

Improve Accuracy of the TMP006 With a Simple Transient Correction Algorithm

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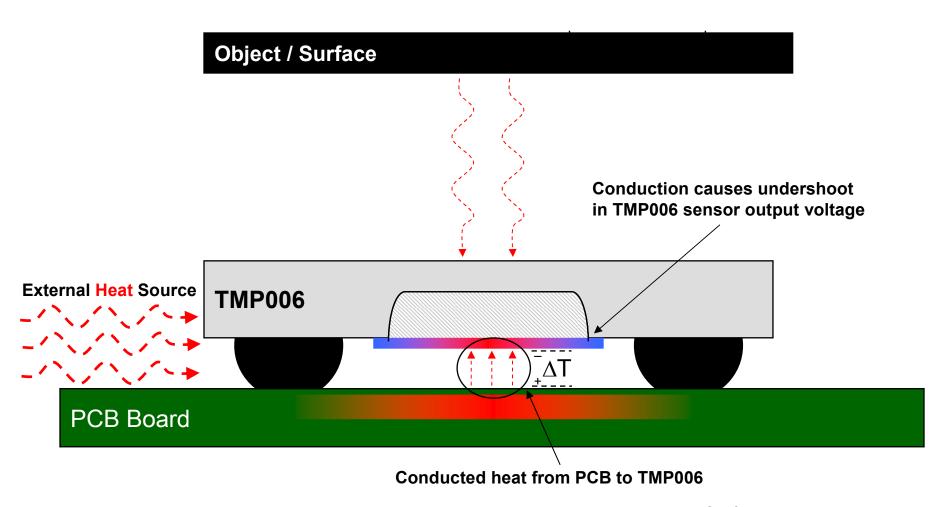


Background

- Accuracy of the TMP006 is highly dependent on stable local temperature
- The IR (infrared) thermopile sensor in the TMP006 has a thermal RC response
 - Responds to thermal transients more slowly than a
 PCB board, causing temperature gradients to develop
 - Temperature gradients cause heat transfer by conduction between TMP006 and PCB, resulting in offsets in sensor voltage and unwanted error

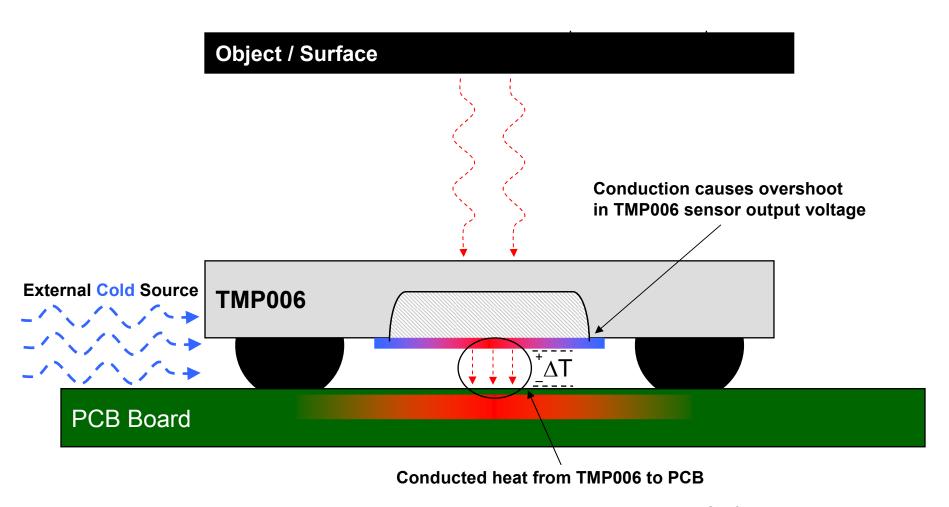


Response to <u>Hot</u> Transient Event



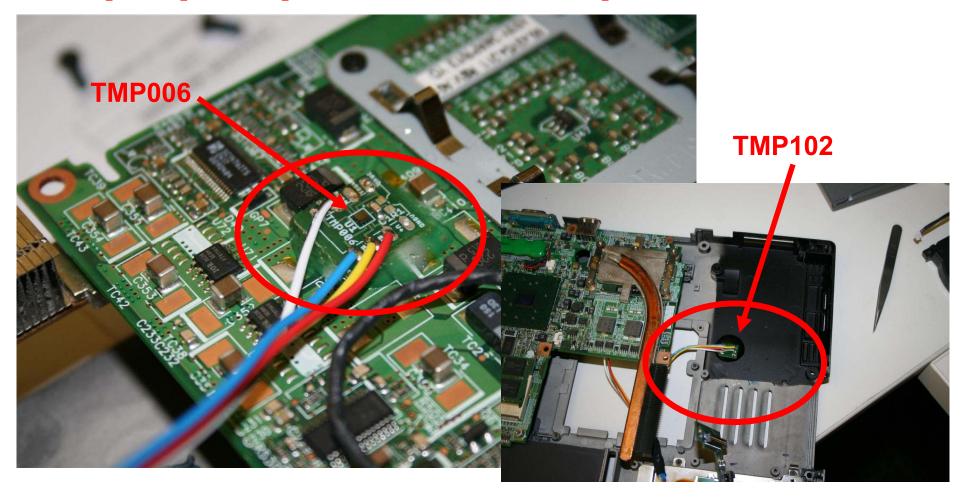


Response to **Cold** Transient Event





Laptop Experiment Setup

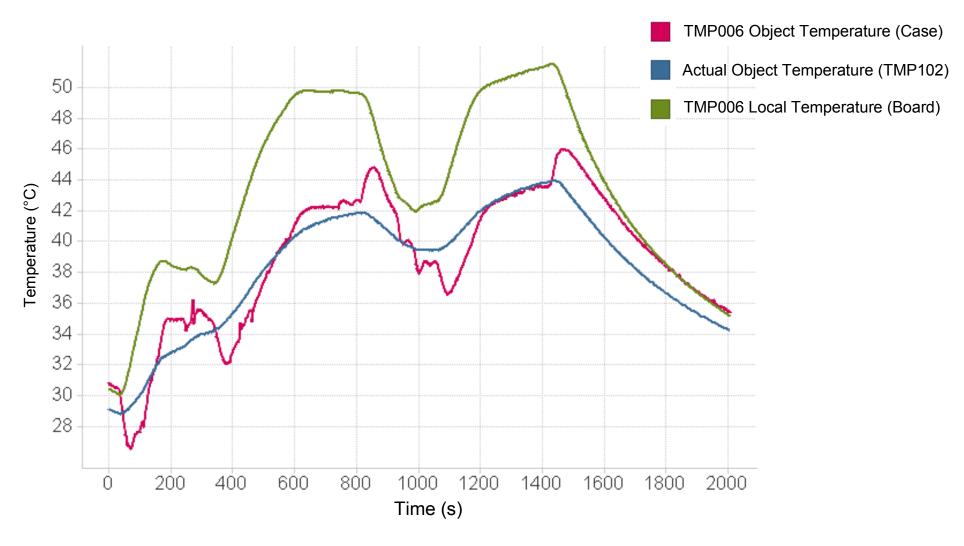


 Laptop was powered for 30 min and several applications were run to stress the processor

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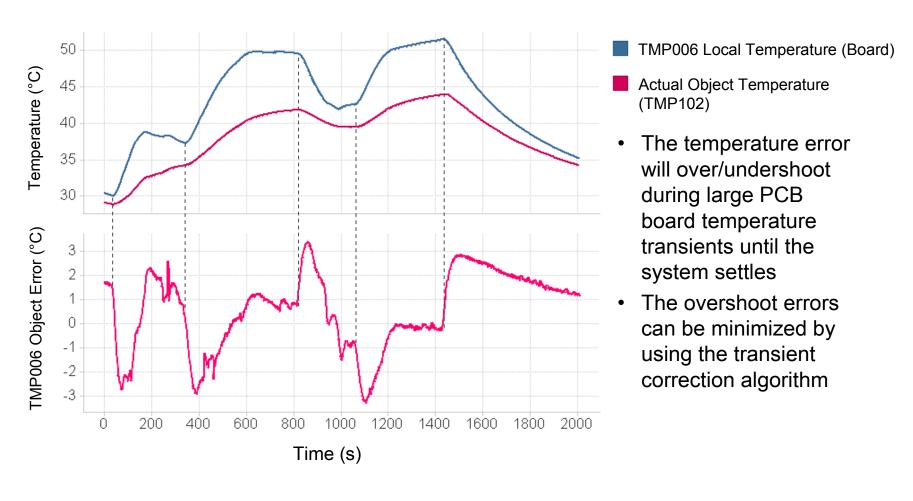


Laptop Experiment Results





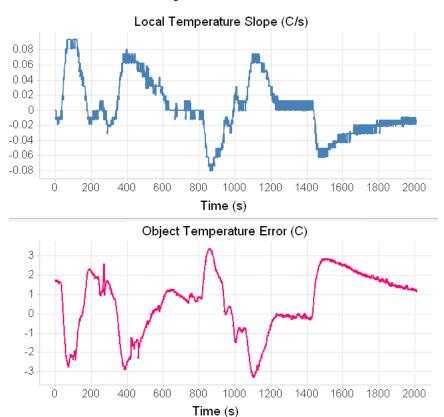
Laptop Experiment Results





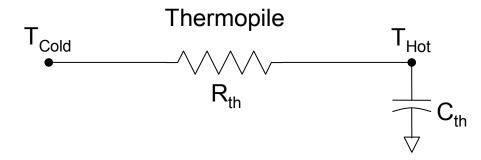
Object Temperature Error Due to Transients

• The TMP006 transient error is proportional to the slope of the local temperature: $V_{obj} Error = \alpha (dT_{die}/dt)$





Theory: Sensor Time Constant Effect on Transients



- R_{th} Thermal resistance of thermopile
- C_{th} Thermal capacitance of thermopile

•
$$\frac{\partial T_{Hot}}{\partial t} = \frac{\partial T_{Cold}}{\partial t}$$
 (Delayed by R_{th}C_{th})

•
$$T_{Hot} - T_{Cold} = -\frac{\partial T_{Cold}}{\partial t} \times R_{th} C_{th}$$
 The difference in temperature created by a drift in the die

temperature



Theory: Sensor Time Constant Effect on Transients

$$T_{Hot} - T_{Die} = -\frac{\partial T_{Cold}}{\partial t} \times R_{th} C_{th}$$

$$V_{\text{Error}} = \text{Seebeck} \times (T_{\text{Hot}} - T_{\text{Die}})$$

The difference in temperature results in a voltage error on the thermopile

$$V_{Error} = Seebeck \times -\frac{\partial T_{Cold}}{\partial t} \times R_{th}C_{th}$$

$$V_{Error} = -\frac{\partial T_{Cold}}{\partial t} \times (Seebeck \times R_{th}C_{th})$$

$$\alpha = (\text{Seebeck} \times \text{R}_{\text{th}} \text{C}_{\text{th}}) = 2.96 \times 10^{-4} (\text{V} \times \text{sec} / \text{C})$$



The alpha mentioned before is a constant which corresponds to the multiplication of the Seebeck coefficient and slope of the die temperature (cold junction)



Calculating the Slope of Die Temperature

The slope of the best straight line fit for any set of points (x_i, y_i) can be calculated using the equation given below.

$$S_{0} = \frac{\left(n\sum_{i=1}^{n} x_{i} y_{i}\right) - \left(\sum_{i=1}^{n} x_{i}\right) \left(\sum_{i=1}^{n} y_{i}\right)}{\left(n\sum_{i=1}^{n} x_{i} x_{i}\right) - \left(\sum_{i=1}^{n} x_{i}\right) \left(\sum_{i=1}^{n} x_{i}\right)}$$

If we use four temperature points that are spaced 1 second apart; $(1, T_{diel})$ $(2, T_{die2})$ $(3, T_{die3})$ $(4, T_{die4})$ where T_{die4} is the latest measurement and T_{diel} is the first measurement, the above equation simplifies to:

$$T_{Slope} = -(0.3 \times T_{diel}) - (0.1 \times T_{die2}) + (0.1 \times T_{die3}) + (0.3 \times T_{die4})$$



Correcting Object Voltage Error

- Measure the slope of the local temperature versus time (recommend using 4 measurements)
 - For four, one second spaced readings:

•
$$T_{Slope} = -(0.3 \times T_{die1}) - (0.1 \times T_{die2}) + (0.1 \times T_{die3}) + (0.3 \times T_{die4})$$

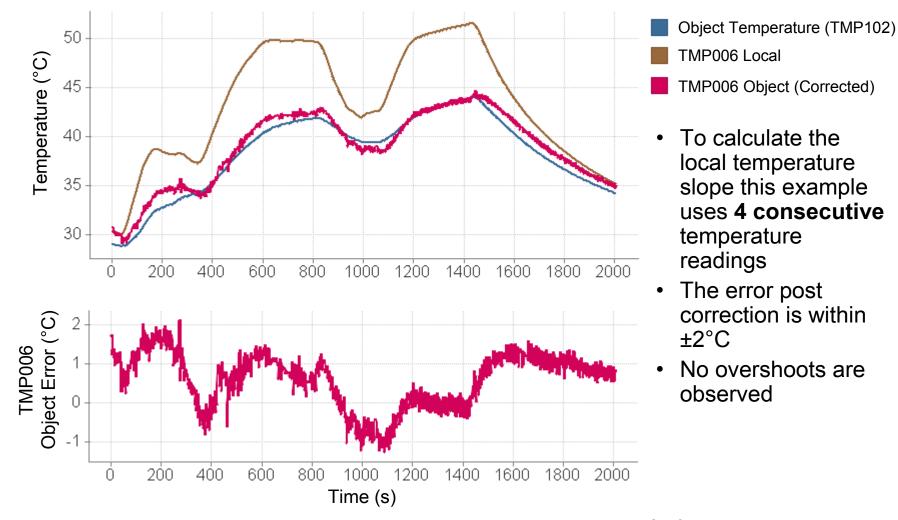
Correct the sensor object voltage using:

•
$$V_{obj\ corrected} = V_{obj} + T_{Slope} \times 2.96 \times 10^{-4}$$

• Apply $V_{obj\ corrected}$ to the standard 3D equation to correct the transients



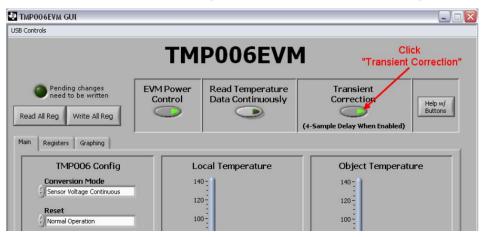
Laptop Experiment Post Transient Correction





TMP006EVM Software

- New revision (Rev. A) of <u>TMP006EVM software</u> includes transient correction functionality
- To enable, click Transient Correction at top-right of GUI
 - 4-sample delay will be observed when enabled while software calculates slope of local temperature





Questions?

- Contact information
 - Temperature Sensor area of E2E forums (preferred):
 http://e2e.ti.com/support/other_analog/temperature_sensors/default.aspx
 - E-mail: ian@ti.com

