## Derivation of a FMCW Beat Frequency

Given a transmitted signal with a linear modulated frequency

$$
V_t = a_1 \cos(\phi(t)) \tag{1}
$$

where  $a_1$  is an amplitude constant and  $\phi(t)$  is a phase function of time, (t) being defined as

$$
\phi(t) = \omega_o t + \frac{1}{2} m t^2 + \phi_o \tag{2}
$$

where  $m = 2\pi \frac{BW}{T_c}$  $\frac{3W}{T_p}$  with  $BW$  is the bandwidth of the signal,  $T_p$  is the time period of the frequency ramp and  $\phi_o$  is an arbitrary phase constant. The initial radian frequency is  $\omega_o = 2\pi f_o$  with  $f_o$  being the initial frequency of the ramp. The radian frequency of this signal is then

$$
\frac{d\phi(t)}{dt} = \omega = \omega_o + mt \tag{3}
$$

The received signal is then

$$
V_r = a_2 \cos(\phi(t - T_d))
$$
\n(4)

where  $a_1$  is an amplitude constant and  $\phi(t - T_d)$  is the transmitted phase function delayed by  $T_d = 2R/c$  which is due the the propagation of the signal through a one way distance of  $R$  at the speed of light,  $c$ .

The IF signal at a mixer is then

$$
V_b = V_t V_r = a_1 a_2 a_3 \cos \left[ \omega_o t + \frac{1}{2} m t^2 + \phi_o \right] \cos \left[ \omega_o t + \frac{1}{2} m t^2 + \phi_o - T_d + \phi_1 \right] \tag{5}
$$

where  $a_3$  and  $\phi_1$  are amplitude and phase constants associated with the mixer.

Reducing the product of the cosines yields

$$
V_b = \frac{1}{2} a_1 a_2 a_3 \cos \left[ mT_d t + \omega_o T_d + \frac{m}{2} T_d^2 - \phi_1 + \text{higher order terms} \right] \tag{6}
$$

or

$$
V_b = \frac{1}{2} a_1 a_2 a_3 \cos \left[ \omega_b t + \phi_c - \phi_1 \right]
$$
 (7)

where  $\omega_b = 2\pi f_b$  with  $f_b$  is the beat frequency is given by

$$
\frac{BW}{T_p} \frac{2R}{c} \tag{8}
$$

and phase constant is given by

$$
\phi_c = 2\pi \frac{2R}{\lambda_o} \tag{9}
$$

with  $\lambda_o = c/f_o$ . The term  $\frac{m}{2}T_d^2$  $\frac{d^2}{dt}$  is very small and dropped.