

PGA309 Transfer function

Below is the mathematical expression used to compute the output voltage. This equation can be algebraically re-arranged to solve for different terms. For example, during calibration this equation is re-arranged to solve for V_{in} .

$$V_{out} = \left[(\text{mux_sign} \cdot V_{in} + V_{\text{coarse_offset}}) \cdot G_I + V_{\text{zero_dac}} \right] \cdot G_D \cdot G_O$$

mux_sign -- This term changes the polarity of the input signal. The value is +/-1. See table 7.28

V_{in} -- The input signal for the PGA309 ($V_{in1} = V_{inp}$, and $V_{in2} = V_{inn}$)
See table 7.28.

$V_{\text{coarse_offset}}$ -- Coarse offset DAC output voltage. See table 6.9.

G_I -- Input stage gain. See table 7.29.

$V_{\text{zero_dac}}$ -- Zero DAC output voltage. See table 7.30

G_D -- Gain DAC. See table 7.25

G_O -- Output Stage Gain. See Table 7.27

$$V_{in} = \frac{V_{out} - G_D \cdot G_O \cdot (V_{\text{zero_dac}} + G_I \cdot V_{\text{coarse_offset}})}{G_D \cdot G_I \cdot G_O \cdot \text{mux_sign}}$$

$$V_{\text{zero_dac}} = \frac{V_{out} - G_D \cdot G_I \cdot G_O \cdot (V_{\text{coarse_offset}} + V_{in} \cdot \text{mux_sign})}{G_D \cdot G_O}$$

$$V_{\text{coarse_offset}} = \frac{V_{out} - G_D \cdot G_O \cdot (V_{\text{zero_dac}} + G_I \cdot V_{in} \cdot \text{mux_sign})}{G_D \cdot G_I \cdot G_O}$$

$$\text{Total_Gain} = G_I \cdot G_D \cdot G_O$$

$$\text{Total_Gain} = \frac{V_{out_max} - V_{out_min}}{V_{in_max} - V_{in_min}}$$

Calibration Algorithm

1. For minimum pressure. Apply low gain and offset control to set V_{out} to $1/2 V_s$.

$$GI := 4 \quad GD := \frac{1 + .3333}{2} = 0.667 \quad GO := 2 \quad V_{coarse_offset} := 0$$

$$V_{out} = [(mux_sign \cdot V_{in} + V_{coarse_offset}) \cdot GI + V_{zero_dac}] \cdot GD \cdot GO$$

$$\frac{5}{2} = [(0 + 0) \cdot 4 + V_{zero_dac}] \cdot 0.667 \cdot 2$$

$$V_{zero_dac} = 1.874 \text{ Solve for Zero Dac.}$$

Back calculate V_{in} , based on V_{out} measured

$$V_{in_min} = \frac{V_{out} - GD \cdot GO \cdot (V_{zero_dac} + GI \cdot V_{coarse_offset})}{GD \cdot GI \cdot GO \cdot mux_sign}$$

2. Adjust gain according to the if-then relationship below and re-do step 1. This will get a more accurate value for V_{in} .

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if (Vin > 0.131)
    Front_Gain = 4;
else if ((Vin > 0.035) && (Vin <= 0.131))
    Front_Gain = 8;
else if ((Vin > 0.023) && (Vin <= 0.035))
    Front_Gain = 16;
else if ((Vin > 0.015) && (Vin <= 0.023))
    Front_Gain = 32;
else Front_Gain = 64;
```

3. Do the same procedure as in step 1 and 2 with maximum pressure.
Now we have V_{in_min} and V_{in_max} .

4. Calculate total gain.

$$\text{Total_Gain} = \frac{V_{out_max} - V_{out_min}}{V_{in_max} - V_{in_min}}$$

5. Search through all combinations of $GI \times GO \times 0.667$ to find the optimal values that is closest to the total gain

i.e. $\text{Total_Gain} \sim GI \times GO \times 0.667$

6. Solve for the value of GD to get the exact Total_Gain

$$GD = \frac{\text{Total_Gain}}{GI \cdot GO}$$

7. Solve for V_{coarse_offset} to cancel V_{in_min}

$$V_{coarse_offset} = -V_{coarse_offset}$$

8. Solve for

V_{zero_dac}

$$V_{zero_dac} = \frac{V_{out} - GD \cdot GI \cdot GO \cdot (V_{coarse_offset} + V_{in} \cdot \text{mux_sign})}{GD \cdot GO}$$

9. Now the gain and offset correction should give approximately V_{out_max} and V_{out_min} for maximum and minimum stimulus. At this point maximum pressure is applied so the output should be close to the target. However, this will not be the best accuracy. To further improve the accuracy we will do a linear correction to offset (GD, and V_{zero_dac}).

$$V_{in_max} = \frac{V_{out} - GD \cdot GO \cdot (V_{zero_dac} + GI \cdot V_{coarse_offset})}{GD \cdot GI \cdot GO \cdot mux_sign} \quad \text{improved value}$$

$$V_{zero_dac} = \frac{V_{out} - GD \cdot GI \cdot GO \cdot (V_{coarse_offset} + V_{in} \cdot mux_sign)}{GD \cdot GO} \quad \text{improved value}$$

10. Adjust pressure to minimum. Measure the output (it should be near the target). Back calculate the input. Use this information to compute the gain and zero dac.

$$V_{in_min} = \frac{V_{out} - GD \cdot GO \cdot (V_{zero_dac} + GI \cdot V_{coarse_offset})}{GD \cdot GI \cdot GO \cdot mux_sign}$$

$$Total_Gain = \frac{V_{out_max} - V_{out_min}}{V_{in_max} - V_{in_min}}$$

$$GD = \frac{Total_Gain}{GI \cdot GO}$$

$$V_{zero_dac} = \frac{V_{out} - GD \cdot GI \cdot GO \cdot (V_{coarse_offset} + V_{in} \cdot mux_sign)}{GD \cdot GO}$$

11. At this point minimum pressure is applied so the output should be close to the target. However, this will not be the best accuracy. To further improve the accuracy we will do a linear correction to offset (GD, and V_{zero_dac}).

$$V_{in_min} = \frac{V_{out} - GD \cdot GO \cdot (V_{zero_dac} + GI \cdot V_{coarse_offset})}{GD \cdot GI \cdot GO \cdot mux_sign} \quad \text{improved value}$$

$$V_{zero_dac} = \frac{V_{out} - GD \cdot GI \cdot GO \cdot (V_{coarse_offset} + V_{in} \cdot mux_sign)}{GD \cdot GO} \quad \text{improved value}$$

12. The same procedure is done at all temperatures. At each temperature the GD, and Vzero_dac are adjusted to get the ideal Vout_max and Vout min.

13. Use the GD, and Vzero_dac at each temperature to generate the look up table.

