A Simple Pressure Sensor Signal Conditioning Circuit

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INTRODUCTION

A simple signal conditioning circuit should allow the output of the amplifier to be independent of the sensor used, providing interchangeability and high level output at very low cost. A laser trimmed resistor on the sensor's compensation board programs the gain of an external amplifier to normalize the pressure sensitivity variation.

SIMPLE SIGNAL CONDITIONING CIRCUIT

The signal conditioning circuit shown in Figure 1 provides a precision constant current source for sensor excitation and an instrumentation amplifier with the gain programmed by sensor feedback resistor r.

For a detailed discussion of the compensation circuit, and for output voltages other than 0-5V, please refer to Application Notes TN-001 and APP-103 to APP-105.
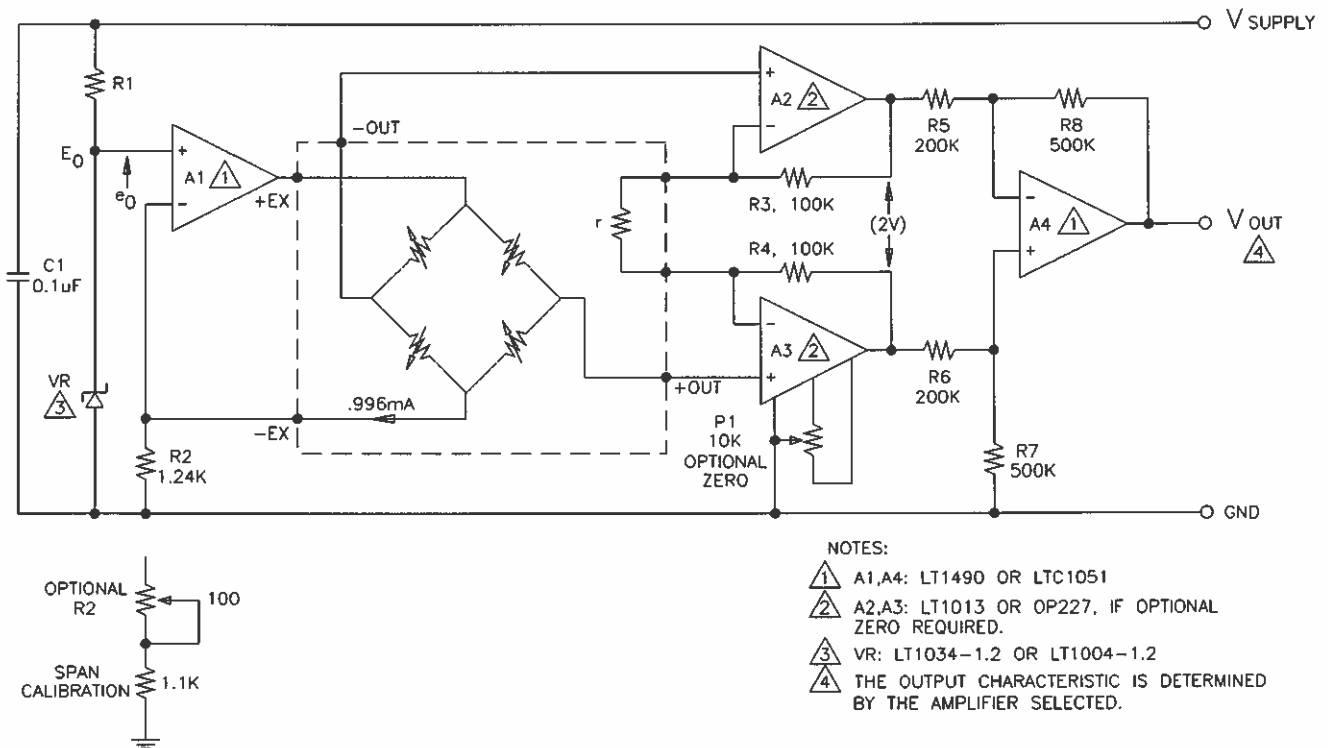

NOTES:
1. A1,A4: LT1490 OR LTC1051
2. A2,A3: LT1013 OR OP227, IF OPTIONAL ZERO REQUIRED.
3. VR: LT1034-1.2 OR LT1004-1.2
4. THE OUTPUT CHARACTERISTIC IS DETERMINED BY THE AMPLIFIER SELECTED.

Figure 1. Basic Signal Conditioning Circuit

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CIRCUIT DETAILS

The current source is controlled by the ±1% band-gap reference diode, VR. The reference current IO is defined by:

$$I_O = (E_O - e_O)/R_2 \qquad [1]$$

where: EO - diode reference voltage: 1.235V ±1%
(LT1034-1.2 or LT1004-1.2)
e_O - offset of amplifier A_1 (~0)
R_2 - current set resistor

Selecting amplifier A_1 with an offset voltage below 1 mV and a ±1% tolerance of resister R_2 delivers current $I_O = 0.996$ mA with typical accuracy of ±1.4%.

The differential input stage of the instrumentation amplifier, A_3-A_2 has a gain of Gain=1+(R_3+R_4)/r.

The gain set resistor r is trimmed for R_3=R_4=100K and a differential output voltage of 2V.

OPTIONAL ZERO ADJUST

If the optional zero adjustment is required, use OP227 amplifiers instead of the LT1013 and add the zeroing potentiometer P1.

The zero range is typically ±4 mV referenced to the input with a differential offset below 0.5 mV. This leaves about a ±3.5 mV zeroing range for the compensation of the sensor offset which is typically below ±1 mV.

OUTPUT

The output stage of the instrumentation amplifier provides additional amplification R8/R5 and translates the differential floating voltage from the first stage into a single ended output voltage. The equation for the overall output voltage is:

$$V_{out} = 2 \cdot A \cdot R_8 / R_5 = 5.000V @ A = 1 \qquad [3]$$

A is the Ratio between the actual excitation current I_O and the specified current.

ACCURACY AND CALIBRATION

The overall accuracy of the span is effected by the accuracy of feedback resisters R_3 through R_8. Using ±1% resistors such as Mepco/Electra 5063Z, the typical gain error will be about ±0.24%. The accuracy error may be decreased when matched thin film resisters are used such as Beckman 694-3-A. The combined span error of the entire signal conditioning circuit at a reference temperature will then typically be about 1.1% without any adjustment or pressure testing. This will be superimposed on the sensor's accuracy of ±1%.

OPTIONAL SPAN CALIBRATION

If additional calibration and normalization is desired, resister R_2 can be replaced with a series combination of a potentiometer and a resistor (Figure 1). The potentiometer can be adjusted to set the bridge excitation current (I) to achieve the exact span voltage (S) with full scale pressure applied to the sensor.

GAIN ERROR

If no pressure source is available, the gain error of the amplifier can be reduced by using the procedure outlined below. This method may be used instead of using the precision resistors discussed above for R_2 through R_8. The sensor span error of ±1% will remain, however.

Calibration procedure:
- replace resistor r with an external resistor 7.50 K ± 0.1%
- check gain K of the instrumentation amplifier and calculate the gain ratio X (in reference to the idea that gain KO = 69.028V/V), where X = K/KO
- set current IO = 0.996/X(mA) by adjusting the potentiometer, thus completing calibration.

Assuming a 6.4 kΩ (50°C) maximum bridge resistance, a 0.996 mA bridge current and a 1.2V diode reference voltage, it follows that the maximum output voltage of amplifier A1 can approach 7.4V. Also, the positive saturation voltage at 1 mA out-put current for the LTC1051 amplifier is 0.5V. Therefore, the minimum excitation voltage which is a function of the current source and amplifiers used would be 7.9V (7.4V + 0.5V) for the LTC1051. For the LT1490, the minimum excitation voltage should be 7.6V. The maximum excitation voltage is limited by the voltage handling characteristics of the specific amplifier used.

Application Notes

OUTPUT SPAN S_0 VARIATION

Resistor r is laser trimmed for each unit using the following equation:

$$r = \frac{2R_F}{\frac{V_{amp}}{S_i} - 1} \quad [4]$$

where: S_i = sensor span value (V) at a reference
excitation current (I_O = 0.996 mA)
r = resistance in (k)
R_F = 100K feedback resistor
V_{amp} = amplified output

The output span S_O at the differential output of amplifiers A_3- A_2 (see Figure 1) for any other feedback resistor R in KΩ is given by:

$$S_O = AS\left(\frac{r+2R}{r}\right) = 2A\left[\frac{R}{100} + S_i\frac{(100-R)}{200}\right] \quad [5]$$

where: $A = I/I_O$, ratio of excitation current
I to reference current I_O

If 100 kΩ feedback resistors are used, the expression for output span is simplified to:

$$S_c = 2A \quad [6]$$

and is constant for all sensors independent of sensor span S_i. The output span is also independent of the pressure range of the sensor. For other values of the feedback resistors (R), the output span (S_O) will vary with the sensor span (S_i). Assuming $I = I_O$, we can calculate S_O variations.

Table 1. Output Span (S_0) Variation

R	SO(Si=40 mV)	SO(Si=90 mV)	SO variation (±%)
50 K	1.0200	1.0450	1.23
75 K	1.5100	1.5225	0.41
99 K	1.9804	1.9809	0.01
100 K	2.0000	2.0000	0.00
101 K	2.0196	2.0191	0.01
200 K	3.9600	3.9100	0.63
500 K	9.8400	9.6400	1.0

As seen in Table 1, a large deviation from the optimum feedback resistance of 100 k is tolerable while maintaining transducer interchangeability.

For the optimum feedback resistance (100 k), calibration accuracy is a function of the accuracy of the excitation current, feedback resistors and sensor trimming. The inaccuracy caused by the excitation current and feedback resistors can be made negligible by the use of precision components. Therefore without pressure testing, a 1% system accuracy can be achieved.

The standard gain programming resistor r has a TCR ≤ ±50 ppm/°C and a trimming range of 2.5 to 12.5 k.Ω For volume orders, a custom trimming algorithm can be made to achieve any desired output span.