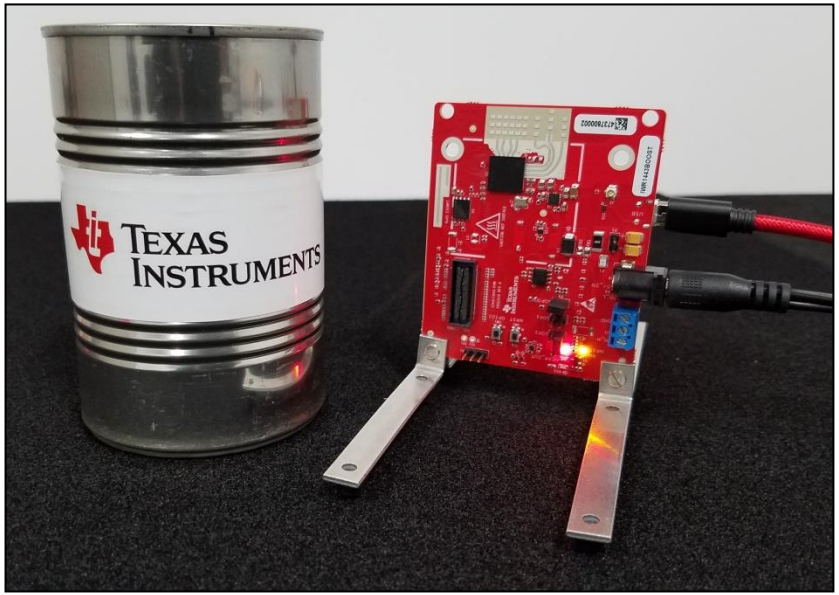
TI mmWave Training

mmWave Demo

Contents

Lab Overview

- Configurable visualization tool for processed radar data
- The following plots are available:
  - Scatter Plot
  - Range Profile
  - Noise Profile
  - Range Azimuth Heat Map
  - Range Doppler Heat Map
  - Statistics

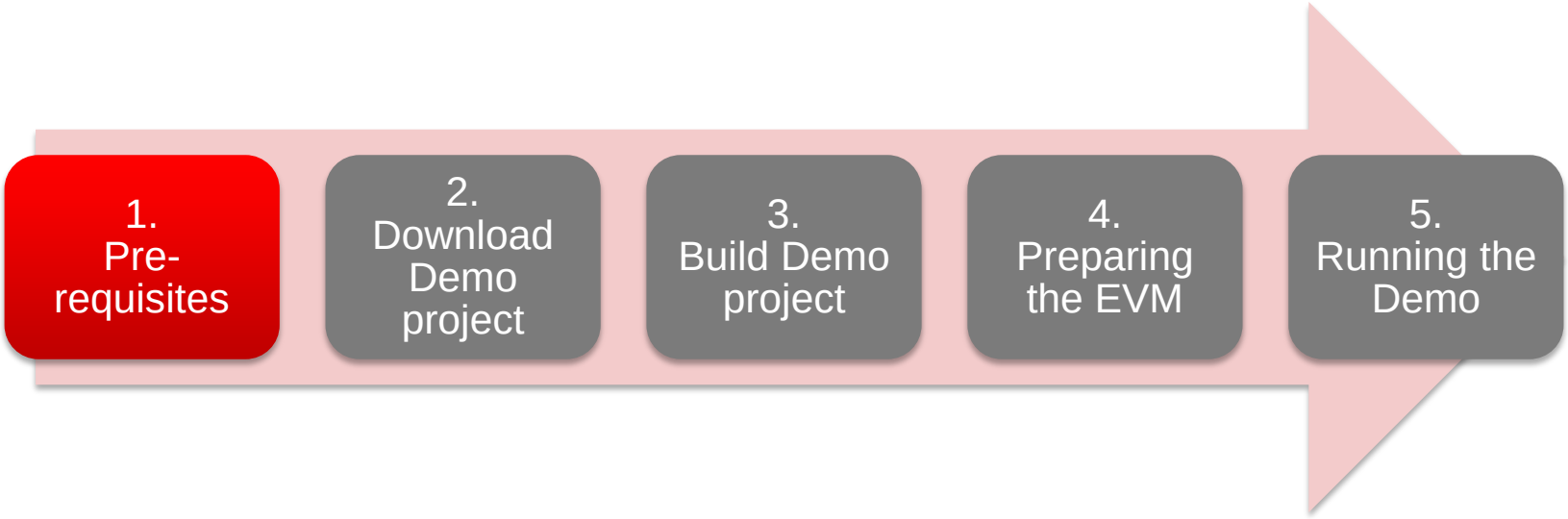


1. Requirements

- Software
  - **Pre-requisites**
    - Latest TI mmWave SDK and all related dependencies installed as mentioned in the mmWave SDK release notes.
  - Google Chrome with TI Cloud Agent Extension
    - For running the mmWave Demo Visualizer
    - Download from TI Cloud Agent or install when accessing the demo
  - mmWave SDK Demo
    - Download from TI Resource Explorer
  - UniFlash
    - For flashing firmware images onto
    - Download from TI.com/tool/uniflash
  - XDS110 Drivers
    - For EVM XDS device support
    - Included with CCS Installation, or standalone through TI XDS Emulation Software

- Hardware
  - xWR14xx EVM
  - Micro USB cable (included in the EVM package)
  - 5V/2.5A Power Supply
    - Purchase from Digikey

Steps


1. Pre-requisites
2. Download Demo project
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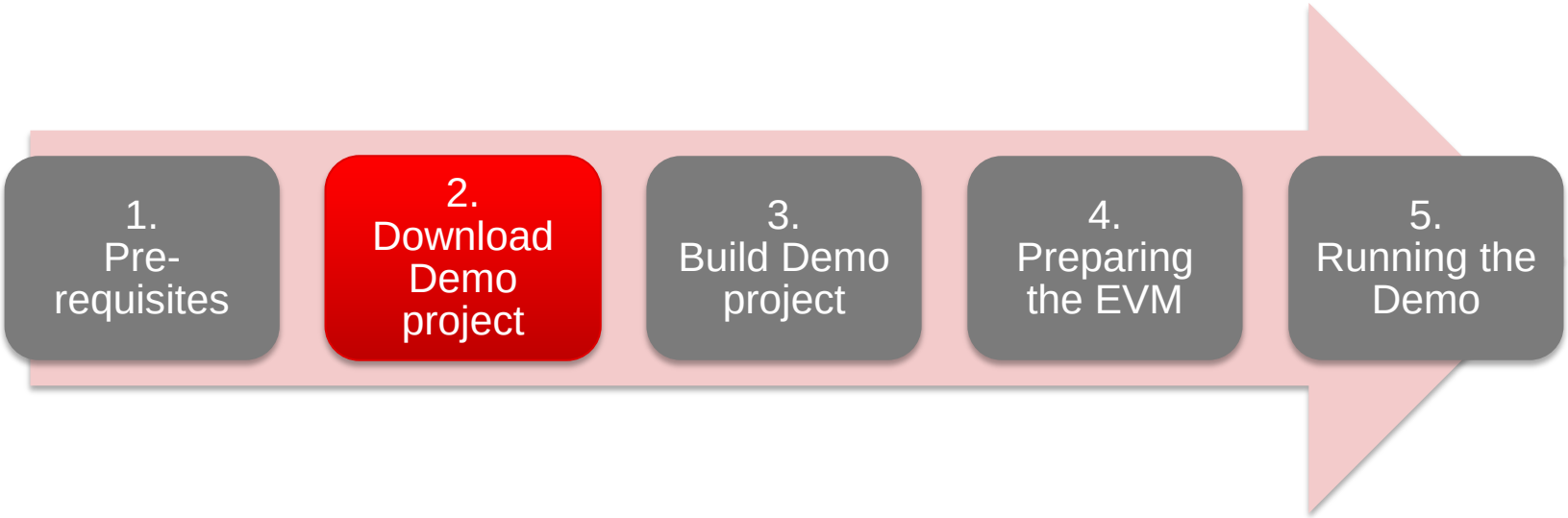
5. Running the Demo

1. Pre-requisites

- It is assumed that you have the latest TI mmWave SDK and all the related tools installed as mentioned in the mmWave SDK release notes.
  - The mmWave SDK release notes include the links for downloading the required versions of the above tools.
  - Helpful Tips
    - Please make sure that any existing PERL installations are removed from the PC before installing the version of PERL listed in the SDK release notes
    - After you've downloaded and saved **CRC.pm**, locate the saved file and remove the .txt extension if it is there. Please ensure that the file has a **.pm** extension and not a .txt extension at the end
    - XDC tools are provided as a zip file which needs to be extracted in the TI install directory (typically C:\ti)
  - Note: For this video, we used mmWave SDK 1.0.0.5 and the snapshot shown here corresponds to **mmWave SDK 1.0.0.5**
- If you have already installed the mmWave SDK and all the required tools, you can move on to the next step i.e. downloading the lab on to your machine.

Tool	Version	Download link
CCS	7.1 or later	download link Please note that CCS v7.1 or later is mandatory. CCSv6.x cannot be used
TI SYS/BIOS	6.50.1.12 or later	download link
TI ARM compiler	16.9.1.LTS or later	Included in CCS v7.1
TI CGT compiler	8.1.3 or later	Included in CCS v7.1
XDC	3.50.00.10 or later	download link Use the installer that has no mention of JRE which by default has JRE (this installer will be bigger than the one without JRE). Also it is recommended that this be installed separately even if CCS has this version installed since the CCS version is without JRE.
C64x+ DSPLIB	3.4.0.0	Please download the installer for C64x+. download link
C674x MATHLIB (little-endian, elf/coff format)	3.1.2.1	Please download the installer for C674x. download link
Perl	5.20.2 or later	download link
CRC.pm	0.21	download link This is an add-on to the Perl installation. This file needs to be copied to <PERL installation folder>\perl\lib\Digest folder.
Mono JIT compiler	3.2.8	Only for Linux builds
mmwave device support packages	1.5.3 or later	Upgrade to the latest using CCS update process
TI Emulators package	6.0.0576.0 or later	Upgrade to the latest using CCS update process

Steps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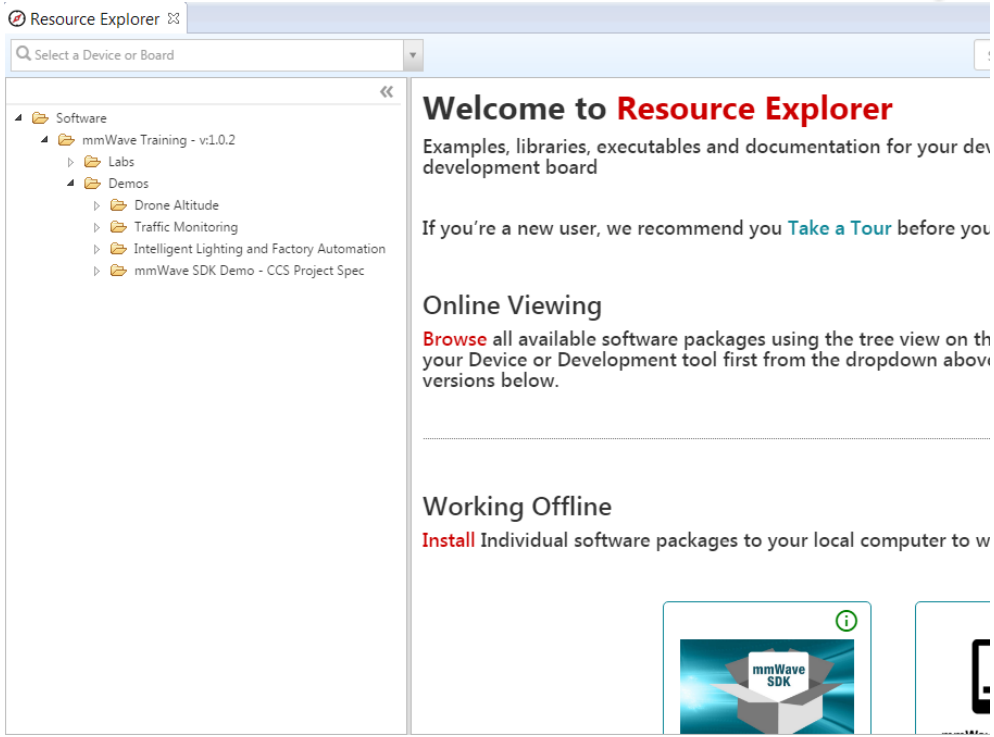
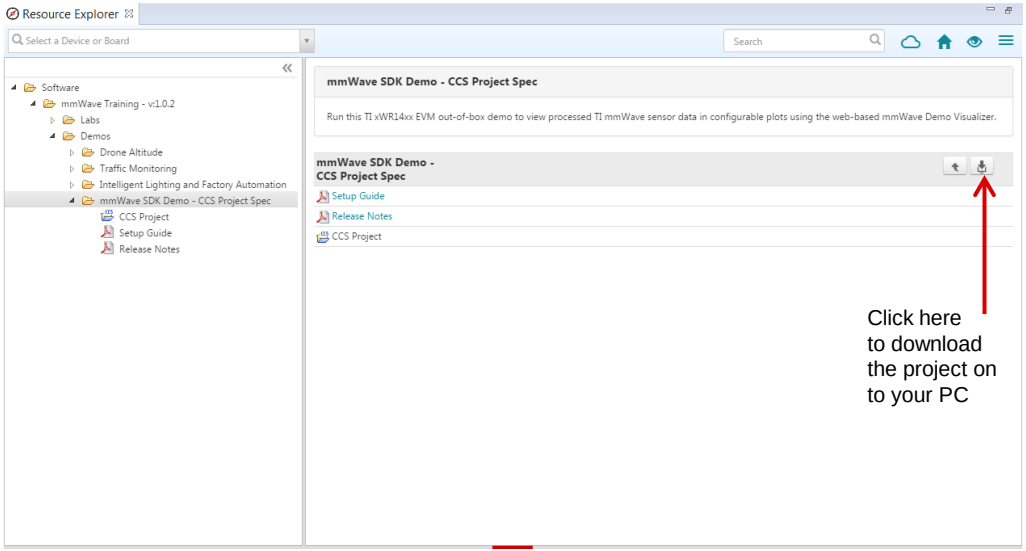
2. Download the Lab project

- The mmWave projects are available under **mmWave Training** in CCS Resource Explorer.
- To download the mmWave demo, start CCS v7.1 (or later) and select **View ► Resource Explorer** to open the Resource Explorer.
- In the Resource Explorer Window, select **Software ► mmWave Training ► Demos**.



2. Download - continued

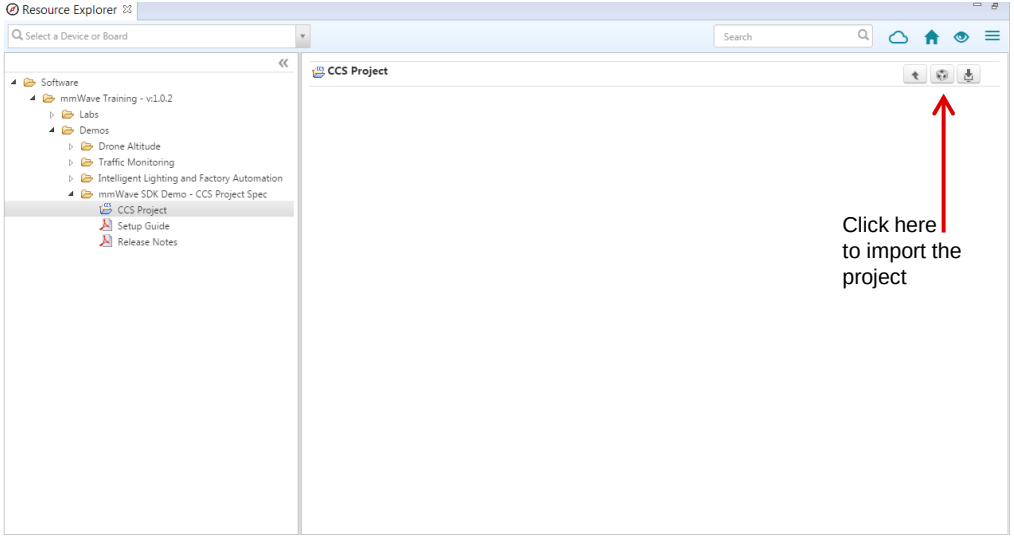
- Select the **mmWave SDK** demo in the left view.
- The right view shows the contents of the Lab which contains the CCS Project and the PC GUI.
- Click on the **Download and Install** button  in the top right corner as shown.
- Select the **Make Available Offline** option from the drop down to start downloading the Lab.



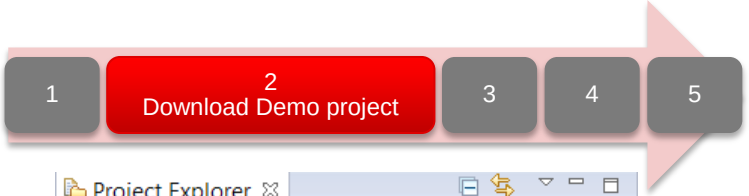
2. Download - continued

- The project will be downloaded in C:\ti\mmwave_training
- Select the CCS Project file in the left view
- Click on the **Import to IDE** button which should be visible in the right side view after a successful download.

- This copies the project in the user's workspace and imports it into the CCS project explorer.
  - It is important to note that the copy created in the workspace is the one that gets imported in CCS. The original project downloaded in mmwave_training is not touched.



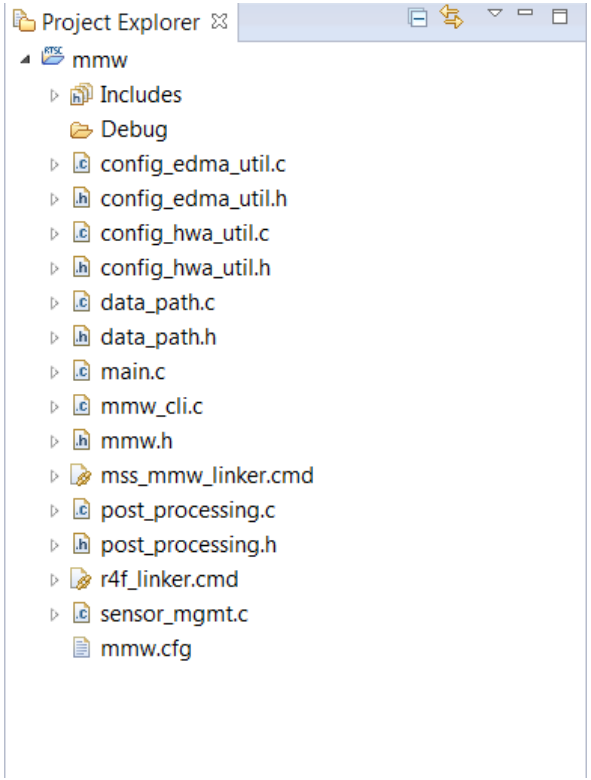
2. Download - continued



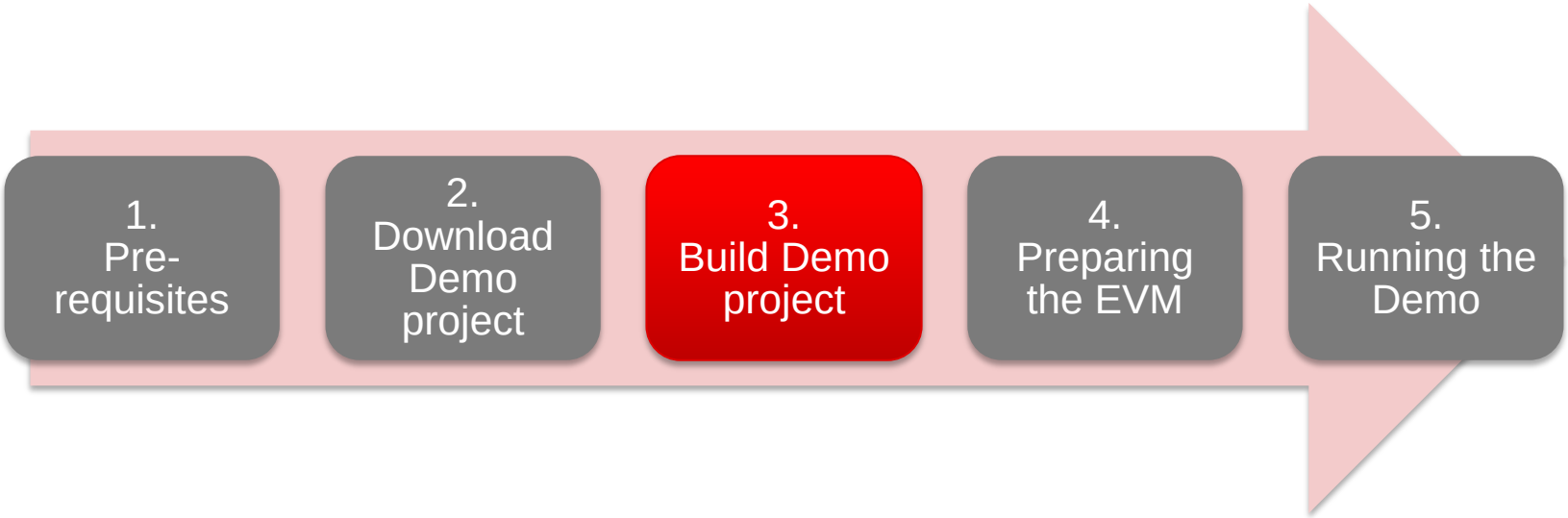
- After successfully completing the **Import to IDE** operation, the project should be visible in CCS Project Explorer as shown here.

- At this point, we have successfully downloaded the mmWave demo and imported it in CCS.

- We are ready to move on to the next step i.e. Building the project.



Steps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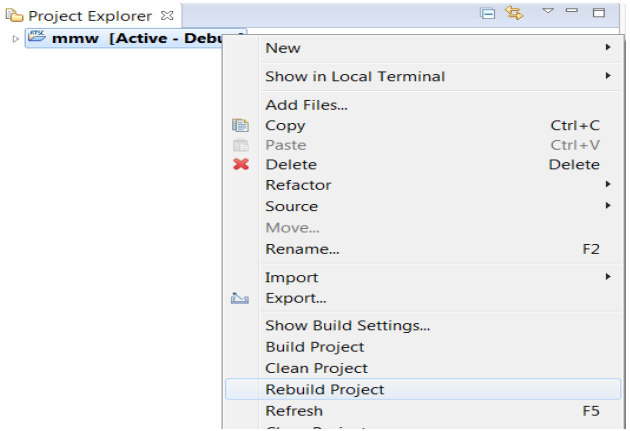
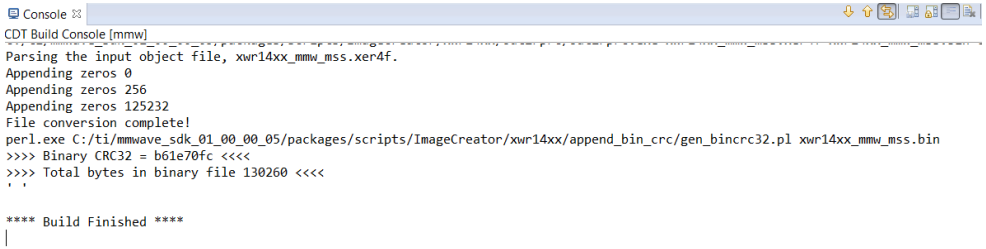
3. Build the Lab

1 | 2 | 3 Build Demo project | 4 | 5

- With the mmw project selected in Project Explorer, open the **Project** menu and select **Rebuild Project**.
  - Selecting **Rebuild** instead of **Build** ensures that the project is always re-compiled. This is especially important in case the previous build failed with errors.

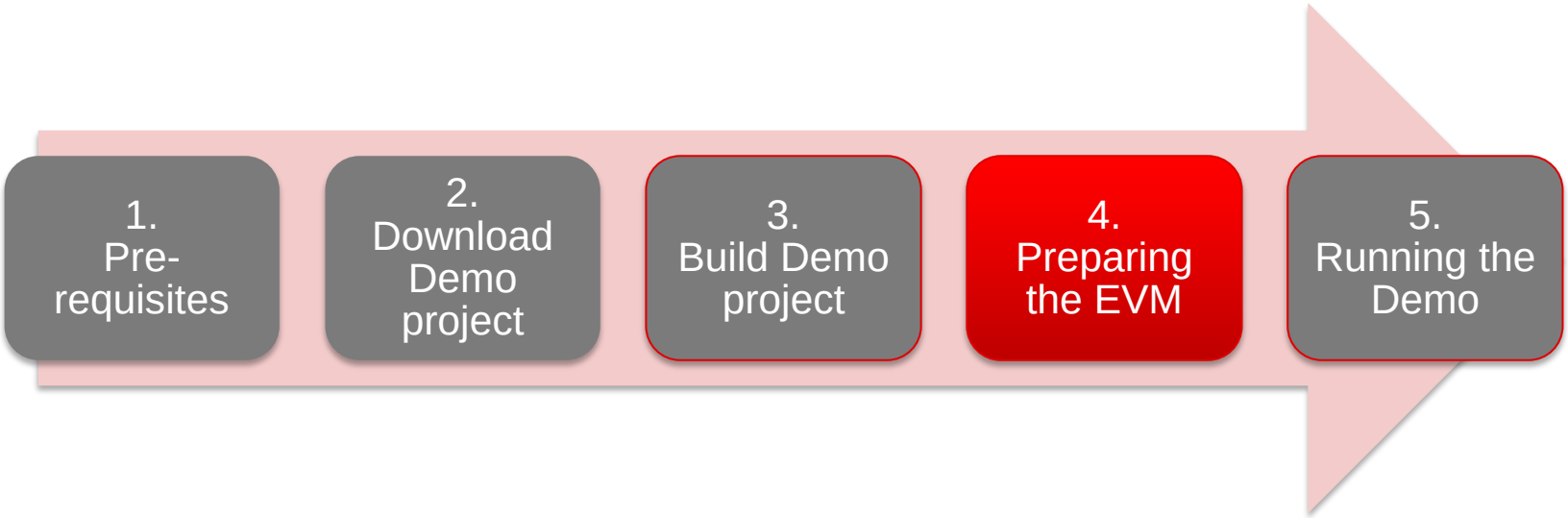


- On successful completion of the build, you should see the output in CCS console as shown here and the following two files should be produced in the project debug directory
  - xwr14xx_mmw_mss.xer4f
  - xwr14xx_mmw_mss.bin



- If the build fails with errors, please ensure that all the pre-requisites are installed as mentioned in the mmWave SDK release notes.

Steps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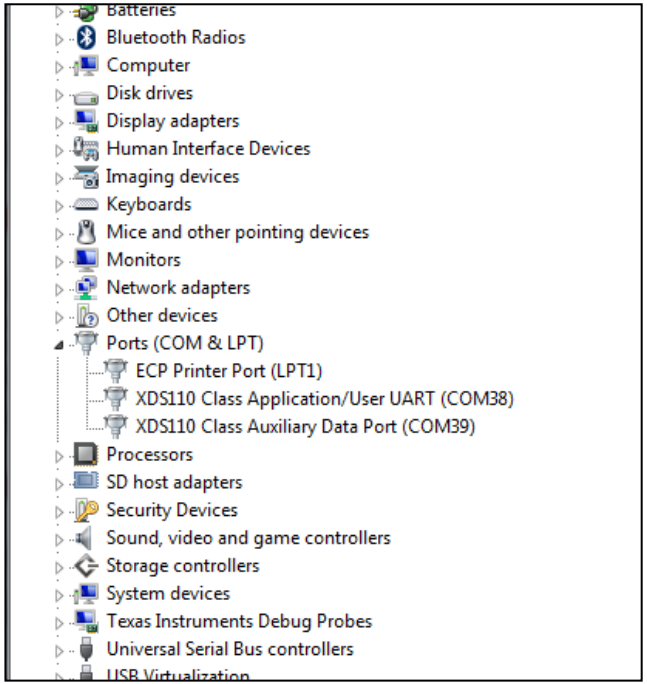
4.1 Preparing the EVM

- There are two ways to execute the compiled code on the EVM:
  - Deployment mode: Flashing the binary (.bin image) on to the EVM serial flash
    - In this mode, the EVM boots autonomously from flash and starts running the bin image.
  - Debug mode: Downloading and running the executable (.xer4f image) from CCS.
    - You will need to flash a small CCS debug firmware on the EVM (one time) to allow connecting with CCS. This debug firmware image is provided with the mmWave SDK.
  - As a recap, the build process in Step 3 produces both the .bin and .xer4f images.

- This presentation explains the second method i.e. Debug mode (CCS).
  - To prepare the EVM for debug mode, we start with flashing the CCS debug firmware image.
  - Please note that the same flashing process can be used to flash the Lab binary to run it in deployment mode.

4.2 Connecting to the EVM

- Power on the EVM using a 5V/2.5A power supply.
- Connect the EVM to your PC and check the COM ports in Windows Device Manager
- The EVM exports two virtual COM ports as shown below:
  - XDS110 Class Application/User UART (COM_{UART}):
    - Used for passing configuration data and firmware to the EVM
  - XDS110 Class Auxiliary Data Port (COM_{AUX})
    - Used to send processed radar data output
- Note the COM_{UART} and COM_{AUX} port numbers, as they will be used later for flashing and running the Lab.

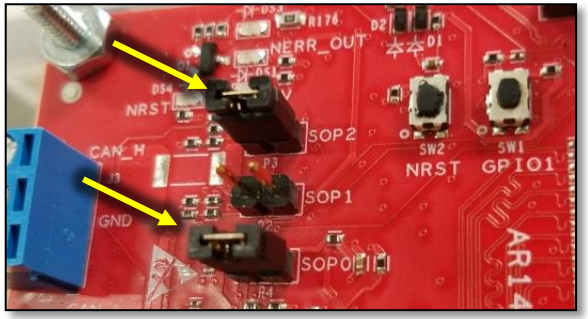


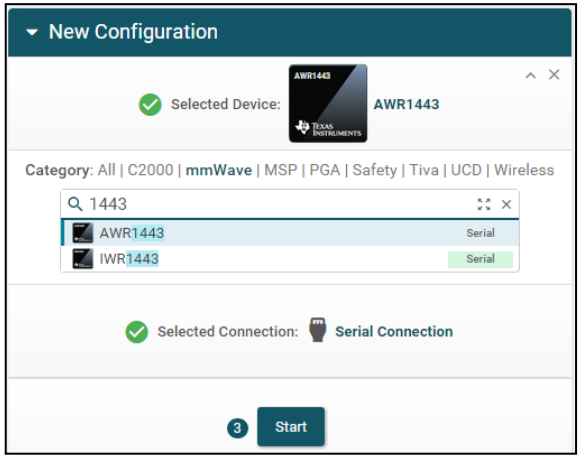
COM_{UART}: COM38 **COM_{AUX}**: COM39

- The actual port numbers on your machine may be different

4.3 Flashing CCS debug firmware

1. Put the EVM in flashing mode by connecting jumpers on SOP0 and SOP2 as shown in the image.
2. Open the **UniFlash** tool
3. In the **New Configuration** section, locate and select the appropriate device (xWR14xx)
4. Click **Start** to proceed



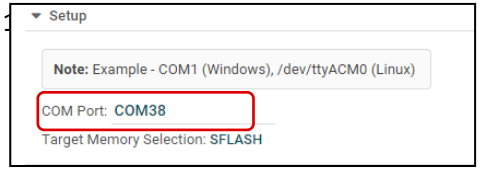


4.3 Flashing CCS debug firmware

5. In the **Program** tab, browse and locate the Radar SS and MSS images shown below:

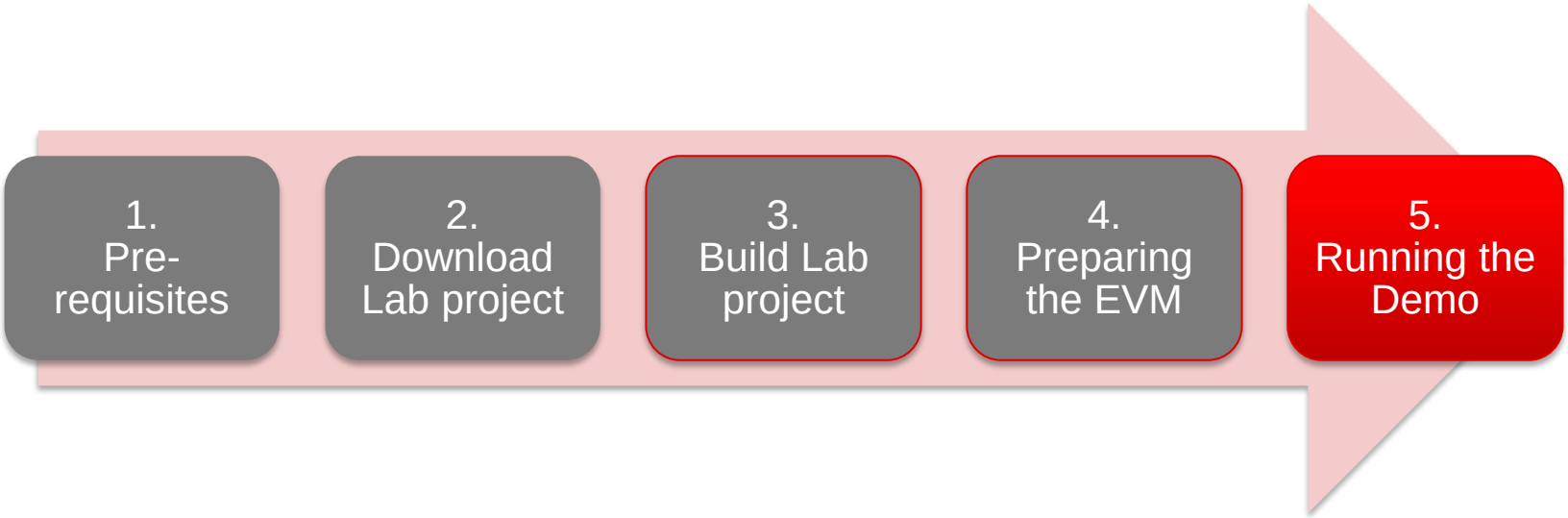
Image	Location
Meta Image 1/RadarSS	C:\ti\mmwave_sdk_<ver>\firmware\radarss**xwr12xx_xwr14xx_radarss.bin**
Meta Image 2/MSS	C:\ti\mmwave_sdk_<ver>\packages\ti\utils\ccsdebug**xwr14xx_ccsdebug_mss.bin**

6. In the **Settings & Utilities** tab, fill the **COM Port** text box with the Application/User UART COM port number (**COM_{UART}**) noted earlier



7. Return to the **Program** tab, power cycle the device and click on **Load Images**
8. When the flash procedure completes, UniFlash's console should indicate: [SUCCESS] Program Load completed successfully
9. Power off the board and remove the jumper from only header **SOP2** (this puts the board back in functional mode)

Steps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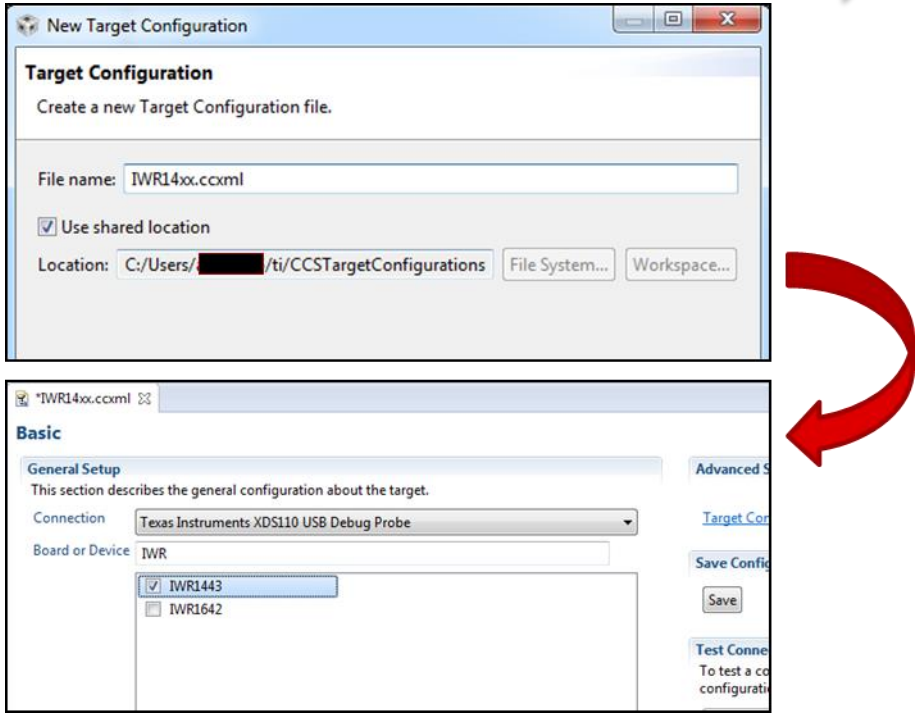
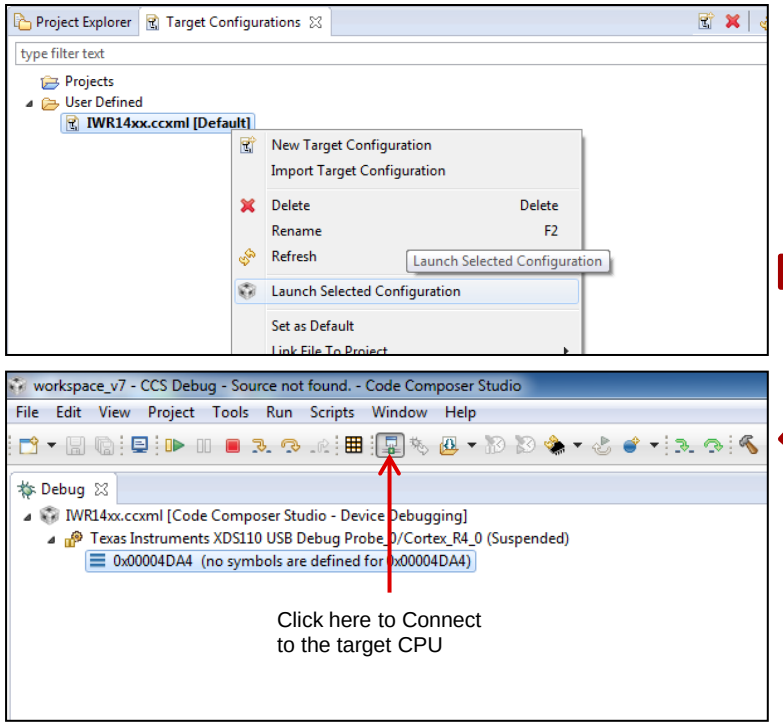
5.1 Connecting EVM to CCS

- It is assumed that you were able to download and build the Lab in CCS (completed steps 1, 2 and 3)
- To connect the Radar EVM to CCS, we need to create a target configuration
  - Go to File ► New ► New Target Configuration File
  - Name the target configuration accordingly and check the “Use shared location” checkbox. Press Finish
  - In the configuration editor window:
    - Select “Texas Instruments XDS110 USB Debug Probe” for **Connection**
    - Select **IWR1443** or **AWR1443** in the **Board or Device** list
    - Press the **Save** button to save the target configuration.
    - You can press the **Test Connection** button to check the connection with the board.



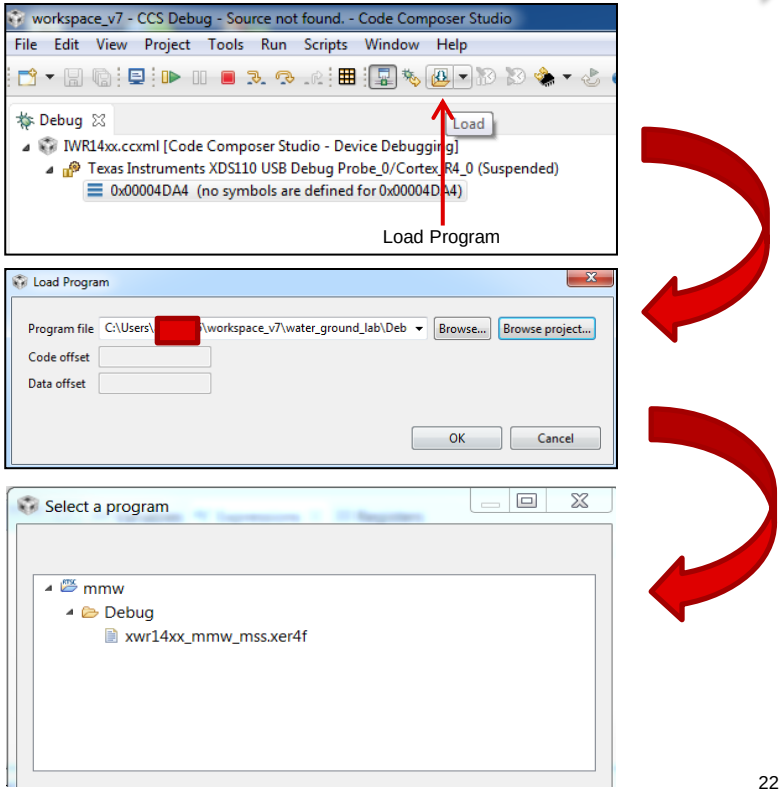
5.1 Connecting - continued

- Go to **View ► Target Configurations** to open the target configuration window.
- You should see your target configuration under **User Defined** configurations.
- Right click on the target configuration and select **Launch Select Configuration**.
- This will launch the target configuration in the debug window.
- Select the Texas Instruments XDS110 USB Debug probe and press the **Connect Target** button 



5.2 Loading the binary

- With the target connected, click on the **Load** button in the toolbar.
- In the **Load Program** dialog, press the **Browse Project** button .
- Select the lab executable (.xer4f) as shown and press OK.
- Press OK again in the **Load Program** dialog.

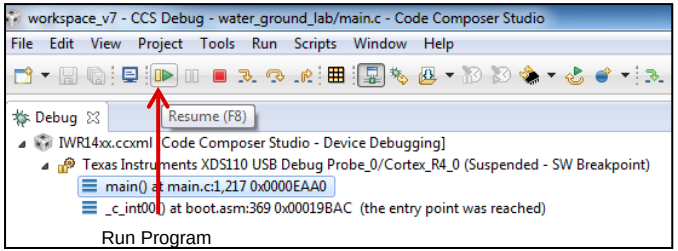


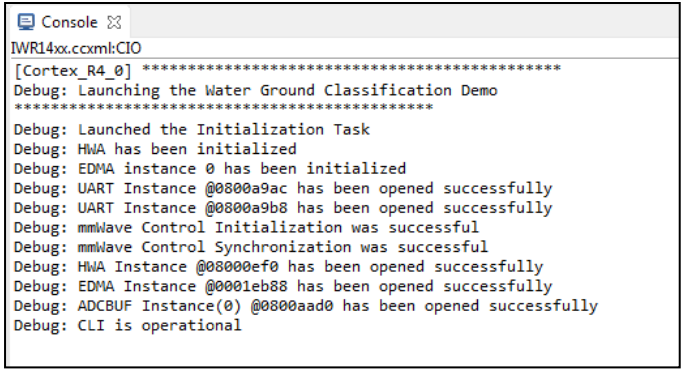
5.3 Running the binary

- With the executable loaded, press the Run/Resume button

- The program should start executing and generate console output as shown.

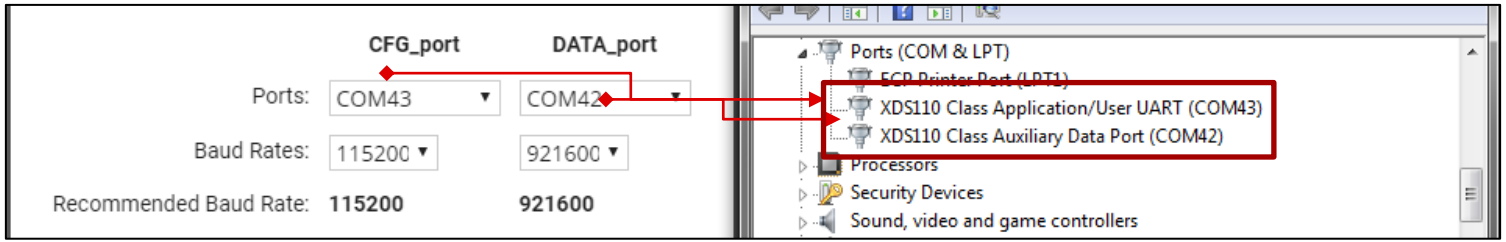
- If everything goes fine, you should see the “CLI is operational” message which indicates that the program is ready and waiting for the sensor configuration.





5.4 Running the Lab GUI

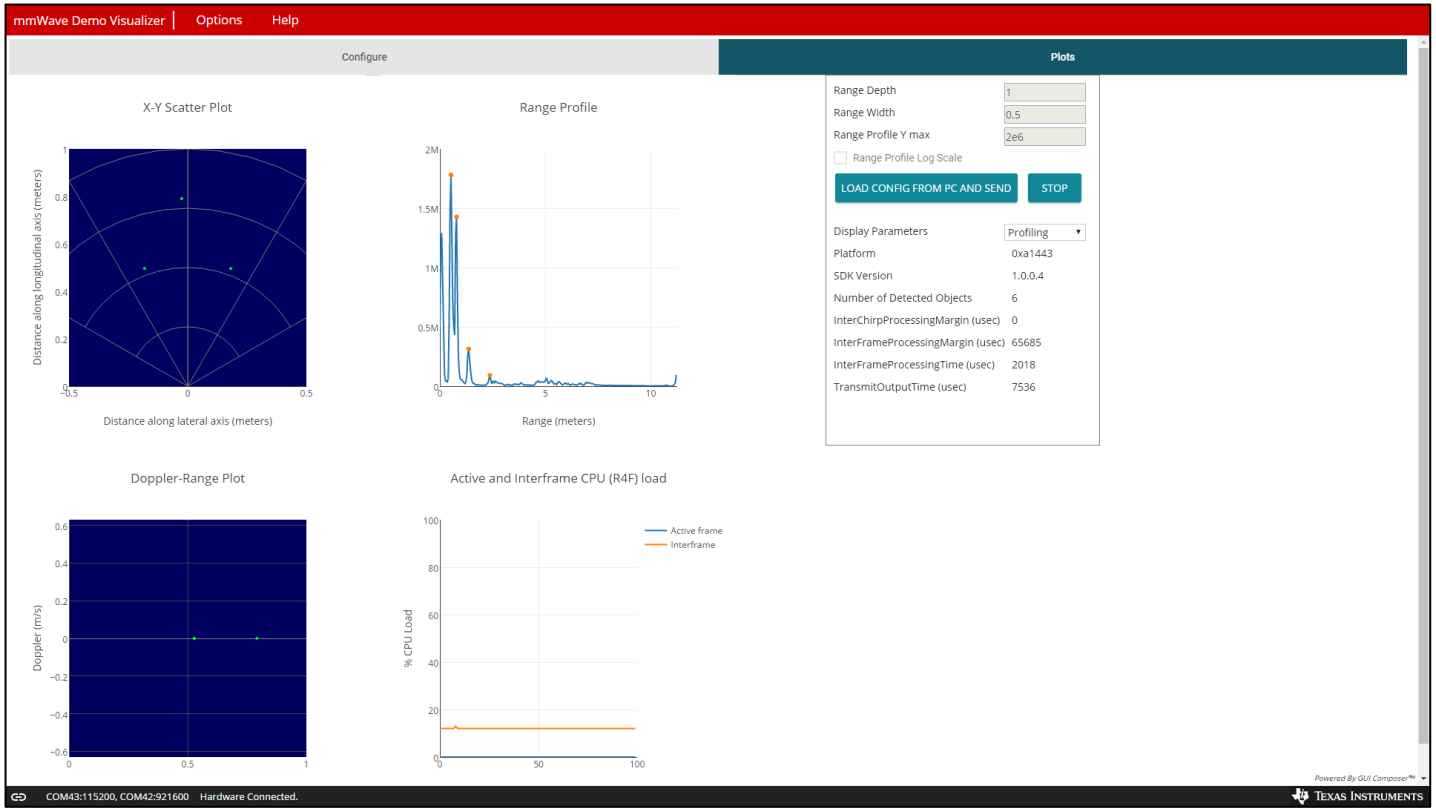
1. Using Google Chrome, navigate to the following URL: https://dev.ti.com/mmWaveDemoVisualizer
   – Alternatively, go to https://dev.ti.com/gallery and search for “mmWave Demo Visualizer”
2. If prompted, follow the on-screen instructions for installing TI Cloud Agent
3. Once the demo is loaded, go to **Options → Serial Port**
4. In the serial port window, enter the appropriate port in each of the drop down menus based on your port numbers from Step 2



5.4 Running GUI - continued

5. Click on **Configure** and the demo will automatically connect to the EVM
   - Not connected:  Connected: 
   - If the connection fails, try clicking on the connection icon in the bottom left corner
6. Select the appropriate mmWave device from the **Platform** dropdown menu
7. Use the available options to create the desired configuration
   - Additional details about the configuration parameters can be found in the **mmWave Demo Visualizer User Guide**
8. When ready to send the configuration, click on **Send Config To mmWave Device**
9. Click on the **Plots** tab to view the plots that were selected to be shown
10. Move a highly reflective object in front of the EVM and see how the demo responds

5.4 Running GUI - continued



Learn more about TI mmWave Sensors

- Learn more about xWR1x devices, please visit the product pages
  - IWR1443: http://www.ti.com/product/IWR1443
  - IWR1642: http://www.ti.com/product/IWR1642
  - AWR1443: http://www.ti.com/product/AWR1443
  - AWR1642: http://www.ti.com/product/AWR1642
- Get started evaluating the platform with xWR1x EVMs, purchase EVM at
  - IWR1443 EVM: http://www.ti.com/tool/IWR1443BOOST
  - IWR1642 EVM: http://www.ti.com/tool/IWR1642BOOST
  - AWR1443 EVM: http://www.ti.com/tool/AWR1443BOOST
  - AWR1642 EVM: http://www.ti.com/tool/AWR1642BOOST
- Download mmWave SDK @ http://www.ti.com/tool/MMWAVE-SDK
- Ask question on TI's E2E forum mmWave Sensors forum @ https://e2e.ti.com/support/sensor/mmwave_sensors/