For one of our application, we need to find current sensors that must have these characteristics:

• One current sensor with:

Bandwidth	3500Hz	
Nominal current	1A and 5A	
Nominal frequency	50Hz and 60Hz	
Temperature range	-40°C to +85°C	
Withstand	Sine wave of:	
	• 12.5A _{RMS} 50Hz permanently	
	50A _{RMS} 50Hz during 5s	
Dynamic range	±15A _{PEAK}	
Accuracy (1)	Applicable over the temperature range and at nominal frequency ±1% of:	
	 Amplitude error < 0.2%, phase error < 0.167° between 12.5mA and 	
	50mA	
	 Amplitude error < 0.1%, phase error < 0.08° between 50mA and 10A 	
Frequency response	0Hz: amplitude error between -100% and +1%	
	1Hz: amplitude error between -15% and +1%, phase error < 22°	
	Harmonics 2 to 4: amplitude error < 1%, phase error < 1°	
	Harmonics 5 to 6: amplitude error < 2%, phase error < 2°	
	Harmonics 7 to 9: amplitude error < 4%, phase error < 4°	
	Harmonics 10 to 13: amplitude error < 8%, phase error < 8°	
	Harmonics > 13: amplitude error between -100% to +8%	

⁽¹⁾ If necessary, a digital current/frequency/temperature-dependent calibration system could be used to achieve these accuracy figures. In any cases, the sensor shall exhibit a linear transfer function in the ranges of interest to reduce the complexity of the calibration process

• A second sensor with:

Nominal current	1A and 5A
Nominal frequency	50Hz and 60Hz
Temperature range	-40°C to +85°C
Withstand	Sine wave of: • 20A _{RMS} 50Hz permanently • 150A _{RMS} 50Hz during 5s • 500A _{RMS} 50Hz during 1s • 1250A _{RMS} 50Hz during 10ms
Dynamic range	±430A _{PEAK}
Accuracy (1)	Applicable over the temperature range and at nominal frequency - 4%/+2% of: • Amplitude error < 0.1%, phase error < 0.08° at 1A and 5A
Transient error limit under the specified operating cycle condition	AC component error peak of 6% in respect with CEI 61869-2 with: • Ksscs = 30 • t' = 160ms • tfr = 300ms • t'' = 300ms • t'al = 160ms • t''al = 300ms • Tp = 180ms

⁽¹⁾ If necessary, a digital current/frequency/temperature-dependent calibration system could be used to achieve these accuracy figures. In any cases, the sensor shall exhibit a linear transfer function in the ranges of interest to reduce the complexity of the calibration process