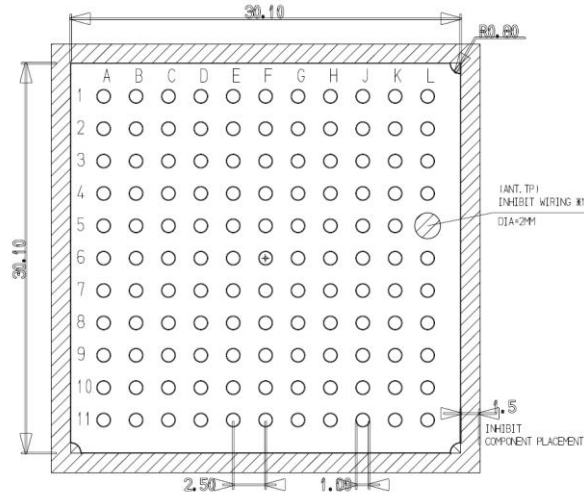
### 14.1. Assembling the GE864-QUAD V2 and GE864-GPS

The Telit GE864-QUAD V2 have been designed in order to be compliant with the standard lead-free SMT process.

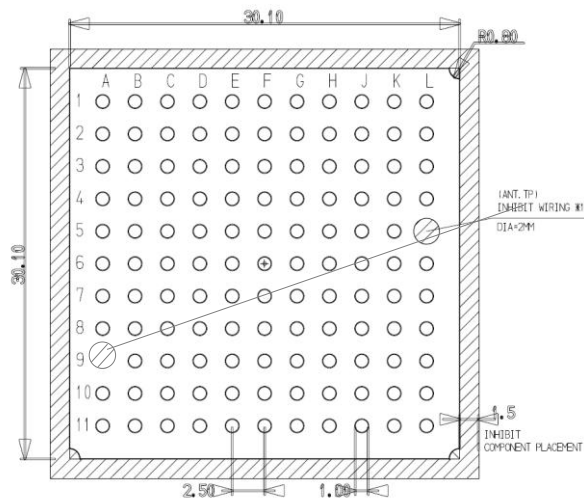


### 14.1.1. Recommended foot print for the application

GE864-QUAD V2



GE864-GPS



**NOTE:**

In order to easily rework the GE864-QUAD V2 module is suggested to consider on the application a 1.5mm inhibit area around the module.

It is also suggested, as common rule for a SMT component, to avoid having a mechanical part of the application in direct contact with the module.

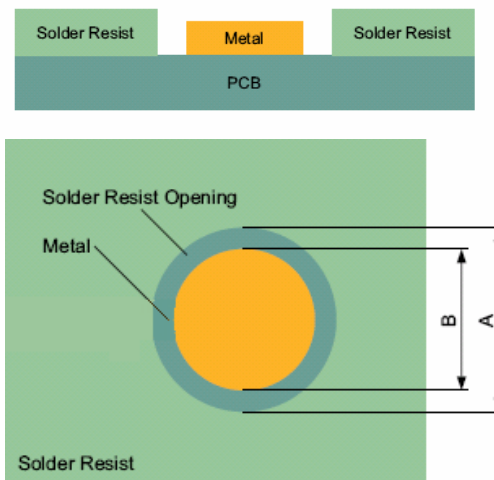


### 14.1.2. Stencil

Stencil apertures layout can be the same of the recommended footprint (1:1), we suggest a thickness of stencil foil >120µm.

### 14.1.3. PCB pad design

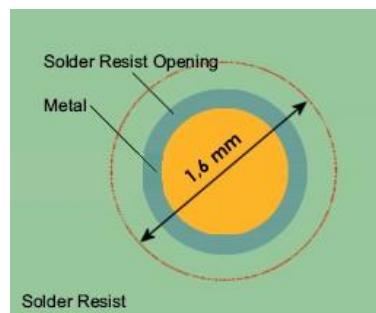
Non solder mask defined” (NSMD) type is recommended for the solder pads on the PCB.



Recommendations for PCB pad dimensions

Ball pitch [mm]	2,5
Solder resist opening diameter A [mm]	1,150
Metal pad diameter B [mm]	1 ± 0.05

It is recommended no microvia without solder resist cover under the module and no microvia around the pads (see following figure).



Holes in pad are allowed only for blind holes and not for through holes.



Recommendations for PCB pad surfaces:

Finish	Layer thickness [ $\mu\text{m}$ ]	Properties
Electro-less Ni / Immersion Au	3 – 7 / 0.05 – 0.15	good solder ability protection, high shear force values

The PCB must be able to resist the higher temperatures which are occurring at the lead-free process. This issue should be discussed with the PCB-supplier. Generally, the wettability of tin-lead solder paste on the described surface plating is better compared to lead-free solder paste.

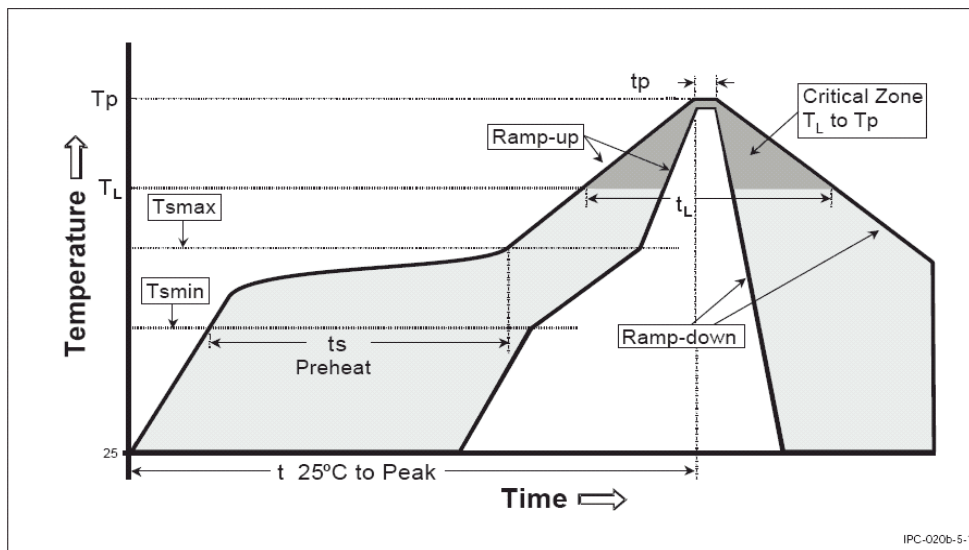
#### 14.1.4. Solder paste

	Lead free
Solder paste	Sn/Ag/Cu

It is recommended to use only “no clean” solder paste in order to avoid the cleaning of the modules after assembly.

#### 14.1.5. GE864-QUAD V2/GPS Solder reflow

The following is the recommended solder reflow profile





Profile Feature	Pb-Free Assembly
Average ramp-up rate ( $T_L$ to $T_P$ )	3°C/second max
Preheat	
– Temperature Min ( $T_{smin}$ )	150°C
– Temperature Max ( $T_{smax}$ )	200°C
– Time (min to max) (ts)	60-180 seconds
$T_{smax}$ to $T_L$	
– Ramp-up Rate	3°C/second max
Time maintained above:	
– Temperature ( $T_L$ )	217°C
– Time ( $t_L$ )	60-150 seconds
Peak Temperature ( $T_P$ )	245 +0/-5°C
Time within 5°C of actual Peak Temperature ( $t_P$ )	10-30 seconds
Ramp-down Rate	6°C/second max.
Time 25°C to Peak Temperature	8 minutes max.



**NOTE:**

All temperatures refer to topside of the package, measured on the package body surface



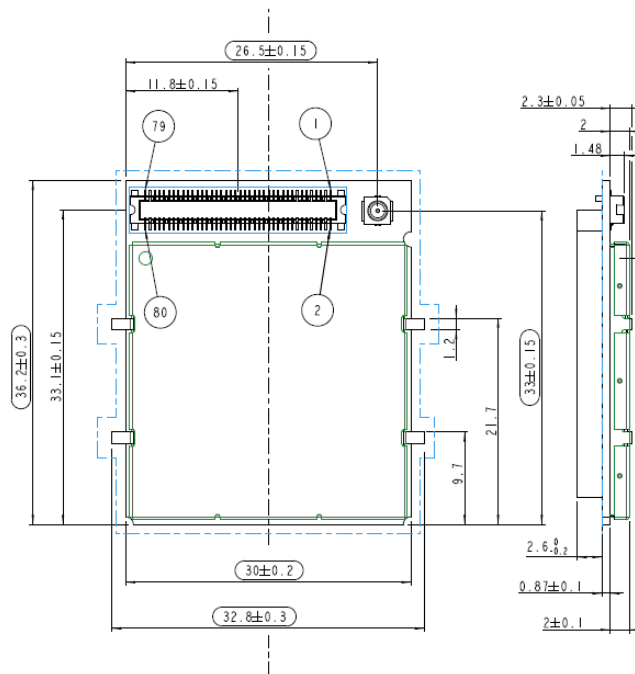
**WARNING:**

The GE864 module withstands one reflow process only.



## 14.2. Assembling the GC864-QUAD V2

The position of the Molex board to board connector and the pin 1 are shown in the following picture.



### NOTE:

The metal tabs present on GC864-QUAD V2 must be connected to GND.

This module could not be processed with a reflow.



### 14.3. Debug of the GE/GC864-QUAD V2 AND GE864-GPS in Production

To test and debug the mounting of GC/GE864-QUAD V2 and GE864-GPS, we strongly recommend to foreseen test pads on the host PCB, in order to check the connection between the GE/GC864-QUAD V2 and GE864-GPS itself and the application and to test the performance of the module connecting it with an external computer. Depending by the customer application, these pads include, but are not limited to the following signals:

Ball GE864	Pin GC864	Signal	Function
J1, J2, K1, K2	1,2,3,4	VBATT	Main power supply
A1, A11, D6, F1, F11, H1, H2, J3, K3, K4, K5, K6, L1, L2, L3, L6, L11	5,6,7, 46	GND	Ground
E7	25	C103/TXD	Serial data input (TXD) from DTE
H8	26	C104/RXD	Serial data output (RXD) to DTE
L8	49	PRWMON	Power ON Monitor
J5	53	ON/OFF*	Input command for switching power ON or OFF (toggle command).
A2	54	RESET*	Reset input
F10	23	RX_AUX	Auxiliary UART (RX Data from DTE)
D11	24	TX_AUX	Auxiliary UART (TX Data to DTE)
H4	47	SERVICE	Service pin shall be used to upgrade the module from ASC1 (RX_TRACE, TX_TRACE). The pin shall be tied low to enable the feature only in case of a SW Update activity. It is required, for debug purpose, to be connected to a test pad on the final application.
J4 <sup>3</sup>	N/A	GPS_ON_OFF <sup>3</sup>	GPS Power Control
E10 <sup>3</sup>	N/A	GPS_RX <sup>3</sup>	GPS Serial data input
F8 <sup>3</sup>	N/A	GPS_TX <sup>3</sup>	GPS Serial data output
G2 <sup>3</sup>	N/A	GPS_WAKEUP <sup>3</sup>	Wake up output <sup>3</sup>

(3) Available only on GE864-GPS (in case of GE864-QUAD V2 it has to be considered RESERVED)





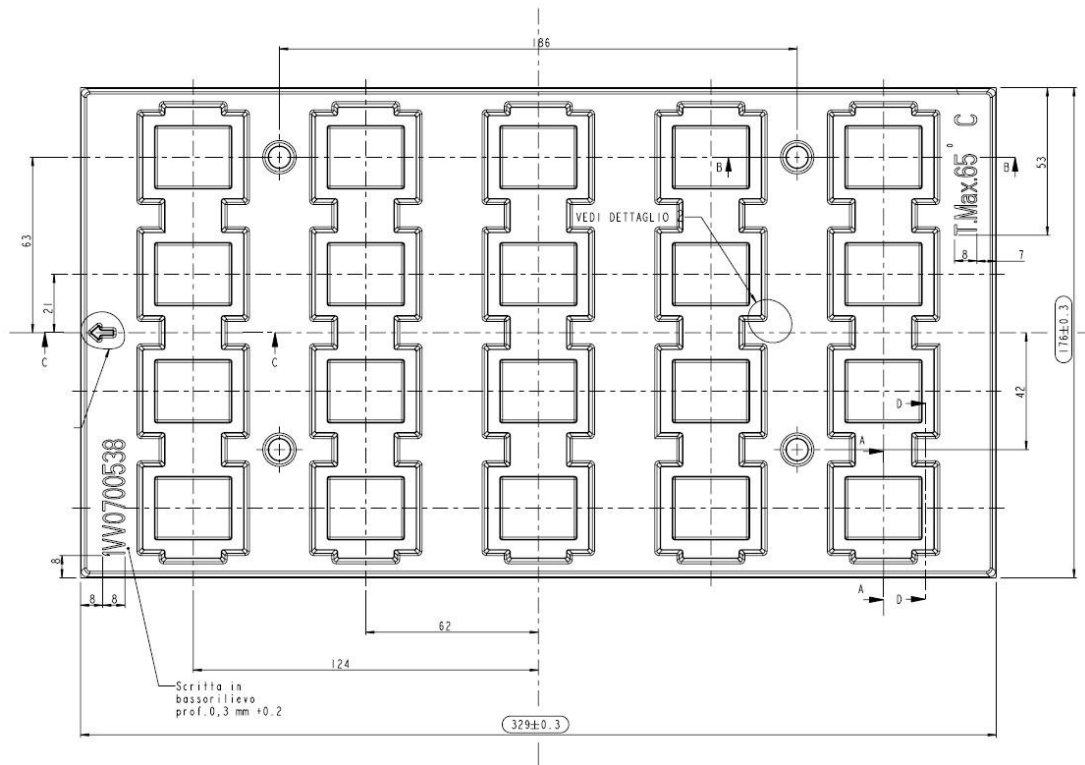






## 15.2. GE/GC864-QUAD V2 AND GE864-GPS Packaging

The Telit GC864-QUAD V2 are packaged on trays of 20 pieces each.



The size of the tray is: 329 x 176mm.



### WARNING:

These trays can withstand at the maximum temperature of 65° C.







The text of the Directive 99/05 regarding telecommunication equipments is available, while the applicable Directives (Low Voltage and EMC) are available at:

<http://ec.europa.eu/enterprise/sectors/electrical>

**FCC Regulatory Requirements**

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions:

- (1) this device may not cause harmful interference, and
- (2) this device must accept any interference received, including interference that may cause undesired operation.

RF Exposure:

The antenna(s) used for this transmitter must be installed to provide a separation distance of at least 20 cm from all the persons and must not be co-located or operating in conjunction with any other antenna or transmitter.

The system antenna(s) used for this module must not exceed 1,4dBi (850MHz) and 3.0dBi (1900MHz) for mobile and fixed or mobile operating configurations.

Users and installers must be provided with antenna installation instructions and transmitter operating conditions for satisfying RF exposure compliance.

A label containing the following information must be affixed to the outside of a host product which incorporates this module:

Label	Module type
Contains FCC ID: <b>RI7GE86Q2</b>	For GE864-QUAD V2
Contains FCC ID: <b>RI7GC864Q2</b>	For CE864-QUAD V2
Contains FCC ID: <b>RI7GE864G2</b>	For GE864-GPS

**IC Regulatory Requirements**

This device complies with Industry Canada license-exempt RSS standard(s).

Operation is subject to the following two conditions:

- (1) this device may not cause interference, and
- (2) this device must accept any interference, including interference that may cause undesired operation of the device.

*Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes :*

- (1) l'appareil ne doit pas produire de brouillage, et*









