

## **SN65DSI86 SW Examples**

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### **ABSTRACT**

The document contains examples of how to program the SN65DSI86 for different purposes. All examples in the document are written using the Total Phase Aardvark I2C controller script language. Software engineers should be able to take the scripts and port them to their specific environment.

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## Introduction

The SN65DSI86/96 DSI to embedded DisplayPort (eDP) bridge features a dual-channel MIPI® D-PHY receiver front-end configuration with 4 lanes per channel operating at 1.5Gbps per lane; a maximum input bandwidth of 12Gbps. The bridge decodes MIPI® DSI 18bpp RGB666 and 24bpp RGB888 packets and converts the formatted video data stream to DisplayPort with up to four lanes at either 1.62Gbps, 2.16Gbps, 2.43Gbps, 2.7Gbps, 3.24Gbps, 4.32Gbps, or 5.4Gbps.

This document provides examples of how to program the SN65DSI86 for various different purposes. The scripts below are for a Total Phase Aardvark I2C controller. Details on the Total phase Aardvark I2C controller can be obtained from the Total Phase website.

## References

1. [SN65DSI86 Datasheet](#) (SLLSEH2)
2. [Aardvark Adapter User Manual](#)
3. *VESA DisplayPort Standard Version 1, Revision 2a. May 23, 2012*

## Read Sink's EDID (Direct Method)

This script will read 256 bytes of the EDID.

```
<aardvark>
<configure i2c="1" spi="1" gpio="0" tpower="1" pullups="0" />
<i2c_bitrate khz="100" />

=====Enable I2C_ADDR_CLAIM1=====
<i2c_write addr="0x2D" count="1" radix="16">60 A1</i2c_write> />

=====Write EDID base of 00 =====
<i2c_write addr="0x50" count="0" radix="16">00</i2c_write> />

=====Read 256 bytes of EDID=====
<i2c_read addr="0x50" count="256" radix="16">00</i2c_read> />

</aardvark>
```

## Read Sink's DPCD Register

This example will read 16-bytes from sink's DPCD registers 0x00000.

```
<aardvark>
<configure i2c="1" spi="1" gpio="0" tpower="1" pullups="0" />
<i2c_bitrate khz="100" />

=====Clear Status Registers for AUX Request=====
```

```

<i2c_write addr="0x2D" count="1" radix="16">F4 FF</i2c_write> />

=====Send AUX Request for 16 bytes from DPCD 0x00000 =====
=====DPCD Address is 0x00000 =====
<i2c_write addr="0x2D" count="1" radix="16">74 00</i2c_write> />
<i2c_write addr="0x2D" count="1" radix="16">75 00</i2c_write> />
<i2c_write addr="0x2D" count="1" radix="16">76 00</i2c_write> />
=====Number of Bytes to Read is 16 =====
<i2c_write addr="0x2D" count="1" radix="16">77 10</i2c_write> />
=====Send AUX Read Request =====
<i2c_write addr="0x2D" count="1" radix="16">78 91</i2c_write> <sleep ms="20" />

=====Read Status of AUX Request=====
=====Make sure SEND_INT is set and no errors=====
<i2c_write addr="0x2D" count="0" radix="16">F4</i2c_write> />
<i2c_read addr="0x2D" count="1" radix="16">00</i2c_read> />

=====Clear Status Registers for AUX Request=====
<i2c_write addr="0x2D" count="1" radix="16">F4 FF</i2c_write> />

=====Read 16 bytes from AUX_RDATA=====
<i2c_write addr="0x2D" count="0" radix="16">79</i2c_write> />
<i2c_read addr="0x2D" count="16" radix="16">00</i2c_read> />

</aardvark>

```

## Write Sink's DPCD Register

This example will write a 0x01 to the Sink's DPCD 0x0010A register.

```

<aardvark>
<configure i2c="1" spi="1" gpio="0" tpower="1" pullups="0" />
<i2c_bitrate khz="100" />

=====Clear Status Registers for AUX Write Request=====
<i2c_write addr="0x2D" count="1" radix="16">F4 FF</i2c_write> />

=====Write DPCD Register 0x0010A in Sink to Enable ASSR=====
=====Data to Write is 0x01. =====
<i2c_write addr="0x2D" count="1" radix="16">64 01</i2c_write> />
=====DPCD Register is 0x0010A. =====
<i2c_write addr="0x2D" count="1" radix="16">74 00</i2c_write> />
<i2c_write addr="0x2D" count="1" radix="16">75 01</i2c_write> />
<i2c_write addr="0x2D" count="1" radix="16">76 0A</i2c_write> />
=====Number of Bytes to Write is 1 =====
<i2c_write addr="0x2D" count="1" radix="16">77 01</i2c_write> />
=====Send AUX Write Request =====
<i2c_write addr="0x2D" count="1" radix="16">78 81</i2c_write> <sleep ms="10" />

=====Read Status of AUX Request=====
=====Make sure SEND_INT is set and no errors=====
<i2c_write addr="0x2D" count="0" radix="16">F4</i2c_write> />

```

```
<i2c_read addr="0x2D" count="1" radix="16">00</i2c_read> />

=====Clear Status Registers for AUX Request=====
<i2c_write addr="0x2D" count="1" radix="16">F4 FF</i2c_write> />

</aardvark>
```

## 1920x1080 2DP @ HBR

This example will configure the DSI86 for the following configuration:

```
REFCLK: 19.2MHz
DSI mode: Single
# of DSI Lanes: 4
DSI Clock Frequency: 422.5MHz
# of DP Lanes: 2
DP Datarate: HBR (2.7Gbps)
bpp: 24
Hactive: 1920
Vactive: 1080
HSync: 16 negative
VSync: 14 negative
HBP: 152
VBP: 19
HFP: 16
VFP: 3
```

```
<aardvark>
<configure i2c="1" spi="1" gpio="0" tpower="1" pullups="0" />
<i2c_bitrate khz="100" />

=====REFCLK 19.2MHz =====
<i2c_write addr="0x2D" count="1" radix="16">0A 02</i2c_write> />

=====Single 4 DSI lanes=====
<i2c_write addr="0x2D" count="1" radix="16">10 26</i2c_write> />

=====DSIA CLK FREQ 422.5MHz=====
<i2c_write addr="0x2D" count="1" radix="16">12 55</i2c_write> />

=====enhanced framing and ASSR=====
<i2c_write addr="0x2D" count="1" radix="16">5A 05</i2c_write> />

=====2 DP lanes no SSC=====
<i2c_write addr="0x2D" count="1" radix="16">93 20</i2c_write> />

=====HBR=====
<i2c_write addr="0x2D" count="1" radix="16">94 80</i2c_write> />

=====PLL ENABLE=====
<i2c_write addr="0x2D" count="1" radix="16">0D 01</i2c_write> <sleep ms="10" />
```

```

=====Verify PLL is locked=====
<i2c_write addr="0x2D" count="0" radix="16">0A</i2c_write> />
<i2c_read addr="0x2D" count="2" radix="16">00</i2c_read> <sleep ms="10" />

=====POST-Cursor2 0dB =====
<i2c_write addr="0x2D" count="1" radix="16">95 00</i2c_write> />

=====Write DPCD Register 0x0010A in Sink to Enable ASSR=====
<i2c_write addr="0x2D" count="1" radix="16">64 01</i2c_write> />
<i2c_write addr="0x2D" count="1" radix="16">74 00</i2c_write> />
<i2c_write addr="0x2D" count="1" radix="16">75 01</i2c_write> />
<i2c_write addr="0x2D" count="1" radix="16">76 0A</i2c_write> />
<i2c_write addr="0x2D" count="1" radix="16">77 01</i2c_write> />
<i2c_write addr="0x2D" count="1" radix="16">78 81</i2c_write> <sleep ms="10" />

=====Semi-Auto TRAIN =====
<i2c_write addr="0x2D" count="1" radix="16">96 0A</i2c_write> <sleep ms="20" />

=====Verify Training was successful=====
<i2c_write addr="0x2D" count="0" radix="16">96</i2c_write> />
<i2c_read addr="0x2D" count="1" radix="16">00</i2c_read> <sleep ms="10" />

=====CHA_ACTIVE_LINE_LENGTH is 1920 =====
<i2c_write addr="0x2D" count="2" radix="16">20 80 07</i2c_write> />

=====CHA_VERTICAL_DISPLAY_SIZE is 1080 =====
<i2c_write addr="0x2D" count="2" radix="16">24 38 04</i2c_write> />

=====CHA_HSYNC_PULSE_WIDTH is 16 negative =====
<i2c_write addr="0x2D" count="2" radix="16">2C 10 80</i2c_write> />

=====CHA_VSYNC_PULSE_WIDTH is 14 negative=====
<i2c_write addr="0x2D" count="2" radix="16">30 0E 80</i2c_write> />

=====CHA_HORIZONTAL_BACK_PORCH is 152=====
<i2c_write addr="0x2D" count="1" radix="16">34 98</i2c_write> />

=====CHA_VERTICAL_BACK_PORCH is 19=====
<i2c_write addr="0x2D" count="1" radix="16">36 13</i2c_write> />

=====CHA_HORIZONTAL_FRONT_PORCH is 16=====
<i2c_write addr="0x2D" count="1" radix="16">38 10</i2c_write> />

=====CHA_VERTICAL_FRONT_PORCH is 3=====
<i2c_write addr="0x2D" count="1" radix="16">3A 03</i2c_write> />

=====DP- 24bpp=====
<i2c_write addr="0x2D" count="1" radix="16">5B 00</i2c_write> />

=====COLOR BAR disabled=====
<i2c_write addr="0x2D" count="1" radix="16">3C 00</i2c_write> />

=====enhanced framing, ASSR, and Vstream enable=====

```

```
<i2c_write addr="0x2D" count="1" radix="16">5A 0D</i2c_write> />

</aardvark>
```

## 2560x1440 2DP @ HBR2

This example will configure the DSI86 for the following configuration:

```
REFCLK: 19.2MHz
DSI mode: Dual Odd/Even
# of DSI Lanes: 8
DSI Clock Frequency: 362.5MHz
# of DP Lanes: 2
DP Datarate: HBR2 (5.4Gbps)
bpp: 24
Hactive: 2560
Vactive: 1440
HSync: 32 positive
VSync: 5 negative
HBP: 80
VBP: 33
HFP: 48
VFP: 3
```

```
<aardvark>
<configure i2c="1" spi="1" gpio="0" tpower="1" pullups="0" />
<i2c_bitrate khz="100" />

=====REFCLK 19.2MHz=====
<i2c_write addr="0x2D" count="1" radix="16">0A 02</i2c_write> />

=====Dual Odd/Even 4 DSI lanes=====
<i2c_write addr="0x2D" count="1" radix="16">10 00</i2c_write> />

=====DSI CLK FREQ 362.5MHz=====
<i2c_write addr="0x2D" count="1" radix="16">12 48</i2c_write> />
<i2c_write addr="0x2D" count="1" radix="16">13 48</i2c_write> />

=====enhanced framing and ASSR=====
<i2c_write addr="0x2D" count="1" radix="16">5A 05</i2c_write> />

=====2 DP lanes and no SSC=====
<i2c_write addr="0x2D" count="1" radix="16">93 20</i2c_write> />

=====HBR2=====
<i2c_write addr="0x2D" count="1" radix="16">94 E0</i2c_write> />

=====PLL ENABLE=====
<i2c_write addr="0x2D" count="1" radix="16">0D 01</i2c_write> <sleep ms="10" />

=====Verify PLL is locked=====
<i2c_write addr="0x2D" count="0" radix="16">0A</i2c_write> />
```

```

<i2c_read addr="0x2D" count="2" radix="16">00</i2c_read> <sleep ms="10" />

=====POST-Cursor2 0dB =====
<i2c_write addr="0x2D" count="1" radix="16">95 00</i2c_write> />

=====Write DPCD Register 0x0010A in Sink to Enable ASSR=====
<i2c_write addr="0x2D" count="1" radix="16">64 01</i2c_write> />
<i2c_write addr="0x2D" count="1" radix="16">74 00</i2c_write> />
<i2c_write addr="0x2D" count="1" radix="16">75 01</i2c_write> />
<i2c_write addr="0x2D" count="1" radix="16">76 0A</i2c_write> />
<i2c_write addr="0x2D" count="1" radix="16">77 01</i2c_write> />
<i2c_write addr="0x2D" count="1" radix="16">78 81</i2c_write> <sleep ms="10" />

=====Semi-Auto TRAIN =====
<i2c_write addr="0x2D" count="1" radix="16">96 0A</i2c_write> <sleep ms="20" />

=====Verify Training is successful=====
<i2c_write addr="0x2D" count="0" radix="16">96</i2c_write> />
<i2c_read addr="0x2D" count="1" radix="16">00</i2c_read> <sleep ms="10" />

=====CHA_ACTIVE_LINE_LENGTH is 1280=====
<i2c_write addr="0x2D" count="2" radix="16">20 00 05</i2c_write> />

=====CHB_ACTIVE_LINE_LENGTH is 1280=====
<i2c_write addr="0x2D" count="2" radix="16">22 00 05</i2c_write> />

=====CHA_VERTICAL_DISPLAY_SIZE is 1440=====
<i2c_write addr="0x2D" count="2" radix="16">24 A0 05</i2c_write> />

=====CHA_HSYNC_PULSE_WIDTH is 32 positive=====
<i2c_write addr="0x2D" count="2" radix="16">2C 20 00</i2c_write> />

=====CHA_VSYNC_PULSE_WIDTH is 5 negative=====
<i2c_write addr="0x2D" count="2" radix="16">30 05 80</i2c_write> />

=====CHA_HORIZONTAL_BACK_PORCH is 80=====
<i2c_write addr="0x2D" count="1" radix="16">34 50</i2c_write> />

=====CHA_VERTICAL_BACK_PORCH is 33=====
<i2c_write addr="0x2D" count="1" radix="16">36 21</i2c_write> />

=====CHA_HORIZONTAL_FRONT_PORCH is 48=====
<i2c_write addr="0x2D" count="1" radix="16">38 30</i2c_write> />

=====CHA_VERTICAL_FRONT_PORCH is 3=====
<i2c_write addr="0x2D" count="1" radix="16">3A 03</i2c_write> />

=====DP-24BPP Enable=====
<i2c_write addr="0x2D" count="1" radix="16">5B 00</i2c_write> />

=====COLOR BAR disabled=====
<i2c_write addr="0x2D" count="1" radix="16">3C 00</i2c_write> />

=====enhanced framing, ASSR, and Vstream enable=====

```

```
<i2c_write addr="0x2D" count="1" radix="16">5A 0D</i2c_write> />
```

```
</aardvark>
```

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