

## INTERFACING A WATER FLOW-METER SENSOR TO TDC1000-TDC7200EVM

Ultrasonic flow-meters are gaining wide usage in commercial, industrial and medical applications. Major benefits of utilizing this type of flow meter are; higher accuracy, low maintenance (no moving parts), non-invasive flow measurement, and the ability to diagnose the meter's health regularly. A major advantage of using TI's ultrasonic sensing is the ultralow power consumption which allows metering companies to use the same battery for a very long time.

This article is intended as an introduction to ultrasonic flow sensing and describes demonstration a setup to measure velocity of flow in a pipe using an ultrasonic water flow-meter sensor, TDC1000 ultrasonic analog-front-end (UAFE) and TDC7200 precision time interval timer.

### Background: Transient-time Ultrasonic Flow-meters

In Figure 1, a typical ultrasonic flow sensor is shown. The sensor consist of a pipe with nominal diameter of "D" and two piezoelectric transducers placed at fixed distance "L" from each other. The transducers are mounted in a protective housing. The housing and the transducers are inserted in the holes in the pipe, exposing the inner cover to the fluid in the pipe. Two reflection mirrors in the pipe direct the ultrasonic signals from one transducer to the other one in the opposite location.

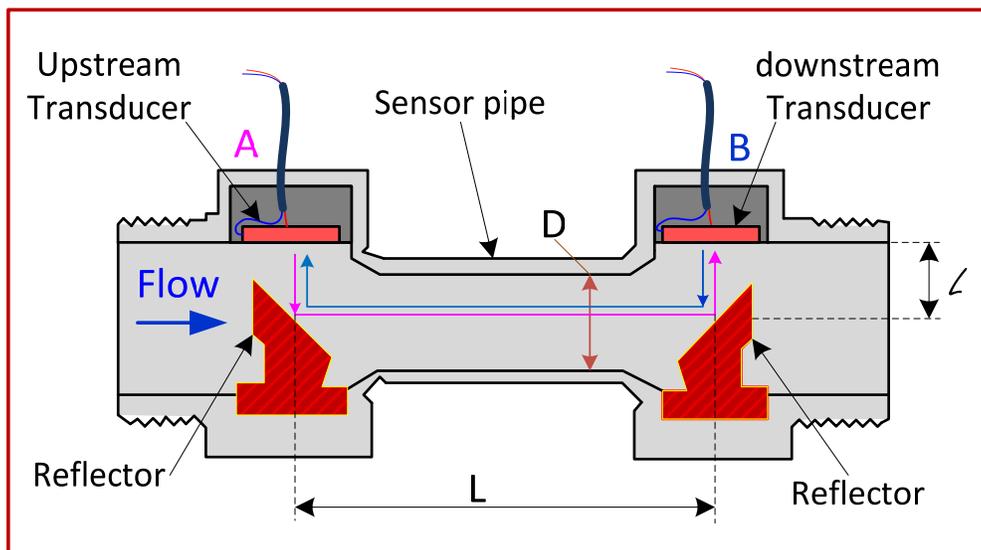


Figure 1. ultrasonic water flow-meter pipe.

The single path sensor of Figure 1 is used for flow applications where the diameter of the pipe is small. For larger diameter pipes sensors with multiple paths are used. Other types of ultrasonic flow sensors are available with clamped-on transducers. In this article we have limited the discussion to reflective-type single path sensors such as one shown in Figure 1.

## Measurement sequence

Referring to Figure 2, the measurement sequence starts by exciting one of the transducer, i.e. “A”, by applying a burst of given number of pulses (in Figure 2, three TX pulses) to the transducer. The frequency of excitation signal must be equal to the resonance frequency of the transducer. For water flow applications, transducers with resonant frequency of one to three MHz are used.

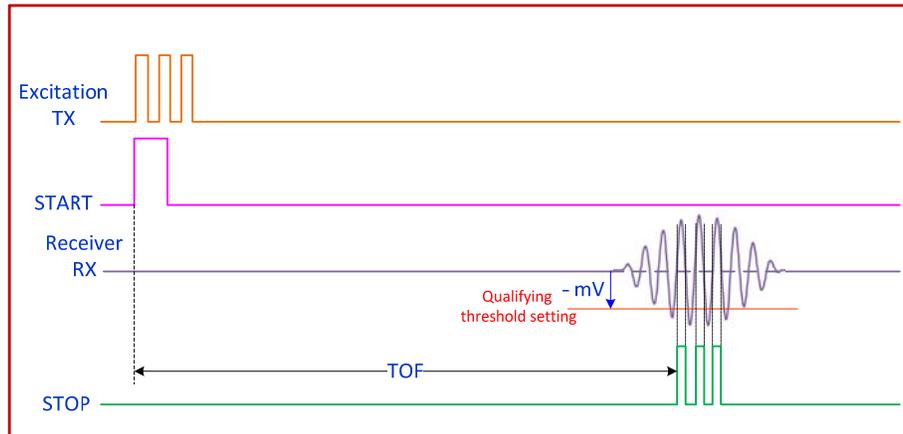


Figure 2. ultrasonic signal measurement sequence.

The transducer generates ultrasonic pressure pulses that are directed towards the second transducer, in this case B, by means of the reflectors in the pipe. At the same time that the first pulse is being applied to the transducer, a “START” signal is generated to mark the beginning of the “time-of-flight” measurement.

On the receiver side, the electronic circuits in the path condition the received signal and generate a “STOP” pulse to mark the time the ultrasonic pulse is received at the other end. The time taken for the ultrasound wave to travel from one sensor to the other is referred as the “Time-Of-Flight” (TOF). A stop watch is needed to measure the time interval between the “START” and “STOP”, in this case  $TOF_{AB}$ .

The direction of the transmit/receive sequence is switched and next the  $TOF_{BA}$  is measured. The difference between  $TOF_{AB}$  and  $TOF_{BA}$  is proportional to the velocity of the flow of the medium in the pipe.

## Volumetric flow calculations:

The expressions for calculating the TOF between two transducers is given as:

$$TOF = \frac{\text{Distance between the transducers}}{\text{speed of sound}}$$

Referring to Figure 1 , the expressions for TOF for downstream ( $TOF_{AB}$ ) and upstream ( $TOF_{BA}$ ) are:

$$TOF_{AB} = \frac{1}{C} L + \frac{L}{C+V} + \frac{1}{C} L \quad (1)$$

$$TOF_{BA} = \frac{1}{C} L + \frac{L}{C-V} + \frac{1}{C} L \quad (2)$$

$$\Delta T = \text{TOF}_{\text{BA}} - \text{TOF}_{\text{AB}} \quad (3)$$

Where:

$$L = D/2 \quad ; D \text{ is the inner diameter of the pipe}$$

$C$  = Speed of sound in the medium

$V$  = Average velocity of the medium (fluid/gas) in the pipe

Rearranging the terms and solving for V:

$$\begin{aligned} \Delta \text{TOF} &= \left( \frac{D}{C} + \frac{L}{C-V} \right) - \left( \frac{D}{C} + \frac{L}{C+V} \right) \\ &= \frac{L2}{C-V} - \frac{L2}{C+V} \\ &= \frac{(C+V)L - (C-V)L}{C^2 - V^2} \end{aligned}$$

$$\Delta T (C^2 - V^2) = 2 * L * V$$

Since  $C \gg V$

$$(C^2 - V^2) \sim C^2$$

And

$$\Delta T * C^2 = 2 * L * V$$

$$V = \frac{\Delta T * C^2}{2L} \quad (4)$$

### Calculation of Volumetric Flow rate, Q

The relationship for calculate the volumetric flow rate is:

$$Q = K * V * A$$

Where:

K = Pipe calibration factor depending on the sensor

V = Average velocity though of the fluid in the pipe.

A = The cross-sectional area of the meter pipe.

TDC 1000 uses a common approach known as “zero-crossing” method to generate the “START” and “STOP”. At low flow rates, the difference between  $\text{TOF}_{\text{AB}}$  and  $\text{TOF}_{\text{BA}}$  is very small, for this reason a highly accurate timer such as TDC7200 with picoseconds resolution is required.

## Zero Flow Measurement Setup

In this document, we describe interfacing of TDC1000 and TDC7200 integrated circuits. The block diagram of the setup is shown in Figure 3. MSP430 microcontroller is used to programming of TDC1000 and TDC7200 and for communication with a host PC over USB interface. A Graphic User Interface (GUI) is used for programming the registers of TDC1000 and TDC7200 and for displaying  $\Delta$ TOF at zero flow condition.

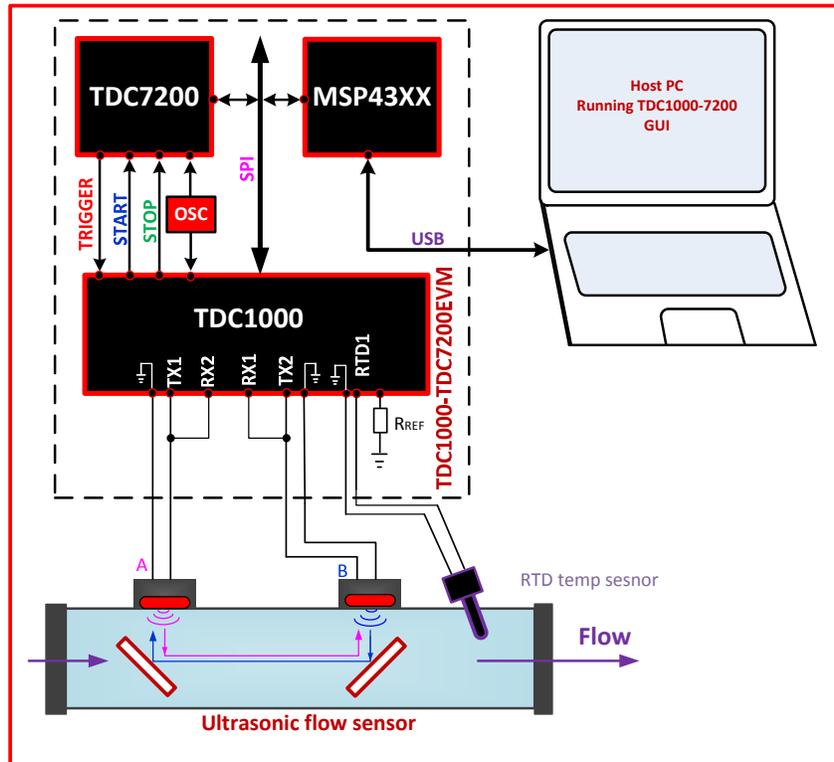


Figure 3. zero flow measurement setup

## The Choice of the Ultrasonic Flow-meter Sensor

The zero-flow demonstration setup is shown in Figure 4.

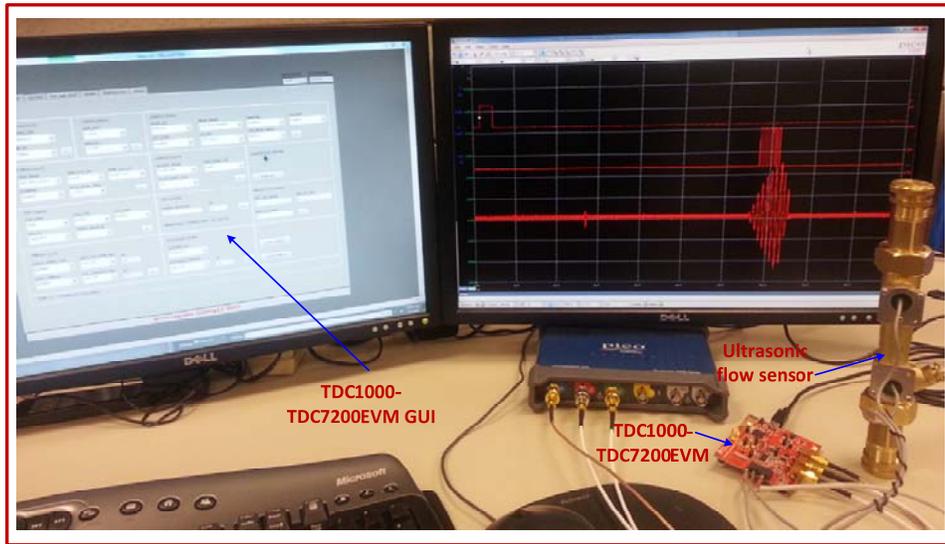


Figure 4. zero flow demonstration setup

System requirements, standards, and cost dictate the choice of flow-meter sensors. Water is a good medium for propagating ultrasonic pressure pulse and the most common sensors in this application have resonance frequency in the range of MHz, 1 MHz in this case.

For the demonstration purpose we use an Audiowell ultrasonic water flow-meter pipe shown in Figure 4. This sensor can be obtained from the source included in the reference section.

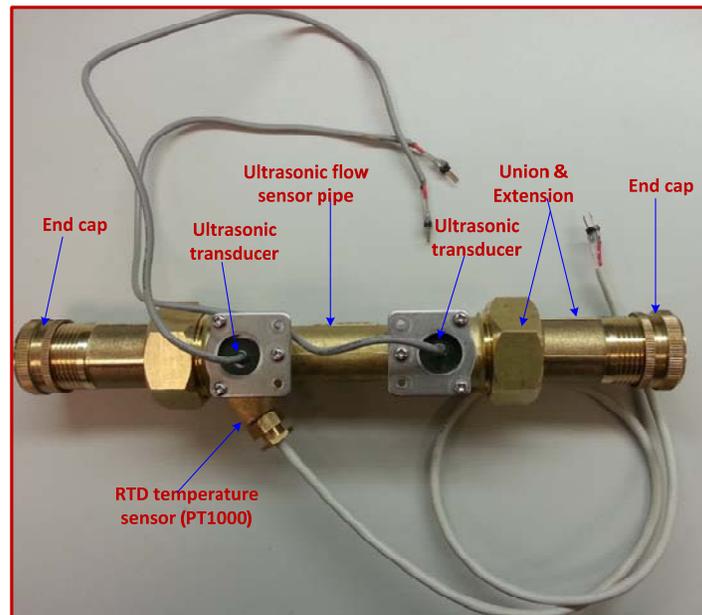


Figure 5. ultrasonic flow-meter sensor pipe

## Steps to configure the setup

1. Obtain a TDC1000-TDC7200EVM
2. Obtain the ultrasonic water flow sensor shown in Figure 5 from the source in the reference section of this document. The union and the pipe extension are not necessary for zero flow test but you would need the end caps to confine water in the pipe for the test. The RTD temperature sensor is not include in the sensor and can be obtained from a different manufacturer. The RTD used in this setup is a JUMO PT1000. If you need to use a PT500 temperature sensor, you would need to change the temp sensor reference resistor ( $R_{REF}$ ) on the TDC1000-TDC7200EVM to 500  $\Omega$  (the EVM board comes with a 1000  $\Omega$  resistor reference resistor).
3. Place a cap at one end of the sensor and fill the pipe with clean water. Make sure there are no bubbles trapped in the sensor. Place the second cap and the open end open of the pipe to confine water inside the pipe.
4. Connect the sensor to the EVM connector as shown below. Place the pipe on a flat surface in a standup position as shown if Figure 4. This would move up any bubbles trapped between the two transducers to the top of the pipe and away from the signal path. Bubbles trapped in the signal path causes severe attenuation of signal.
5. You may want to view the signal waveforms (Start, Stop, and Ultrasound received waveform at the input of TDC1000 internal comparators) on a scope to make sure proper operation of the sensor. You can either connect the scope probes to the provided terminals (test points) on the EVM or solder SMA connector on the EVM board and use the cables shown in Figure 4

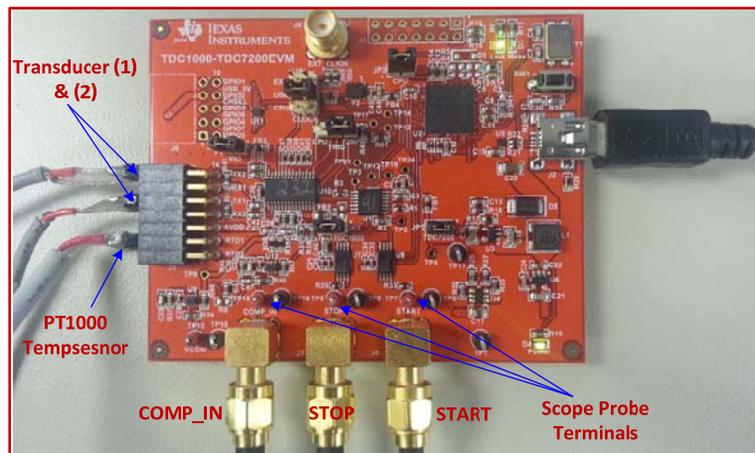


Figure 6, EVM connections to the sensor

6. Install the TDC1000-TDC7200EVM software per the instruction in the user's manual
7. Connect the EVM to the Host PC using the provided USB cable

## GUI Configuration

8. Run the GUI; if prompted, upgrade the version of the EVM firmware per the instructions in the TDC1000-TDC7200EVM User's Manual.
9. Set the registers in the TDC1000 menu to the values shown in Figure 7, Figure 8, and Figure 9. Flip the "CONTINUOUS TRIGGER" switch to the top position (switch will turn to green from red indicating that the system is running).



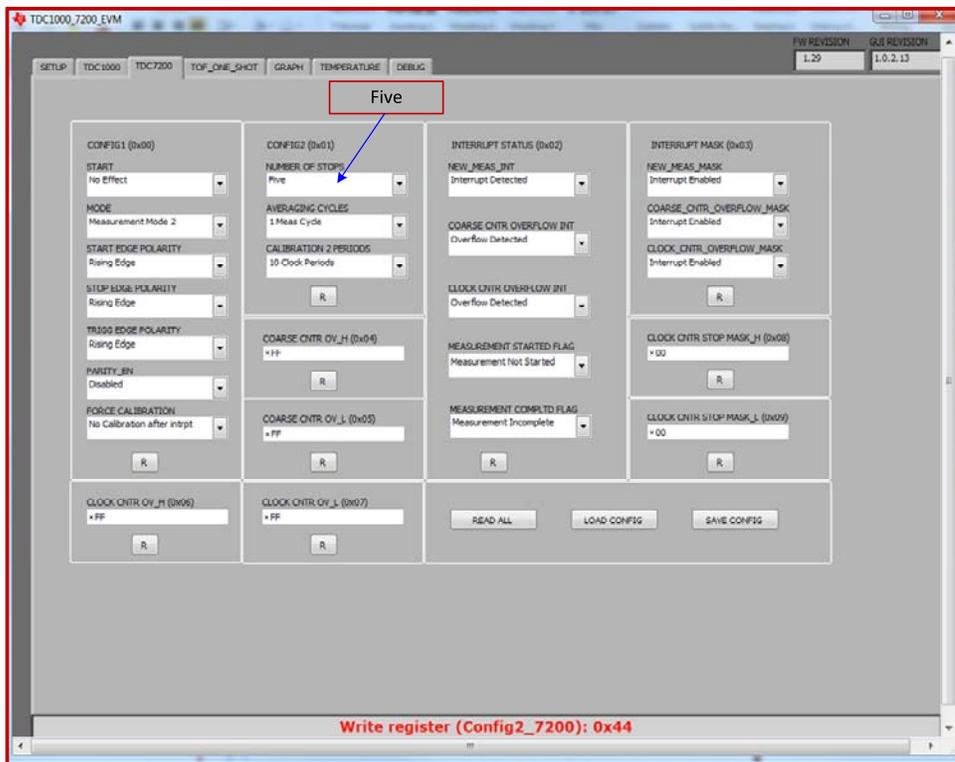


Figure 9. TDC7200 registers setup

## Observing the waveform using an oscilloscope

If you are using a scope, use three channels to observe the signal traces as given below:

CHA A : START, 5V/DIV  
 CHA B: STOP, 5V/DIV  
 CHA C: COMP\_IN, 5V/DIV  
 Trigger: Normal, on Ch A  
 Time base: 20uV/DIV

You should be able to get similar display on you scope screen as shown in Figure 10. The time of flight can be measured reference to STOP pulse one to five. When calculating the delta TOF, if the same STOP pulse is used to measure the TOF for upstream and downstream, the net effect is canceled out and the delta TOF is the same no matter what STOP pulse is used to measure The TOF.

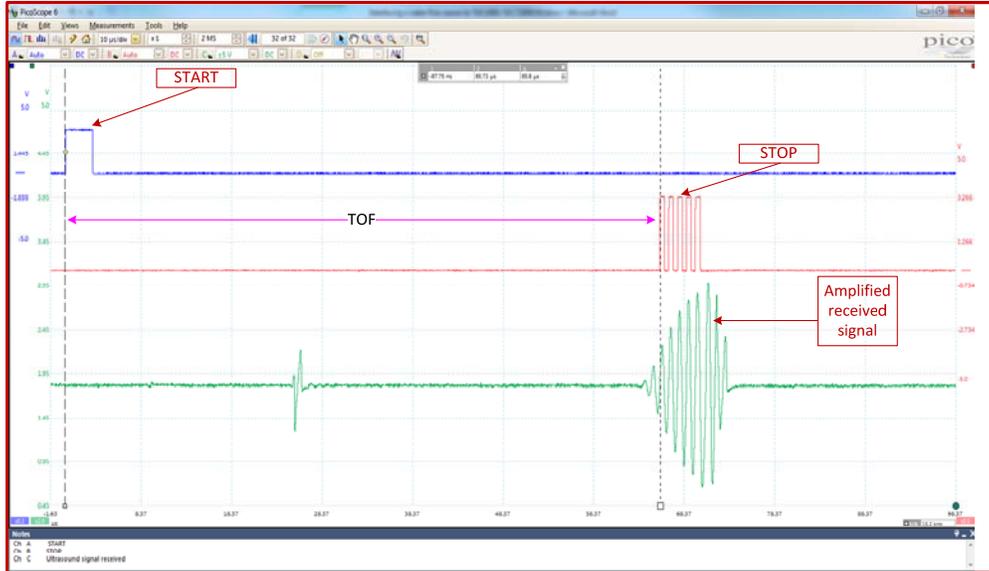


Figure 10. scope trace TOF measurement sequence

Now change the time base of the scope to 200 uV/DIV, you should see the TX/RX sequence for both directions as shown in Figure 11. In mode 2 of TDC1000 operation if CH\_SWP is enabled, the state machine upon receiving a trigger pulse will TX/RX in one direction, then switch the direction and upon receiving a second trigger will TX/RX in the other direction.

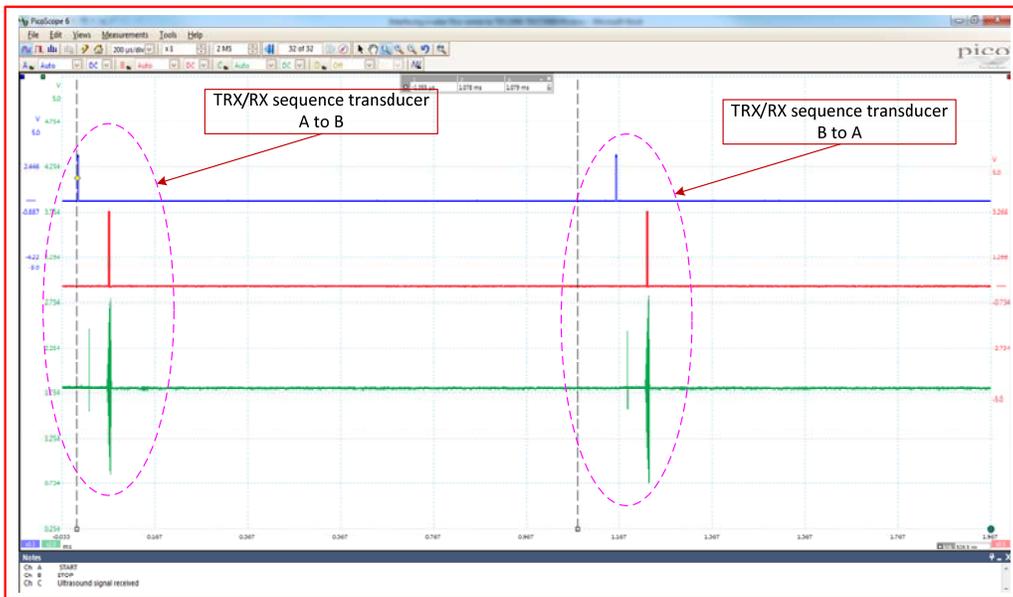


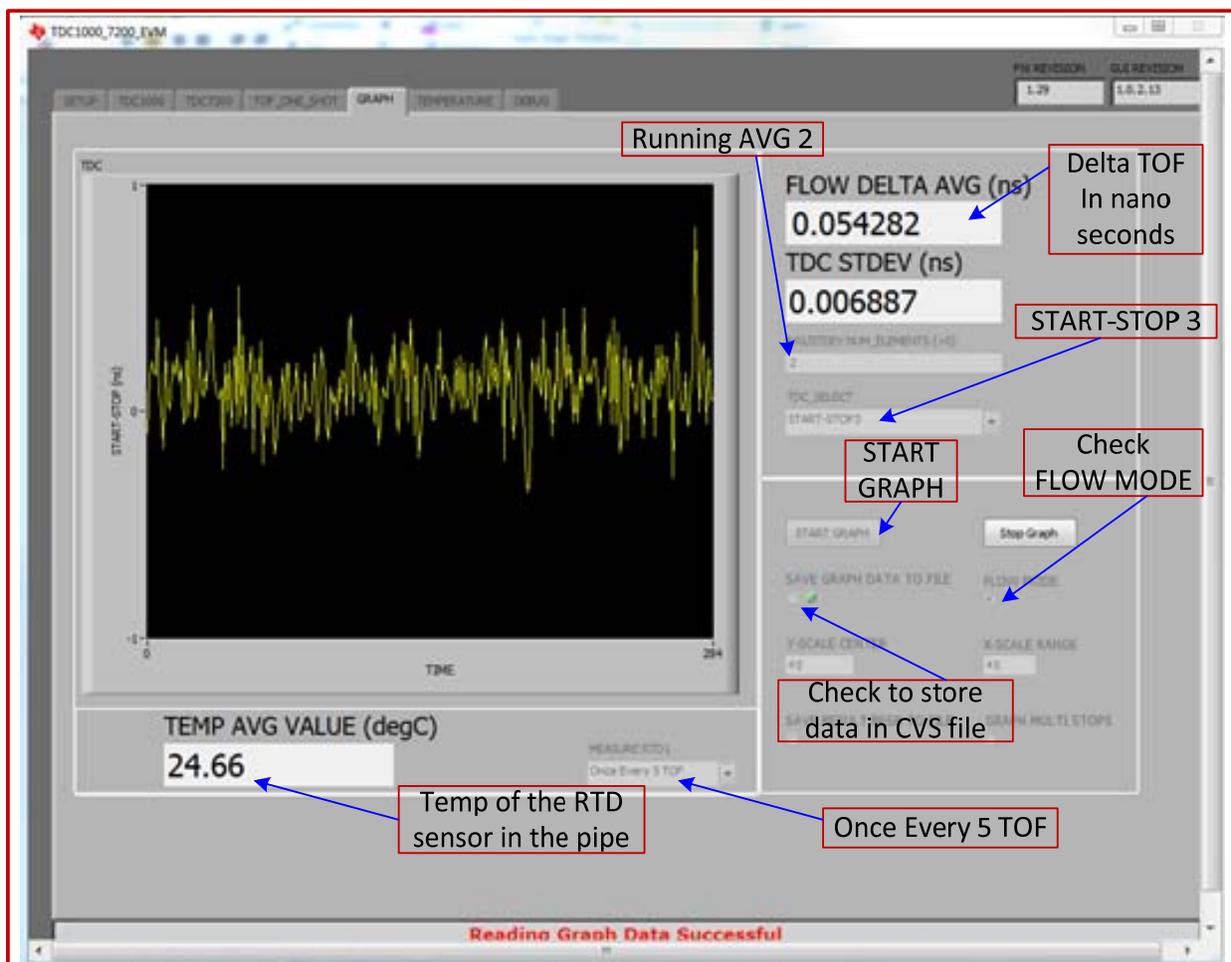
Figure 11. ΔTOF measurement sequence

### Displaying the delta TOF in GUI's GRAPH menu

Click on the "GRAPH" tab to display the "GRAPH" menu. In the box below "Flow MODE" on the right bottom corner of the display, check the flow mode option. In this mode the GUI generates a

downstream and upstream sequence and calculates the “Delta TOF” and display it at the top right of the screen under “FLOW DELTA AVG (ns)”. Under “TDC\_SELECT” chose the STOP pulse (STOP1, STOP2, etc) that provides the best accuracy in calculating the TOF. Try different selection and observe the changes in delta TOF and STADEV. As mentioned in the previous section, as the TOF in the upstream and the downstream directions are measured reference to the same STOP pulse, the net effect is independent of the choice of the STOP pulse.

To start the graph, click on “START Graph” tab, you should see the yellow moving trace of the delta TOF versus time as shown in Figure 12. If the numbers in delta TOF and the STDEV boxes are changing but the graph is not being displayed (black screen) then the graph is out of scale. To force the graph to be displayed in the window, place the cursor on the black background and right-click your mouse. A drop window display will show up giving you the option to select auto scale in the X and Y axis. Once you check mark the auto scale box, the GUI will scale the graph to fit in the display window.



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Figure 12.  $\Delta$ TOF graph display

### Saving data in a file

To save data in a file for post processing purpose, check the box “SAVE GRAPH DATA TO FILE” before running the graph by clicking on “START GRAPH” button. You will be asked to name the file and identify a location on your computer to store the file. When you type in the information click the ok tab, you will be prompted to type the number of samples to be saved. If type ok without typing in the number of samples in the displayed box (0 samples by default), the GUI will continuously save unlimited number of data in the file until the “STOP GRAPH” tab is pressed to stop displaying the graph. The content of the file includes information as shown in Figure 13.

	A	B	C	D	E	F	G
1	Start_to_Stop1	Start_to_Stop2	Start_to_Stop3	Start_to_Stop4	Start_to_Stop5	Delta_TOF	RTD1 Temp
2	63644.77881	64619.45727	65775.96333	66812.95379	67883.51831	0	46.299204
3	63645.3517	64620.56811	65783.53074	66821.02685	67884.44692	-1.110845	46.299204
4	63645.06949	64619.8076	65776.37038	66814.35072	67883.92626	0	46.299204
5	63645.89061	64621.03195	65783.96182	66822.59194	67884.45329	-1.224349	46.299204
6	63645.31445	64620.09651	65776.50218	66814.67933	67883.93135	0	46.299204
7	63646.22752	64621.32601	65784.52387	66822.48847	67885.14722	-1.229494	46.299204
8	63645.47364	64620.15866	65776.42324	66813.92907	67884.62436	0	46.299204
9	63646.47303	64621.49896	65783.90171	66822.12137	67885.56146	-1.340307	46.299204
10	63645.65826	64620.33147	65777.36928	66815.00934	67884.45378	0	46.299204
11	63646.40247	64621.61759	65784.05733	66822.13856	67885.49712	-1.286128	46.299204
12	63646.0613	64620.85775	65777.65389	66814.93414	67885.32645	0	45.693814
13	63647.29109	64622.54915	65785.36231	66823.17548	67886.02884	-1.691396	45.693814
14	63646.52803	64621.32448	65777.88726	66815.34253	67885.44314	0	45.693814
15	63647.76147	64622.9573	65785.36782	66823.42032	67886.49746	-1.632822	45.693814
16	63646.65594	64621.38095	65778.31033	66815.0262	67885.91553	0	45.693814
17	63648.0473	64623.24957	65785.53369	66824.50988	67886.55282	-1.868625	45.693814
18	63646.76365	64621.67419	65778.24024	66815.466	67885.85265	0	45.693814
19	63647.87226	64623.13288	65785.70873	66824.0431	67886.90291	-1.45869	45.693814
20	63647.28878	64622.08262	65778.29858	66815.64105	67886.37778	0	45.693814
21	63648.28069	64623.48296	65785.70873	66824.45153	67887.253	-1.400342	45.693814

Figure 13. Sample data stored in a file

### Appendix 1: Sensor manufacturer

Application	Manufacturer	P/N	FR (kHz)
Heat/water	AudioWell <a href="http://www.audiowell.com/en/product-detail.aspx?id=80">http://www.audiowell.com/en/product-detail.aspx?id=80</a>	Brass Pipe For Heat meter DN25. Ultrasonic flow sensor AW5Y0980K04L193Z	1000
Heat/water	AudioWell <a href="http://www.audiowell.com/en/product-detail.aspx?id=80">http://www.audiowell.com/en/product-detail.aspx?id=80</a>	Brass Pipe For Heat meter DN20. Ultrasonic flow sensor AW5Y0980K08L151Z	1000