





SN75ALS181

SLLS152E - DECEMBER 1992 - REVISED OCTOBER 2022

SN75ALS181 Differential Driver and Receiver Pair

1 Features

- Meets TIA/EIA-422-B, TIA/EIA-485-A, and CCITT recommendations V.11 and X.27
- Low supply-current requirements... 30 mA max
- Driver output capacity...±60 mA
- Thermal shutdown protection
- Driver common-mode output voltage range of -7 V to 12 V
- Receiver input impedance: $12 \text{ k}\Omega$ min
- Receiver input sensitivity: ±200 mV
- Receiver input hysteresis: 60 mV typ
- Receiver common-mode input voltage range of ±12 V
- Operates from single 5-V supply
- Glitch-free power-up and power-down protection

2 Description

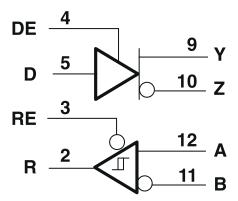
The SN75ALS181 is a differential driver and receiver pair designed for bidirectional data communication on multipoint bus transmission lines. The design provides for balanced transmission lines and meets TIA/EIA-422-B and TIA/EIA-485-A, and CCITT recommendations V.10, V.11, X.26, and X.27.

The SN75ALS181 combines a 3-state differential line driver and a differential-input line receiver that operate from a single 5-V power supply. The driver and receiver have active-high and active-low enables, respectively, that can be connected together externally to function as a direction control. The driver differential outputs and the receiver differential inputs are connected to separate pins for greater flexibility and are designed to offer minimum loading to the bus when the driver is disabled or V_{CC} = 0. These ports feature wide positive and negative common-mode voltage changes, making the device suitable for partyline applications.

Device Information

PART NUMB	ER	PACKAGE ⁽¹⁾	BODY SIZE (NOM)		
SN75ALS18		N (PDIP) 14-pins	19.3 mm x 6.35 mm		
SINTUALS TO		NS (SO) 14-pins	10.3 mm x 5.3 mm		

For all available packages, see the orderable addendum at the end of the data sheet.



Logic Diagram (Positive Logic)



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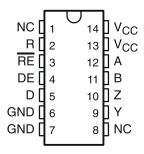
3 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision D (August 2013) to Revision E (October 2022)	Page
Added the Pin Configuration and Functions	3
• Deleted the Package thermal impedance from the Absolute Maximum Ratings	
Added the Thermal Information table	
Added the Detailed Description section	10
Changes from Revision C (May 2010) to Revision D (August 2013)	Page
 Fixed typographical error in MAX value for Δ V_{OD} . 	5
r into a typographical error in this by value for Δr r r r r r r r r r	
• Fixed typographical error in UNITS for $\Delta V_{OC} $	
	5



4 Pin Configuration and Functions



N.C. - No internal connection

Figure 4-1. N OR NS Package (Top View)

Table 4-1. Pin Functions

Table 4 1.1 III allocations					
PIN		TYPE	DESCRIPTION		
NAME	NO.	ITPE	DESCRIPTION		
NC	1, 8	No Connect	Not electrically connected		
R	2	Digital Output	Logic output RS485 data		
RE	3	Digital Input	Receiver enable, active low		
DE	4	Digital Input	Driver enable, active high		
D	5	Digital Input	Driver data input		
GND	6, 7	Ground	Device ground		
Υ	9	Bus Output	Bus Output Y (Complementary to Z)		
Z	10	Bus Output	Bus Output Z (Complementary to Y)		
В	11	Bus Input	Bus Input B (Complementary to A)		
A	12	Bus Input	Bus Input A (Complementary to B)		
V _{CC}	13, 14	Power	5 V Supply		



5 Specifications

5.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted) see (1)

			MIN	MAX	UNIT
V _{CC}	Supply voltage range ⁽²⁾			7	V
	Input voltage range	D, DE, and RE inputs		7	V
	Output voltage range	Driver	-9	14	V
	Input voltage range	Receiver	-14	14	V
	Receiver differential input voltage range ⁽³⁾	·	-14	14	V
	Lead temperature 1,6 mm (1/16 inch) from case for 10 seconds			260	°C
T _{stg}	Storage temperature range		-65	150	°C

⁽¹⁾ Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

5.2 Thermal Information

	THERMAL METRIC(1)	N (PDIP)	NS (SO)	LIMIT
	THERMAL METRIC	14-Pins	14-Pins	UNIT
R _{θJA}	Junction-to-ambient thermal resistance	54.2	88.6	°C/W
R _{θJB}	Junction-to-board thermal resistance	41.6	49.12	°C/W
Ψ ЈТ	Junction-to-top characterization parameter	34.0	14.17	°C/W
Ψ ЈВ	Junction-to-board characterization parameter	21.1	48.6	°C/W
R _{θJC(bot)}	Junction-to-case (bottom) thermal resistance	N/A	N/A	°C/W

⁽¹⁾ For more information about traditional and new thermal metrics, see the Semiconductor and IC package thermal metrics application report.

5.3 Recommended Operating Conditions

			MIN	NOM	MAX	UNIT
V _{CC}	Supply voltage		4.75	5	5.25	V
V _{OC}	Common-mode output voltage(1)	Driver	-7		12	V
V _{IC}	Common-mode input voltage ⁽¹⁾	Receiver	-12		12	V
V _{IH}	High-level input voltage	D, DE, and RE	2			V
V _{IL}	Low-level input voltage	D, DE, and RE			0.8	V
V_{ID}	Differential input voltage	·			±12	V
	Link lavel autout aumant	Driver			-60	mA
I _{OH}	High-level output current	Receiver			-400	μA
	Level and autorit animont	Driver			60	mA
I _{OL}	Low-level output current	Receiver			8	IIIA
T _A	Operating free-air temperature	·	0		70	°C

⁽¹⁾ The algebraic convention, where the less positive (more negative) limit is designated as minimum, is used in this table for common-mode output voltage level only.

Product Folder Links: SN75ALS181

⁽²⁾ All voltage values, except differential input voltage, are with respect to network ground terminal.

⁽³⁾ Differential input voltage is measured at the non-inverting terminal with respect to the inverting terminal.

5.4 Electrical Characteristics: Driver

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS		MIN	TYP ⁽¹⁾	MAX	UNIT
V _{IK}	Input clamp voltage	I _I = -18 mA				-1.5	V
Vo	Output voltage	I _O = 0		0		6	V
V _{OD1}	Differential output voltage	I _O = 0		1.5		6	V
		V _{CC} = 5 V ,		1/2 V _{OD1}			
V _{OD2}	Differential output voltage	R _L = 100 Ω	See Figure 6-1	2			V
		R _L = 54 Ω		1.5	2.3	5	
V _{OD3}	Differential output voltage	$V_{\text{test}} = -7 \text{ V to } 12 \text{ V},$	See Figure 6-2	1.5		5	V
$\Delta V_{OD} $	Change in magnitude of differential output voltage	R_L = 54 Ω or 100 Ω,	See Figure 6-1			±0.2	V
V _{oc}	Common mode output voltage	$R_L = 54 \Omega \text{ or } 100 \Omega,$	See Figure 6-1			3 –1	V
Δ V _{OC}	Change in magnitude of common-mode output voltage ⁽²⁾	R_L = 54 Ω or 100 Ω,	See Figure 6-1			±0.2	V
I _{OZ}	High-impedance-state output current	$V_O = -7 \text{ V to } 12 \text{ V}^{(3)}$				±100	μA
I _{IH}	High-level input current	V _{IH} = 2.4 V				20	μA
I _{IL}	Low-level input current	V _{IL} = 0.4 V				-100	μA
		V _O = -7 V				-250	
	Chart singuit autout aurout	V _O = V _{CC}				250	Л
los	Short circuit output current	V _O = 12 V				250	mA
		V _O = 0 V				-150	
	Cumply surrent (total masks as)	No load	Outputs enabled		21	30	m 1
I _{CC}	Supply current (total package)	เพอ เอลน	Outputs disabled		14	21	mA

⁽¹⁾

5.5 Switching Characteristics: Driver

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS			TYP ⁽¹⁾	MAX	UNIT
Differential output delay time, tdDH or tdDL	$R_L = 54 \Omega$,	C _L = 50 pF,	See Figure 6-3	9	13	20	ns
Pulse skew (tdDH – tdDL)	$R_L = 54 \Omega$,	C _L = 50 pF,	See Figure 6-3		1	8	ns
Differential output transition time	$R_L = 54 \Omega$,	C _L = 50 pF,	See Figure 6-3	3	10	16	ns
Output enable time to high level	$R_L = 110 \Omega$,	See Figure 6-4	4		36	53	ns
Output enable time to low level	$R_L = 110 \Omega$,	See Figure 6-5	5		39	56	ns
Output disable time from high level	$R_L = 110 \Omega$,	See Figure 6-4	4		20	31	ns
Output disable time from low level	$R_L = 110 \Omega$,	See Figure 6-	5		9	20	ns
	Differential output delay time, tdDH or tdDL Pulse skew (tdDH – tdDL) Differential output transition time Output enable time to high level Output enable time to low level Output disable time from high level	$\begin{array}{ll} \mbox{Differential output delay time, tdDH} \\ \mbox{or tdDL} \\ \mbox{Pulse skew (tdDH - tdDL)} \\ \mbox{Differential output transition time} \\ \mbox{Output enable time to high level} \\ \mbox{Output enable time to low level} \\ \mbox{Output disable time from high level} \\ \mbox{R}_L = 110 \ \Omega \ , \\ \mbox{Output disable time from high level} \\ \mbox{R}_L = 110 \ \Omega \ , \\ \mbox{Output disable time from high level} \\ \mbox{R}_L = 110 \ \Omega \ , \\ \mbox{Output disable time from high level} \\ \mbox{R}_L = 110 \ \Omega \ , \\ \mbox{Output disable time from high level} \\ \mbox{R}_L = 110 \ \Omega \ , \\ \mbox{Output disable time from high level} \\ \mbox{R}_L = 110 \ \Omega \ , \\ \mbox{Output disable time from high level} \\ \mbox{R}_L = 110 \ \Omega \ , \\ \mbox{R}_L = 110 \ \Omega \ , \\ \mbox{Output disable time from high level} \\ \mbox{R}_L = 110 \ \Omega \ , \\ \mbox{R}_L = 110 \ \Omega$	$\begin{array}{c} \text{Differential output delay time, tdDH} \\ \text{or tdDL} \\ \\ \text{Pulse skew (tdDH - tdDL)} \\ \\ \text{Differential output transition time} \\ \\ \text{Output enable time to low level} \\ \\ \text{Output disable time from high level} \\ \\ \text{R}_{L} = 54 \ \Omega \ , \\ \\ \text{R}_{L} = 54 \ \Omega \ , \\ \\ \text{C}_{L} = 50 \ \text{pF}, \\ \\ \text{C}_{L} = 110 \ \Omega \ , \\ \text{See Figure 6-4} \\ \\ \text{C}_{L} = 110 \ \Omega \ , $	Differential output delay time, tdDH or tdDL $R_L = 54~\Omega$, $C_L = 50~pF$, See Figure 6-3 Pulse skew ([tdDH – tdDL]) $R_L = 54~\Omega$, $C_L = 50~pF$, See Figure 6-3 Differential output transition time $R_L = 54~\Omega$, $C_L = 50~pF$, See Figure 6-3 Output enable time to high level $R_L = 110~\Omega$, See Figure 6-4 Output disable time from high level $R_L = 110~\Omega$, See Figure 6-5 Output disable time from high level $R_L = 110~\Omega$, See Figure 6-4	Differential output delay time, tdDH or tdDL $R_L = 54~\Omega$, $C_L = 50~pF$, See Figure 6-3 $P_L = 54~\Omega$, $C_L = 50~pF$, See Figure 6-3 $P_L = 54~\Omega$, $P_L = 50~pF$, See Figure 6-3 $P_L = 54~\Omega$, $P_L = 54~\Omega$, $P_L = 50~pF$, See Figure 6-3 $P_L = 110~\Omega$, See Figure 6-4 $P_L = 110~\Omega$, See Figure 6-5 $P_L = 110~\Omega$, See Figure 6-5 $P_L = 110~\Omega$, See Figure 6-4	Differential output delay time, tdDH or tdDL $R_L = 54 \Omega$, $C_L = 50 pF$, See Figure 6-3 9 13 Pulse skew ([tdDH - tdDL]) $R_L = 54 \Omega$, $C_L = 50 pF$, See Figure 6-3 1 Differential output transition time $R_L = 54 \Omega$, $C_L = 50 pF$, See Figure 6-3 3 10 Output enable time to high level $R_L = 110 \Omega$, See Figure 6-4 36 Output enable time to low level $R_L = 110 \Omega$, See Figure 6-5 39 Output disable time from high level $R_L = 110 \Omega$, See Figure 6-4 20	Differential output delay time, tdDH or tdDL $R_L = 54 \Omega$, $C_L = 50 pF$, See Figure 6-3 $9 13 20$ Pulse skew ([tdDH – tdDL]) $R_L = 54 \Omega$, $C_L = 50 pF$, See Figure 6-3 $1 8$ Differential output transition time $R_L = 54 \Omega$, $C_L = 50 pF$, See Figure 6-3 $1 10 16$ Output enable time to high level $R_L = 110 \Omega$, See Figure 6-4 $10 10 10 10$ Output enable time to low level $10 10 10 10 10$ Output disable time from high level $10 10 10 10 10$ See Figure 6-5 $10 10 10 10 10$ Output disable time from high level $10 10 10 10 10 10 10 10 $

(1) All typical values are at $V_{CC} = 5 \text{ V}$ and TA = 25°C.

All typical values are at V_{CC} = 5 V and TA = 25°C. $\Delta |V_{OD}|$ and $\Delta |V_{OC}|$ are the changes in magnitude of V_{OD} and V_{OC} , respectively, that occur when the input is changed from a high level (2) to a low level.

⁽³⁾ This applies for both power on and power off. Refer to TIA/EIA-485-A for exact conditions



5.6 Electrical Characteristics: Receiver

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS			MIN	TYP ⁽¹⁾	MAX	UNIT
V _{T+}	Positive-going threshold voltage, differential input	V _O = 2.7 V,	I _O = -0.4 mA				0.2	V
V _{T-}	Negative-going threshold voltage, differential input	V _O = 0.5 V,	I _O = 8 mA		-0.2			V
V _{hys}	Input hysteresis (V _{T+} – V _{T-})					60		mV
V _{IK}	Input clamp voltage, RE	I _I = -18 mA					-1.5	V
V _{OH}	High-level output voltage	V _{ID} = 200 mV,	$I_{OH} = -400 \mu A$,	See Figure 6-6	2.7			V
V _{OL}	Low-level output voltage	V _{ID} = 200 mV,	I _{OL} = 8 mA,	See Figure 6-6			0.45	V
I _{OZ}	High-impedance-state output current	V _O = 0.4 V to 2.4	V _O = 0.4 V to 2.4 V				±20	μΑ
	Line input current	Other input at 0	V _I = 12 V				1	mA
1	Line input current	V ⁽²⁾ ,	V _I = -7 V				-0.8	mA
I _{IH}	High-level input current, RE	V _{IH} = 2.7 V					20	μΑ
I _{IL}	Low-level input current, RE	V _{IL} = -7 V					-100	μΑ
R _I	Input resistance				12			kΩ
Ios	Short circuit output current	V _{ID} = 200 mV,	V _O = 0 V		-15		-85	mA
	Supply ourrent (total pookage)	No load	Outputs enabled			21	30	mΛ
Icc	Supply current (total package)	No load	Outputs disabled			14	21	mA

5.7 Switching Characteristics: Receiver

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP ⁽¹⁾	MAX	UNIT
t _{PHL}	Differential output delay time, tdDH or tdDL	V _{ID} = -1.5 V to 1.5 V	10	16	25	ns
t _{PLH}	Propagation delay time, low- to high-level output	V _{ID} = -1.5 V to 1.5 V	10	16	25	ns
t _{sk(p)}	Pulse skew (tdDH – tdDL)	V _{ID} = -1.5 V to 1.5 V		1	8	ns
t _{PZH}	Output enable time to high level			7	15	ns
t _{PZL}	Output enable time to low level			9	19	ns
t _{PHZ}	Output disable time from high level			18	27	ns
t _{PLZ}	Output disable time from low level			10	15	ns

All typical values are at V_{CC} = 5 V and TA = 25°C.

All typical values are at V_{CC} = 5 V and TA = 25°C. This applies for both power on and power off. Refer to TIA/EIA-485-A for exact conditions

Parameter Measurement Information

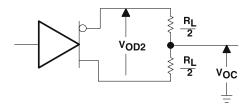


Figure 6-1. Driver Test Circuit, V_{OD} and V_{OC}

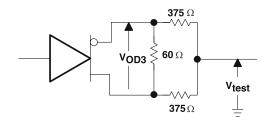
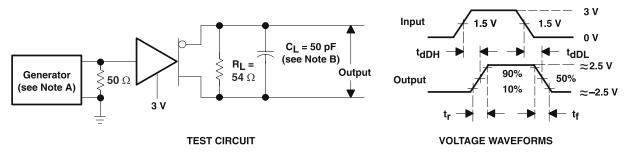
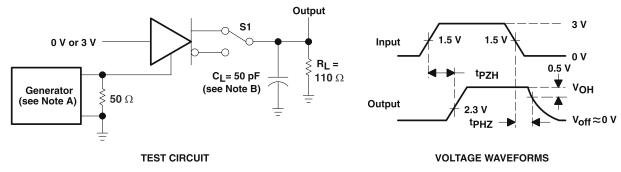


Figure 6-2. Driver Circuit, V_{OD3}



- A. The input pulse is supplied by a generator having the following characteristics: PRR \leq 1 MHz, 50% duty cycle, $t_r \leq$ 6 ns, $t_f \leq$ 6 ns, $Z_O =$ 50 Ω
- B. C_L includes probe and jig capacitance.

Figure 6-3. Driver Differential-Output Delay and Transition Times



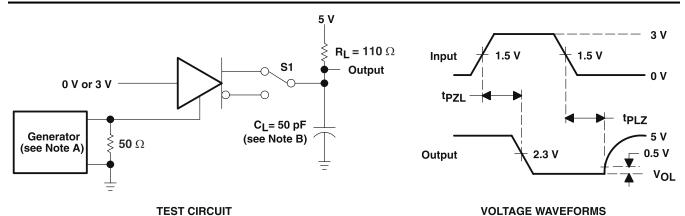
- A. The input pulse is supplied by a generator having the following characteristics: PRR \leq 1 MHz, 50% duty cycle, $t_r \leq$ 6 ns, $t_f \leq$ 6 ns, $Z_O =$ 50 Ω
- B. C_L includes probe and jig capacitance.

Figure 6-4. Driver Enable and Disable Times

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- A. The input pulse is supplied by a generator having the following characteristics: PRR ≤ 1 MHz, 50% duty cycle, t_r ≤ 6 ns, t_f ≤ 6 ns, Z_O = 50 Ω
- B. C_L includes probe and jig capacitance.

Figure 6-5. Driver Enable and Disable Times

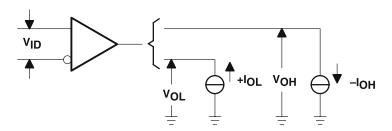
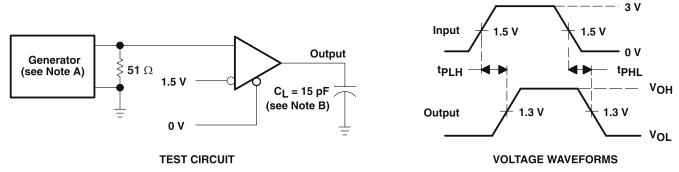
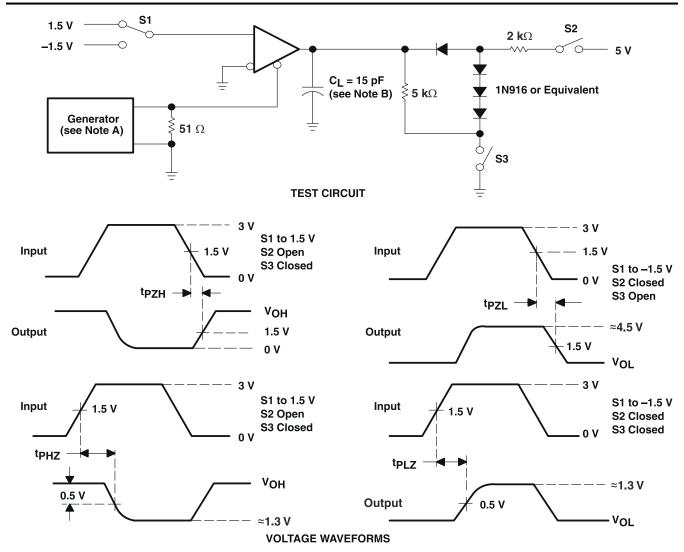


Figure 6-6. Receiver, V_{OH} and V_{OL}



- A. The input pulse is supplied by a generator having the following characteristics: PRR ≤ 1 MHz, 50% duty cycle, t_r ≤ 6 ns, t_f ≤ 6 ns, Z_O = 50 Ω
- B. C_L includes probe and jig capacitance.

Figure 6-7. Receiver Propagation-Delay Times



- A. The input pulse is supplied by a generator having the following characteristics: PRR \leq 1 MHz, 50% duty cycle, $t_r \leq$ 6 ns, $t_f \leq$ 6 ns, $Z_O =$ 50 Ω
- B. C_L includes probe and jig capacitance.

Figure 6-8. Receiver Output Enable and Disable Times



6 Detailed Description

6.1 Device Functional Modes

6.1.1 Function Tables

Each Driver

INPUTS		OUTPUTS	
D	DE	Υ	Z
Н	Н	Н	L
L	Н	L	Н
X	L	Z	Z

Each Receiver(1)

DIFFERENTIAL A-B	ENABLE RE	OUTPUT R
V _{ID} ≥ 0.2 V	L	Н
$-0.2 \text{ V} < \text{V}_{\text{ID}} < 0.2 \text{ V}$	L	?
V _{ID} ≤ -0.2 V	L	L
X	н	Z

(1) H = high level, L = low level, ? = indeterminate, X = irrelevant, Z = high impedance (off)

6.1.2 Schematics

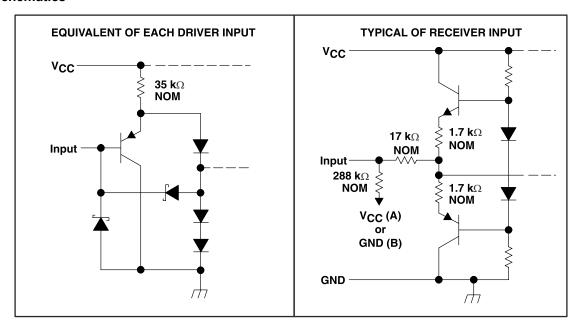


Figure 6-1. SCHEMATICS OF INPUTS

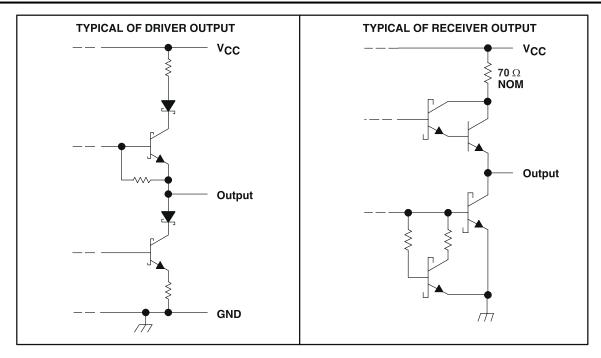


Figure 6-2. SCHEMATICS OF OUTPUTS



7 Device and Documentation Support

TI offers an extensive line of development tools. Tools and software to evaluate the performance of the device, generate code, and develop solutions are listed below.

7.1 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Subscribe to updates* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

7.2 Support Resources

TI E2E[™] support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

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7.3 Trademarks

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7.4 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

7.5 Glossary

TI Glossary

This glossary lists and explains terms, acronyms, and definitions.

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