

# Stability: Capacitance on Inverting Input

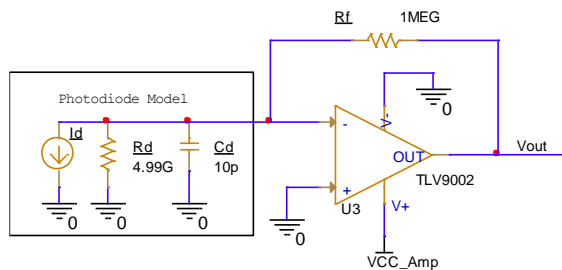
TI Precision Labs – Op Amps

Prepared by Art Kay

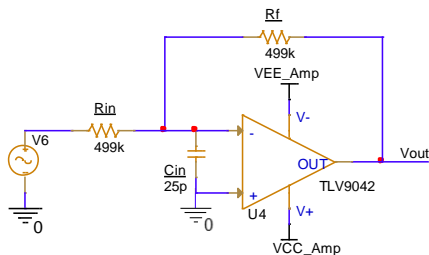
Presented by Brittany Hertneky

# Amplifiers with capacitance on inverting input

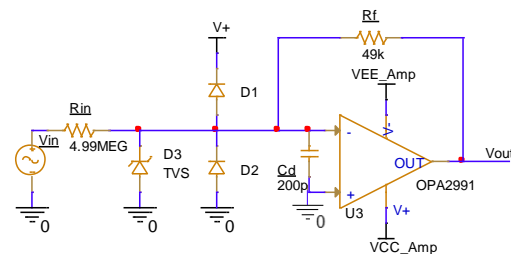
Transimpedance amplifiers



Large value resistors for low-power circuits

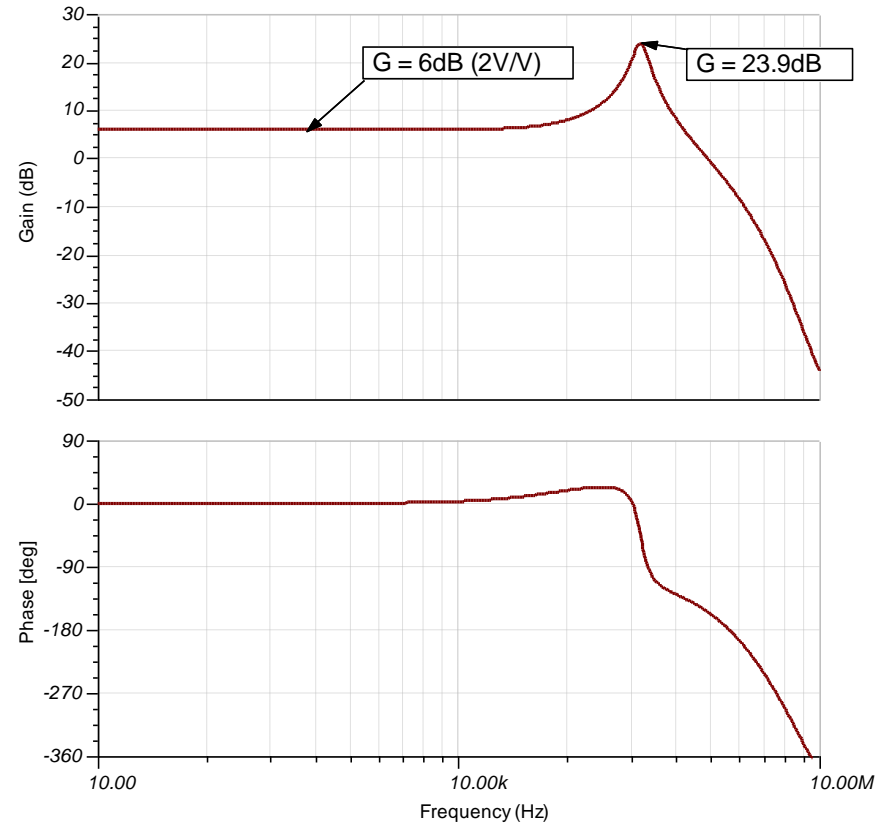
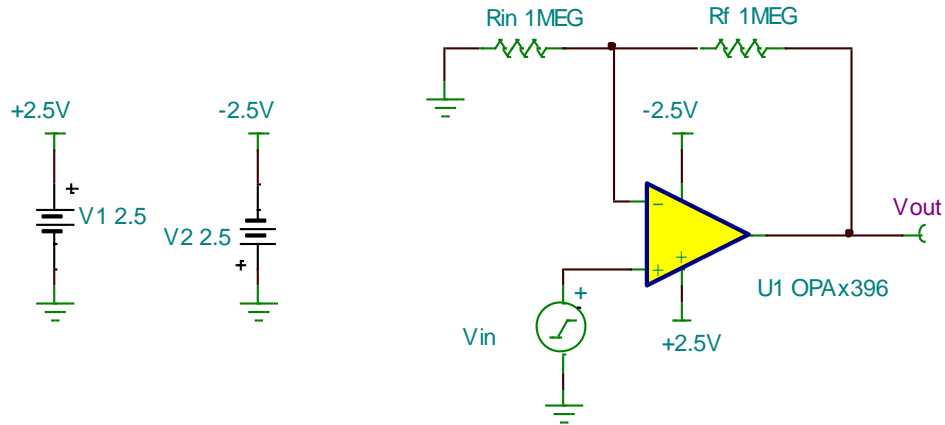


Transient suppression



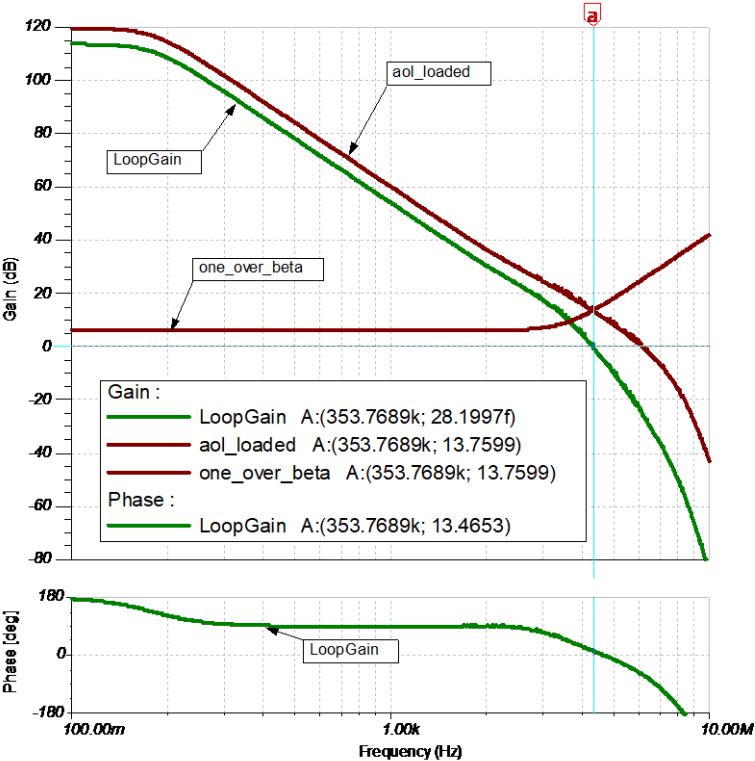
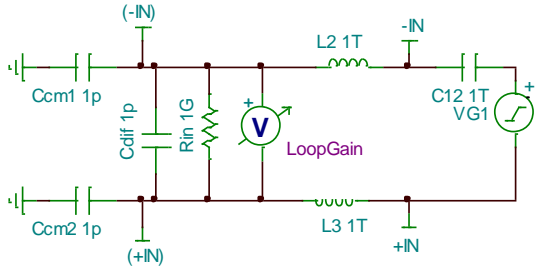
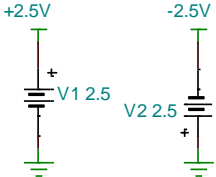
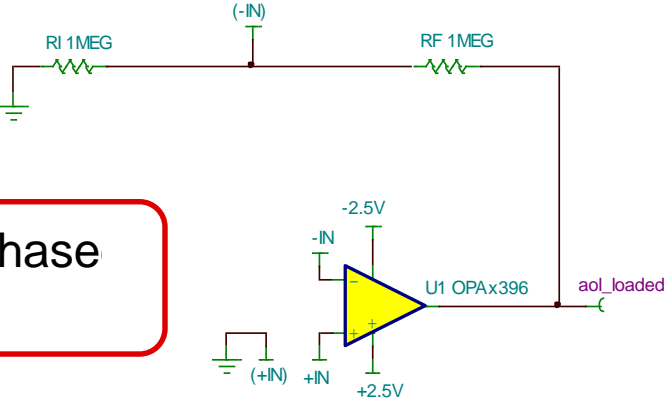
- Capacitance on inverting input interacts with feedback to cause stability problems
- Let's discuss how to solve this issue

# Amplifier with large feedback resistors

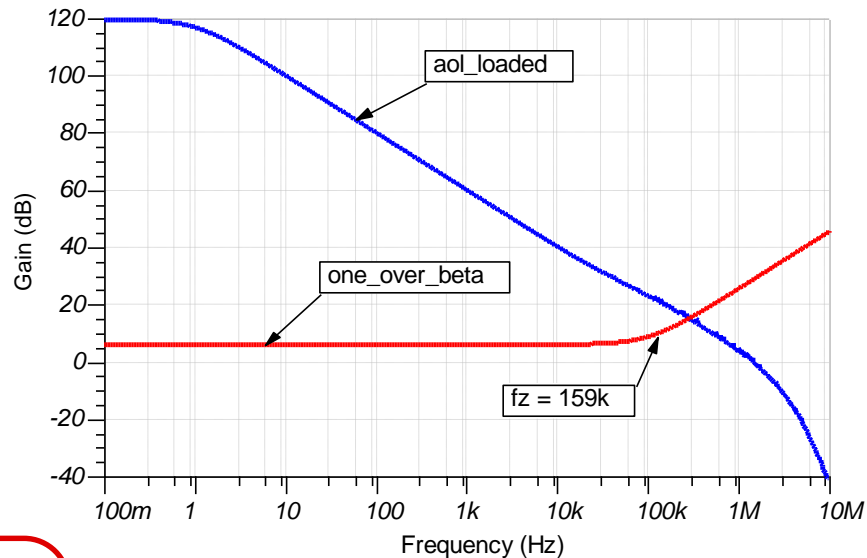
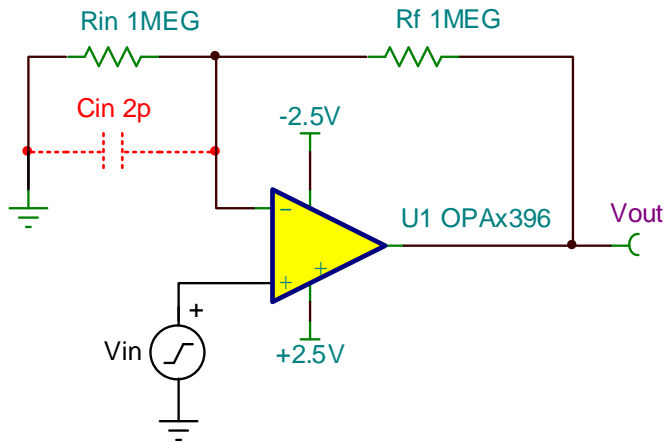


# Open loop stability test

• 14° of phase margin



# Why $1/\beta$ increases at high frequency

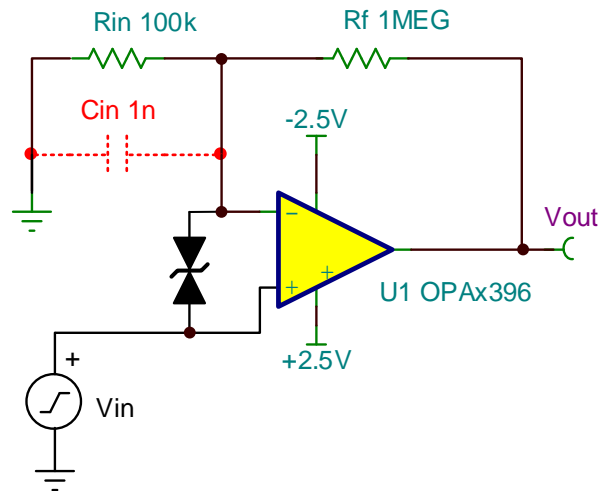


$$G = \frac{Z_f}{Z_{in}} + 1, \quad Z_{in} = R_{in} || X_{cin}, \quad X_{cin} = \frac{1}{2\pi f C_{in}}$$

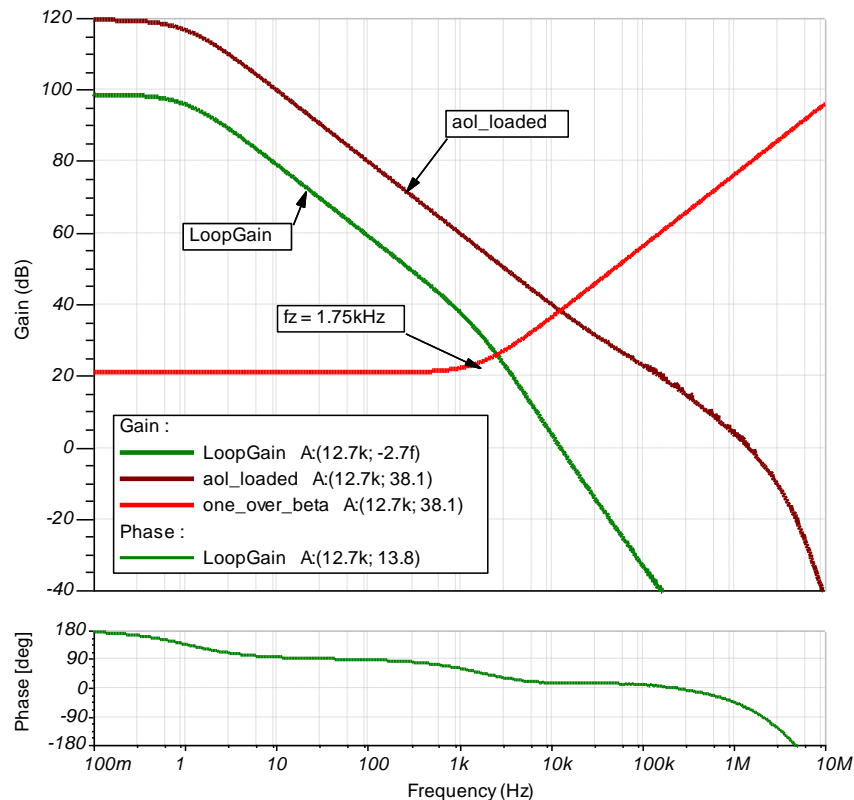
$$f_z = \frac{R_{in} + R_f}{2\pi C_{in} R_{in} R_f} = \frac{1M\Omega + 1M\Omega}{2\pi (2pF)(1M\Omega)(1M\Omega)} = 159kHz$$

$$\uparrow G = \frac{Z_f}{Z_{in}\downarrow} + 1, \text{ at high } f$$

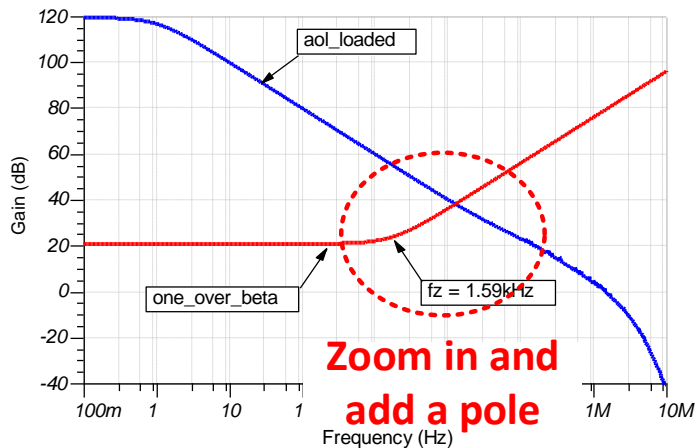
# Some components add significant capacitance



Sometimes external components included in the design add substantial capacitance. The TVS in this example adds 1nF of capacitance across  $R_{in}$ .



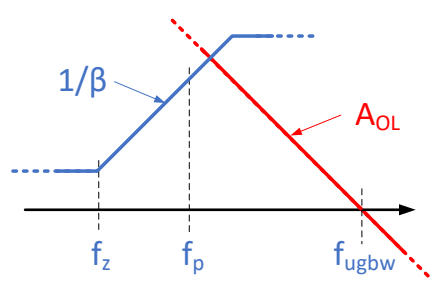
# Add a pole to cancel the zero



- The position of the pole will determine stability.
- The pole frequency must be lower than the intersection of  $1/\beta$  and  $A_{OL}$

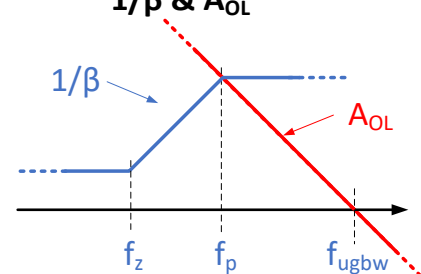
**1. Unstable!**

Pole near after  $1/\beta$  intersects  $A_{OL}$



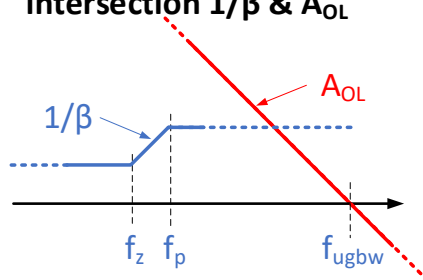
**2. Stable (minimal)**

Pole at intersection  $1/\beta$  &  $A_{OL}$



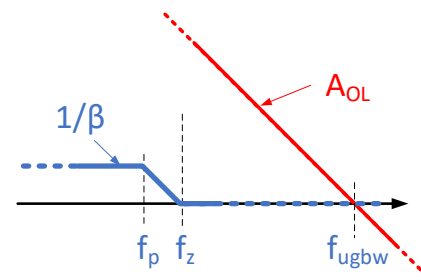
**3. Stable**

Pole before intersection  $1/\beta$  &  $A_{OL}$

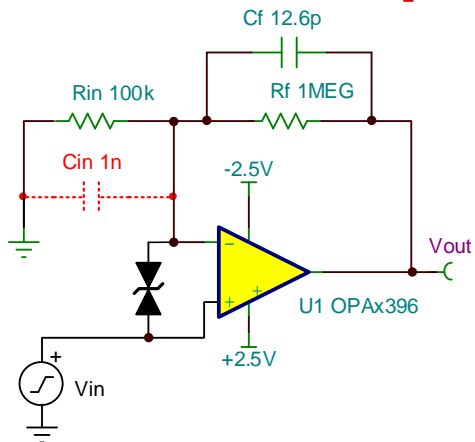


**4. Stable**

Pole before zero



# Minimum capacitance to stabilize amp

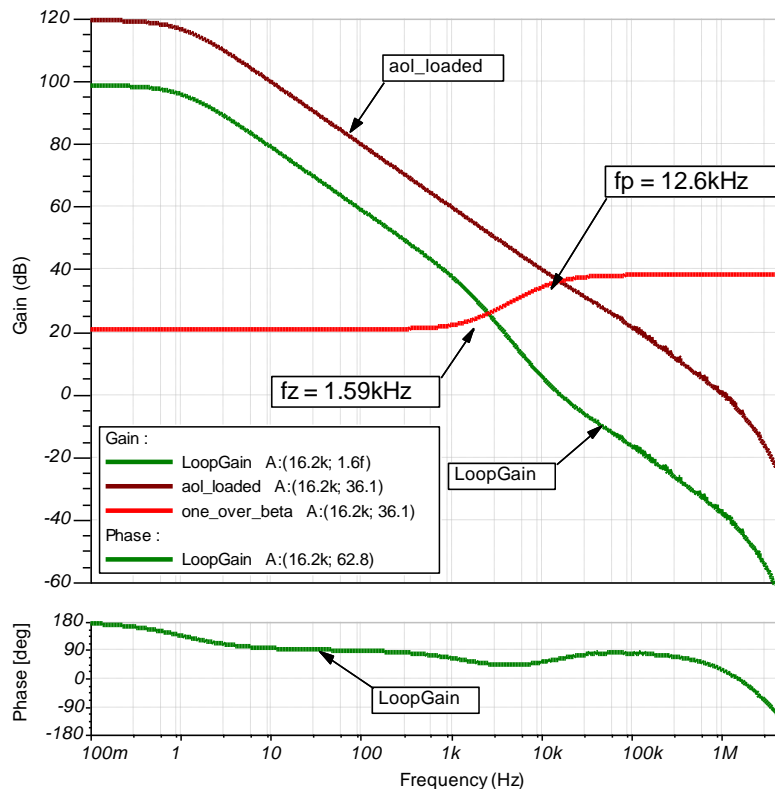


$$G = \frac{Z_f}{Z_{in}} + 1$$

Minimum feedback capacitor:

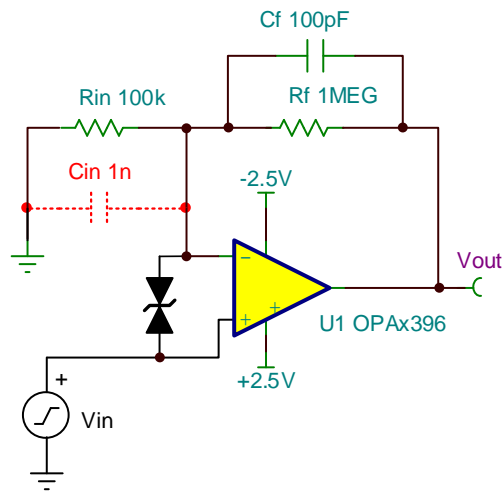
$$C_{f(min)} = \sqrt{\frac{C_{in}}{2\pi R_f f_{ugbw}}} = \sqrt{\frac{1nF}{2\pi(1M\Omega)(1MHz)}} = 12.6pF$$

$$f_p = \frac{1}{2\pi C_f R_f} = \frac{1}{2\pi(12.6pF)(1MHz)} = 12.6kHz$$





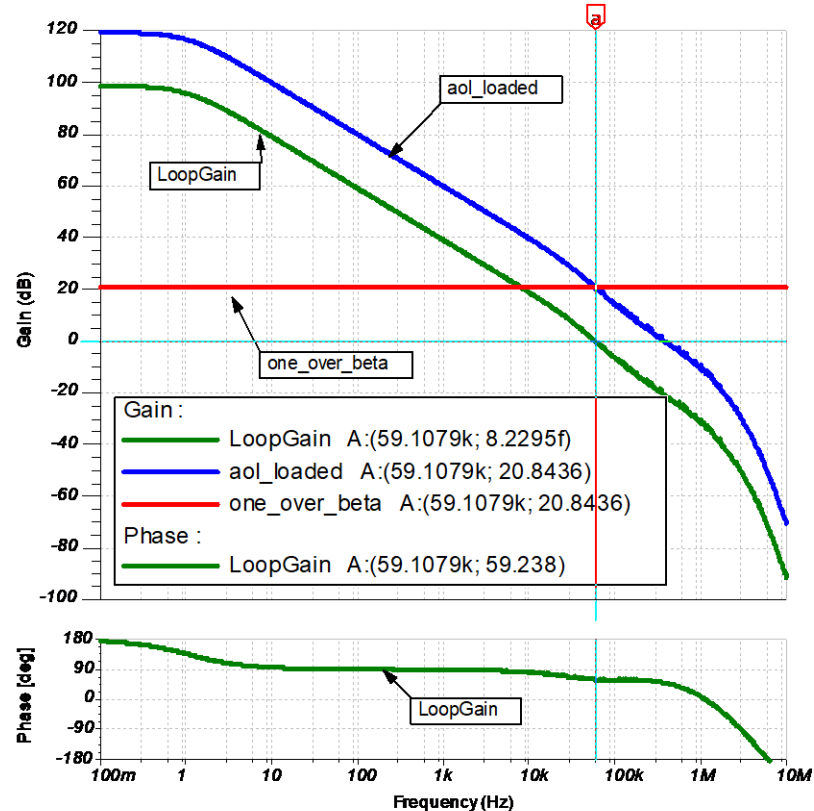
# Solving stability issues from input capacitance



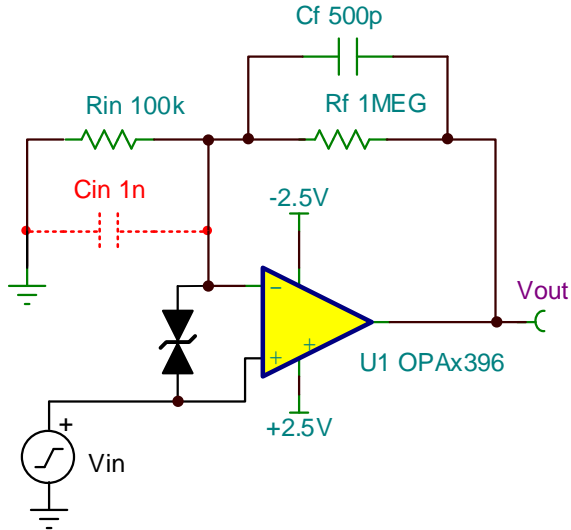
Adding a capacitance in the feedback cancels the zero caused by  $C_{in}$ .

Choose:  $R_f \times C_f = R_{in} \times C_{in}$

$$C_f = \frac{R_{in} C_{in}}{R_f} = \frac{(100k\Omega)(1nF)}{(1M\Omega)} = 100pF$$

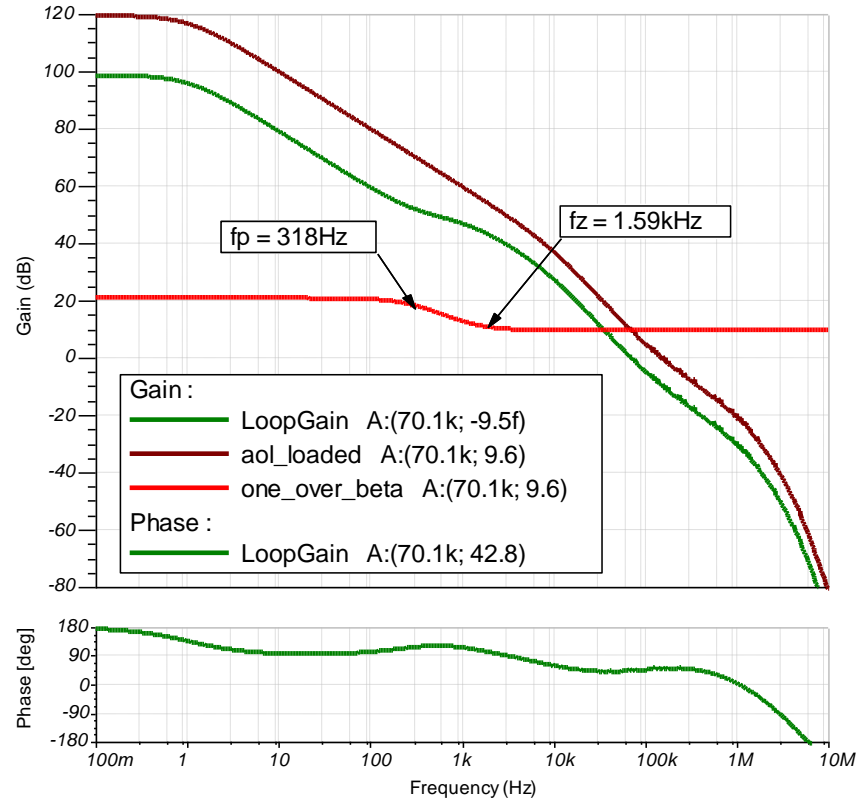


# Maximum feedback capacitance



$C_{f(\min)} = 13.2\text{pF}$ ,  $C_{f(f_p = f_z)} = 100\text{pF}$   
Choosing  $C_f > C_{f(f_p = f_z)}$  reduces  
bandwidth and noise

$$f_p(500\text{pF}) = \frac{1}{2\pi R_f C_f} = 318\text{Hz}$$

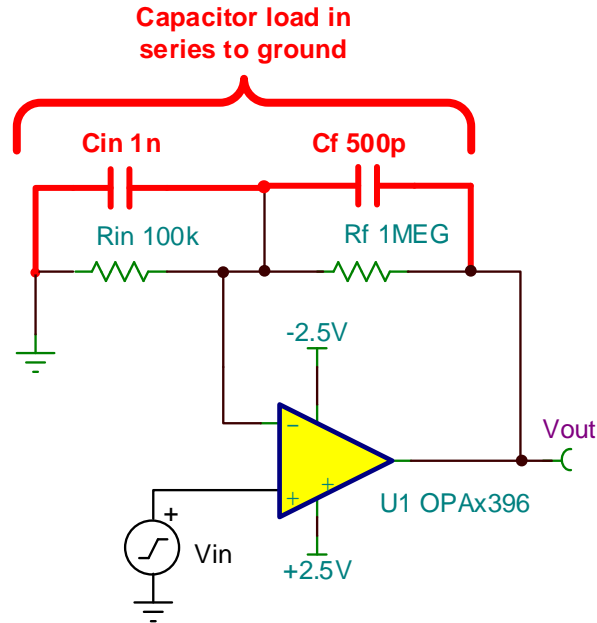


# Feedback capacitor as an output load

Remember:  $C_{total} = \frac{1}{\frac{1}{C_1} + \frac{1}{C_2} + \dots + \frac{1}{C_N}}$

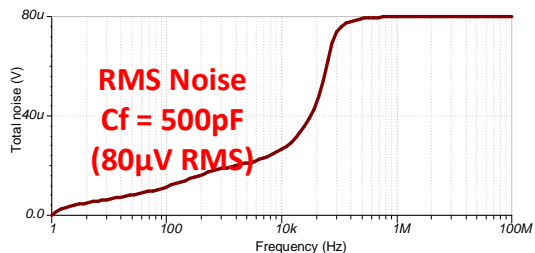
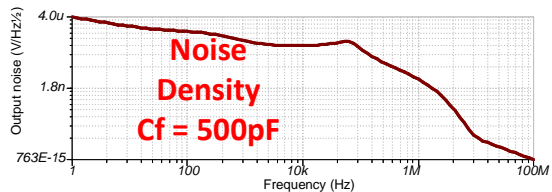
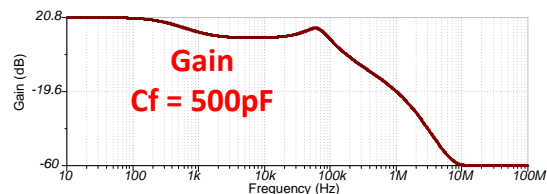
$$C_{total} = \frac{1}{\frac{1}{1nF} + \frac{1}{500pF}} = 333pF$$

- Capacitors in series add like parallel resistors
- Total capacitance is less than the smallest capacitor
- For small  $C_{in}$ ,  $C_f$  can be very large and  $C_{total}$  is still small.

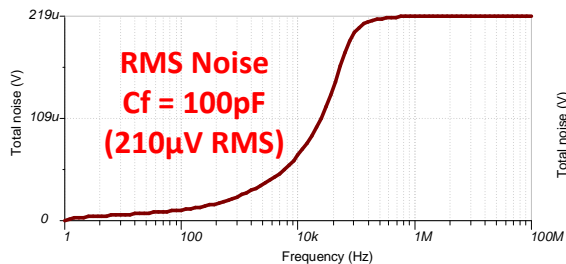
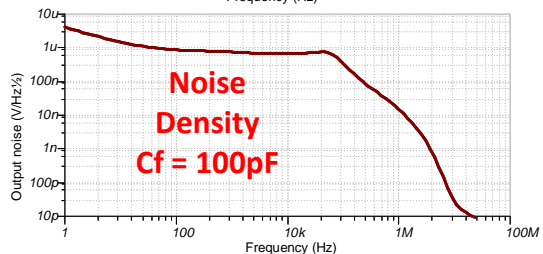
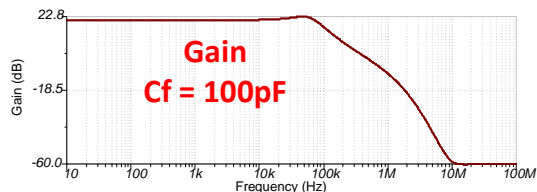


# AC and noise response for minimum capacitance

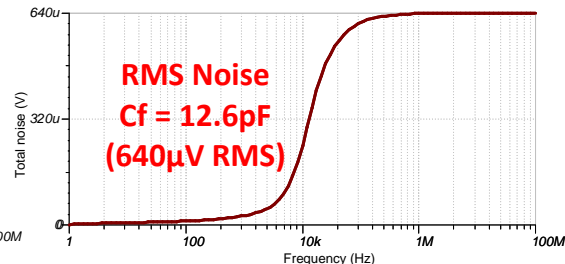
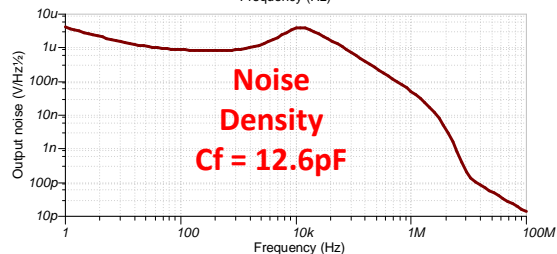
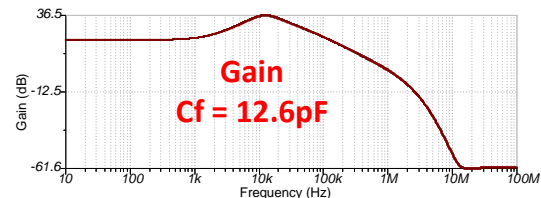
$f_p < f_z$



$R_f \times C_f = R_{in} \times C_{in}$

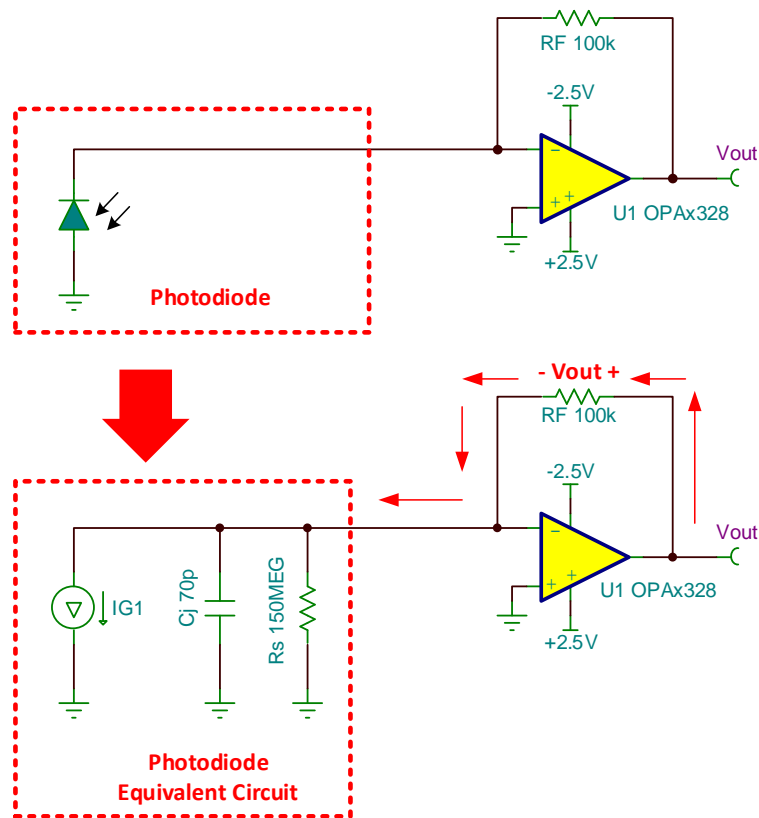


Minimum Cf

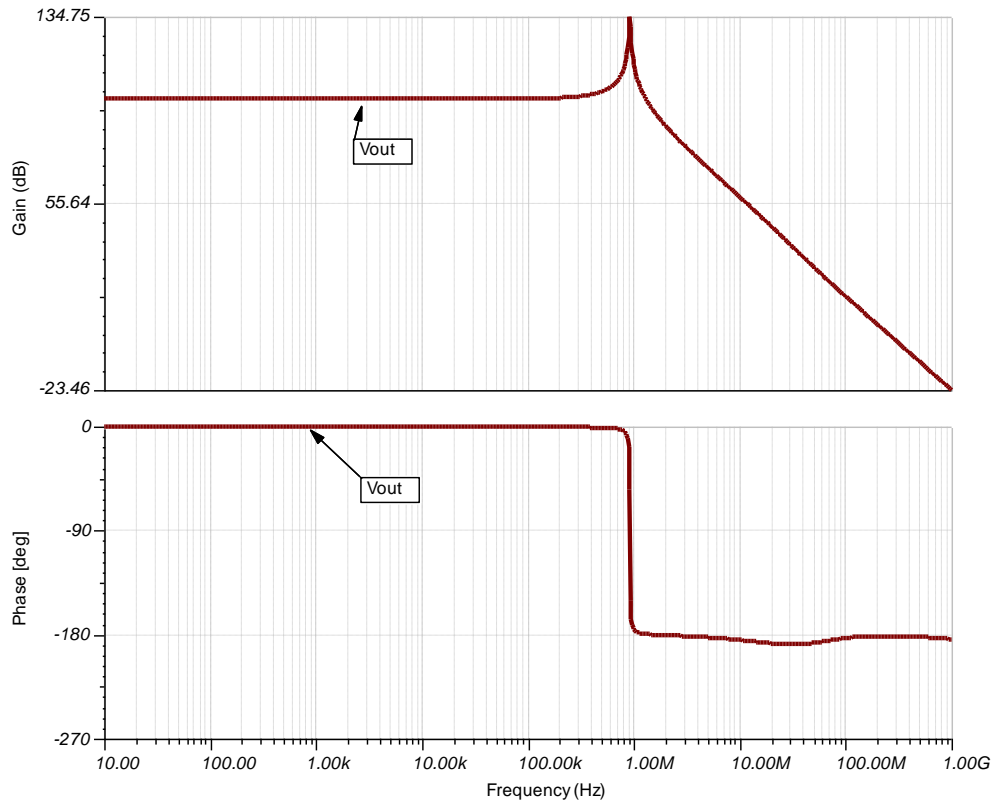
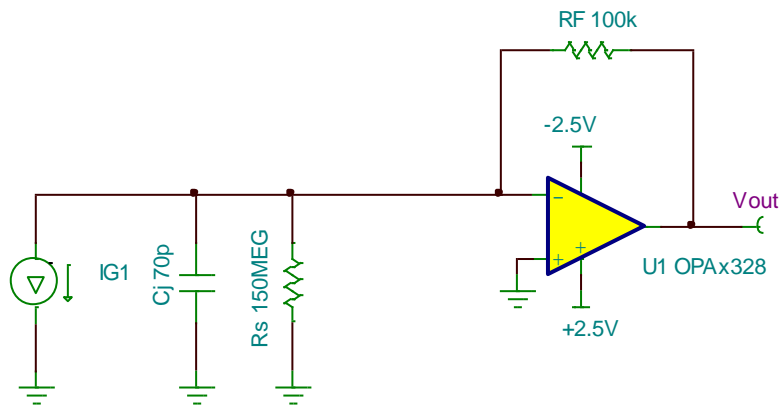


# Another example: Transimpedance amp

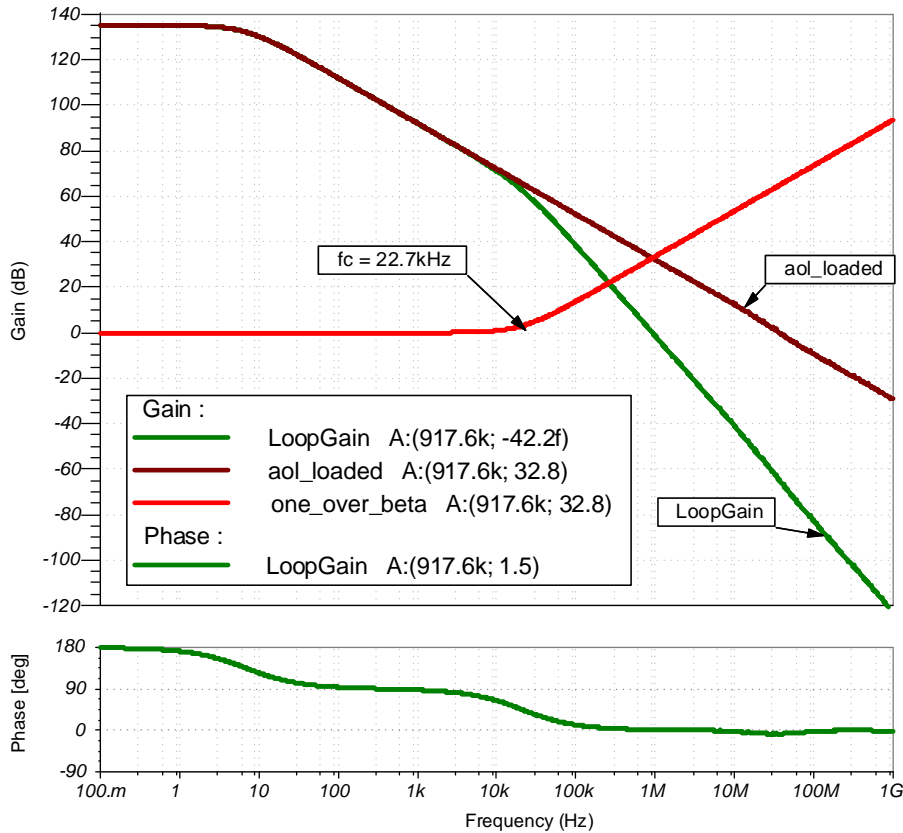
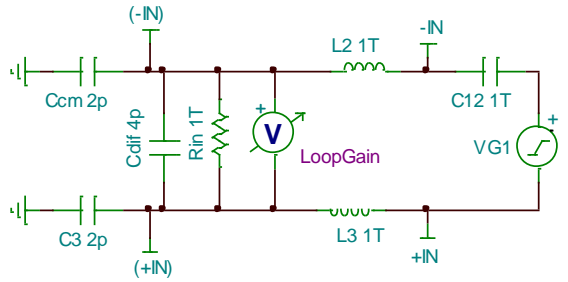
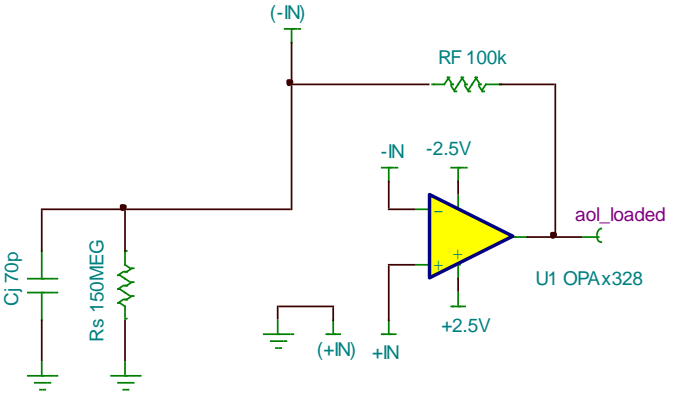
- A transimpedance amplifier converts an input current to an output voltage
- Commonly used to convert photodiode current to voltage
- Photodiodes have significant capacitance that can cause instability in this application.
- The parasitic resistance of the photodiode is quite high



# AC response of transimpedance example



# Open loop stability test for transimpedance amp



# Stabilizing transimpedance with minimum $C_f$

## Feedback capacitor for amplifier

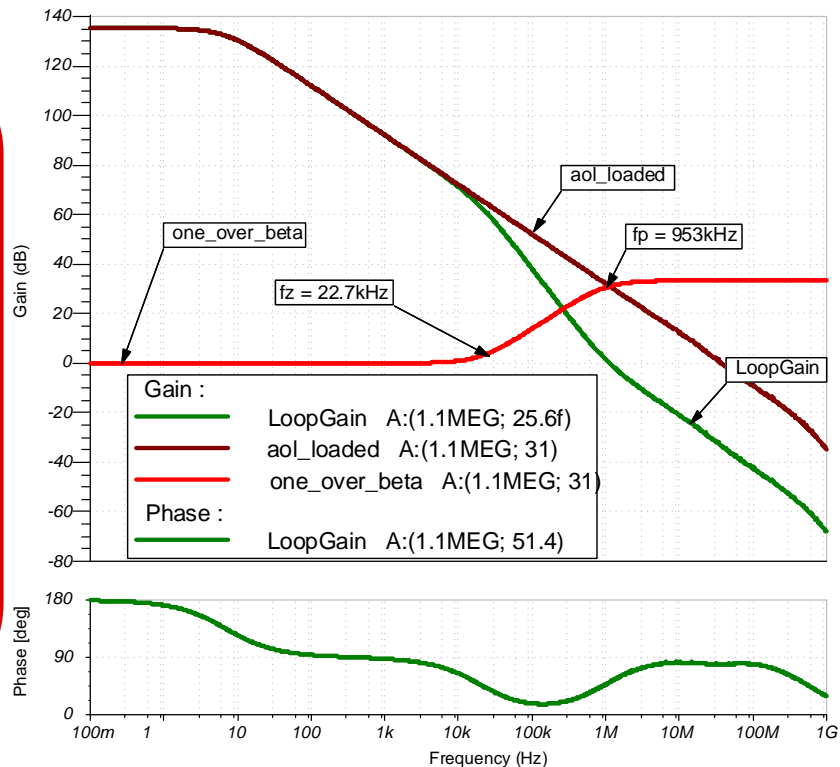
$$C_{f(\min)} = \sqrt{\frac{C_{in}}{2\pi R_f f_{ugbw}}} = \sqrt{\frac{70\text{pF}}{2\pi(100\text{k})(40\text{MHz})}} = 1.67\text{pF}$$

## Poles and zeros

$$f_z = \frac{R_s + R_f}{2\pi C_{in} R_s R_f} = \frac{150\text{M}\Omega + 100\text{k}\Omega}{2\pi(70\text{pF})(150\text{M}\Omega)(100\text{k}\Omega)} = 22.7\text{kHz}$$

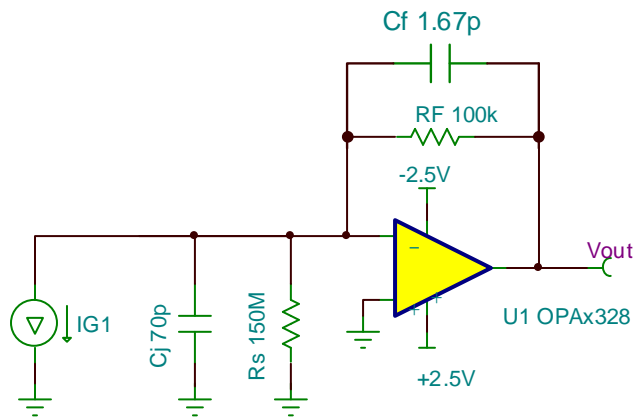
$$\text{For } R_s \gg R_f, f_z \approx \frac{1}{2\pi C_{in} R_f} = 22.7\text{kHz}$$

$$f_p = \frac{1}{2\pi C_f R_f} = \frac{1}{2\pi(1.67\text{pF})(100\text{k}\Omega)} = 953\text{kHz}$$



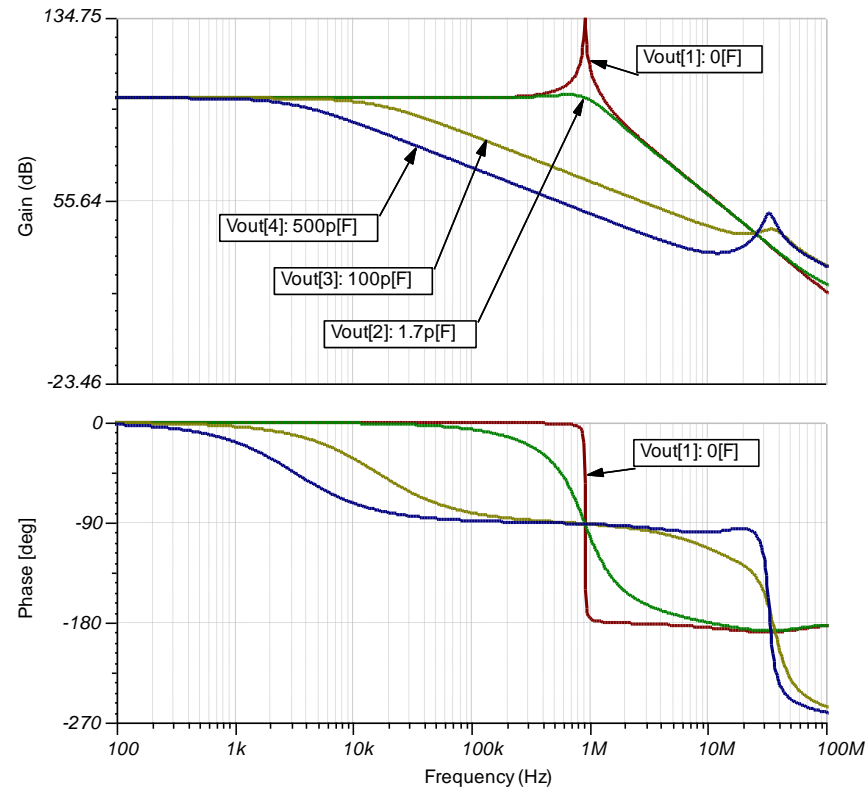


# Transimpedance AC response



Closed loop transimpedance bandwidth relates to feedback capacitor

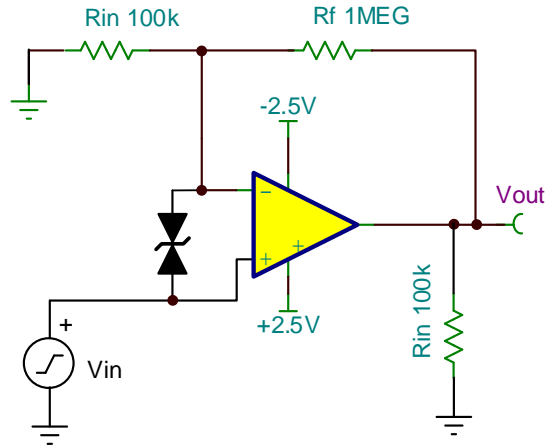
$$f_{BW} = \frac{1}{2\pi R_f C_F}$$



**Thanks for your time!**  
**Please try the quiz.**

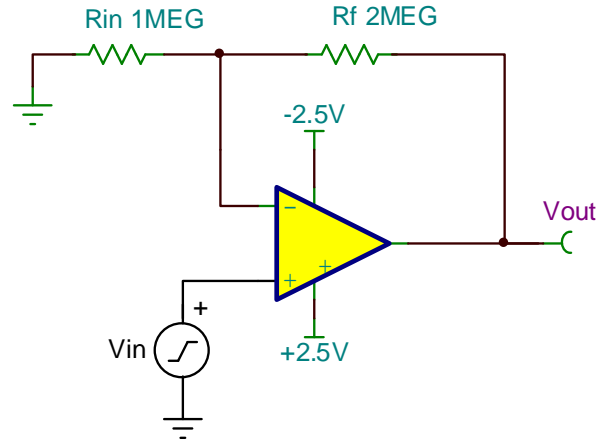
# Questions: Capacitance on inverting input

1. What is the most likely reason the circuit below is unstable?
  - a. Capacitance at the output adds a pole in  $A_{OL}$
  - b. Capacitance on the inverting input adds a zero in  $1/\beta$**
  - c. Capacitance on the inverting output adds a pole in  $1/\beta$
  - d. Capacitance on the inverting adds a zero in loop gain



# Questions: Capacitance on inverting input

2. For the transimpedance circuit below, how can stability be improved?
  - a. Reduce resistance of  $R_f$  and  $R_{in}$  proportionately while keeping gain constant
  - b. Choose a photodiode with a lower junction capacitor
  - c. Add a feedback capacitor
  - d. Improve the PCB layout so that the parasitic capacitance on the inverting input is minimized
  - e. All of the above



**Thanks for your time!**

# Derivations: Pole and zero for noninverting amp

"Feedback impedances"

$$Z_{in} = \frac{\frac{1}{s \cdot C_{in}} \cdot R_{in}}{R_{in} + \frac{1}{s \cdot C_{in}}} \quad Z_f = \frac{\frac{1}{s \cdot C_f} \cdot R_f}{R_{out} + \frac{1}{s \cdot C_f}}$$

"General Gain equation"

$$G = \frac{Z_f}{Z_{in}} + 1$$

"Substitute impedances into gain"

$$G = \frac{\frac{\frac{1}{s \cdot C_f} \cdot R_f}{R_f + \frac{1}{s \cdot C_f}} + 1}{\frac{\frac{1}{s \cdot C_{in}} \cdot R_{in}}{R_{in} + \frac{1}{s \cdot C_{in}}}}$$

"simplify for standard transfer function"

$$\frac{\frac{1}{s \cdot C_f} \cdot R_f}{R_f + \frac{1}{s \cdot C_f}} + 1 \xrightarrow{\text{simplify}} \frac{(C_{in} + C_f) \cdot R_f \cdot R_{in} \cdot s + R_{in} + R_f}{R_{in} \cdot (C_f \cdot R_f \cdot s + 1)}$$

"find the pole"

$$R_{in} \cdot (C_f \cdot R_f \cdot s + 1) = 0 \xrightarrow{\text{solve, } s} -\frac{1}{C_f \cdot R_f}$$

"pole frequency"

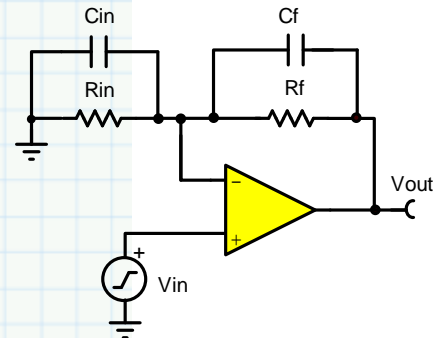
$$f_p = \frac{1}{2 \cdot \pi \cdot C_f \cdot R_f}$$

"find the zero"

$$(C_{in} + C_f) \cdot R_f \cdot R_{in} \cdot s + R_{in} + R_f = 0 \xrightarrow{\text{solve, } s} \frac{-R_{in} - R_f}{(C_{in} + C_f) \cdot R_f \cdot R_{in}}$$

"zero frequency"

$$f_z = \frac{R_{in} + R_f}{2 \cdot \pi \cdot (C_{in} + C_f) \cdot R_f \cdot R_{in}}$$



This shows the derivation of poles and zeros for a noninverting (and inverting) op amp.

# Derivations: Pole and zero when $R_{in} \cdot C_{in} = R_f \cdot C_f$

General pole frequency

$$f_p = \frac{1}{2 \cdot \pi \cdot C_f \cdot R_f}$$

General zero frequency

$$f_z = \frac{R_{in} + R_f}{2 \cdot \pi \cdot (C_{in} + C_f) \cdot R_f \cdot R_{in}}$$

This shows the derivation for  $C_f$  that will set the pole and zero equal. This is a good general choice for stability.

substitute gain relationship for  $R_{in} \cdot C_{in} = R_f \cdot C_f$   
into general equation

$$G = \frac{R_f}{R_{in}} + 1 \quad C_f = C_{in} \cdot \frac{R_{in}}{R_f}$$

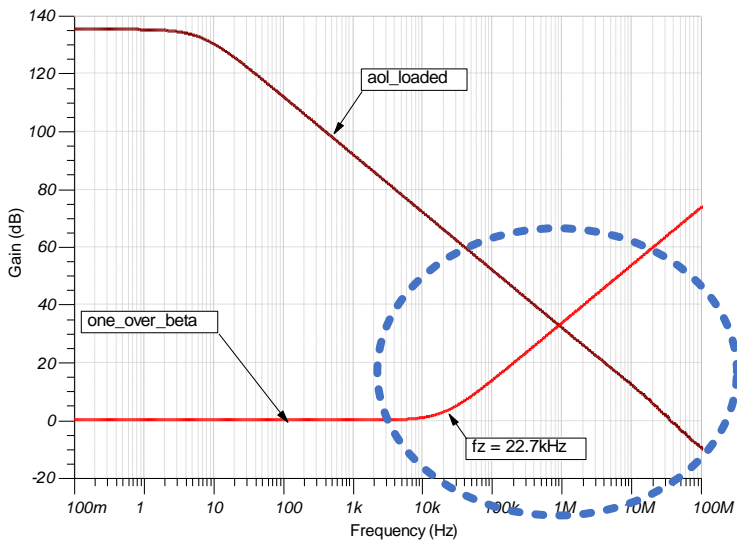
$$\frac{R_{in} + R_f}{(C_{in} + C_f) \cdot R_f \cdot R_{in}} \xrightarrow{\text{substitute, } G = \frac{R_f}{R_{in}} + 1, C_f = C_{in} \cdot \frac{R_{in}}{R_f}} \frac{1}{C_{in} \cdot R_{in}}$$

$$f_z = \frac{1}{2 \pi \cdot C_{in} \cdot R_{in}} \quad f_p = \frac{1}{2 \cdot \pi \cdot C_f \cdot R_f}$$

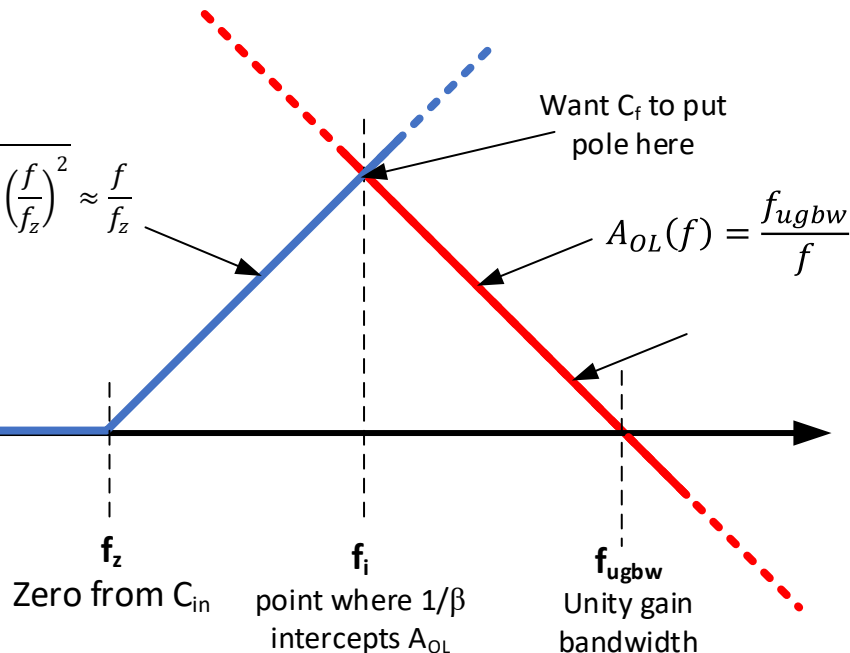
Note from above that when  $R_{in} \cdot C_{in} = R_f \cdot C_f$ , then  $f_z = f_p$

Use  $C_f = C_{in} \cdot \frac{R_{in}}{R_f}$  to find  $C_f$  for good stability

# Derivations: Minimum Cf for stability: part 1



$$1/\beta(f) = \sqrt{1 + \left(\frac{f}{f_z}\right)^2} \approx \frac{f}{f_z}$$



Equations on next slide relate to this figure



# Derivations: Minimum Cf for stability: part 2

Closed loop gain or  $1/\beta$  is the DC gain multiplied by the zero response

$$1/\beta(f) = G_{dc} \sqrt{1 + \left(\frac{f}{f_z}\right)^2} \approx G_{dc} \left(\frac{f}{f_z}\right)$$

Open loop gain near the unity gain bandwidth:

$$A_{OL}(f) \approx \frac{f_{ugbw}}{f}$$

Find the point where Aol and  $1/\beta$  intersect

$$G_{dc} \left(\frac{f}{f_z}\right) = \frac{f_{ugbw}}{f}$$

$$f_i = \sqrt{\frac{f_{ugbw} f_z}{G_{dc}}}$$

Substitute  $f_z = \frac{R_{in} + R_f}{2\pi C_{in} R_f R_{in}}$  into  $f_i$

$$f_i = \sqrt{\frac{f_{ugbw} (R_{in} + R_f)}{2\pi C_{in} R_f R_{in} G_{dc}}}$$

Set pole  $f_p = \frac{1}{2\pi R_f C_f}$  to intercept of  $A_{OL}$  and  $1/\beta$

$$\frac{1}{2\pi R_f C_f} = \sqrt{\frac{f_{ugbw} (R_{in} + R_f)}{2\pi C_{in} R_f R_{in} G_{dc}}}$$

Substitute  $G_{dc} = \frac{R_f}{R_{in}} + 1$  and solve for  $C_f$

$$C_f = \sqrt{\frac{C_{in}}{2\pi f_{ugbw} R_f}}$$

General eq for inverting non-inverting, and transimpedance