# **MSP** with Captivate<sup>™</sup> Technology

**Finger Probes** 

June 3, 2019 Dennis Lehman – MSP430 Applications



#### **Overview**

- The information in these slides offer a few suggestions, but it is up to the design/manufacturing engineer to validate the performance over time and temperature
- These are by no means the only options do a google search for other options
- TI did perform experiments with the three options described in the following slides and ranked the in order of performance
  - #1 Gelatin Finger
    - Worked reasonably well (fun to make)
    - Had to experiment with different formulations of mixture, R and C values
  - #2 Conductive Rubber
    - Worked reasonably well
    - Difficult to find
  - #3 Copper Slug
    - due to the curved surface, the coupling is far inferior to the gelatin finger
- None of these options performed exactly like an actual human finger

### **Gelatin Finger**

- Use non-flavored gelatin, glycerin and water to create the finger
- Video showing how to do it.
  https://www.youtube.com/watch?v=guUVc9spVSg
- 2tbs gelatin
- 2tbs water
- 1tbs glycerin
- Heat in microwave for few seconds



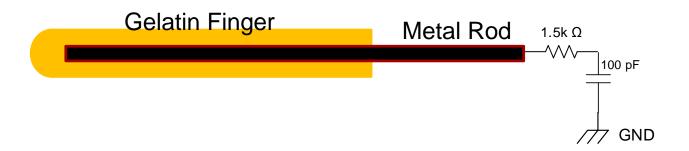
Soft molding compound to create the mold.





### **Gelatin Finger**

- The gelatin finger has a limited life
- Over time, the finger will begin to dry out and possibly loose some of its coupling characteristics
  - You will need to make replacements
  - How often? You will need to experiment
- Use a metal rod to stiffen the finger and provide mounting to automated test fixture.



Note: The Human Body Model for capacitance, as defined by the <u>Electrostatic Discharge Association (ESDA)</u> is a  $100p_{\overline{L}}^{\underline{E}}$  capacitor in series with a  $1.5k_{\overline{L}}^{\underline{O}}$  resistor.



## **Copper Slug Finger**

- 12mm copper slug
- $\sim$ 3 4 mm touch area

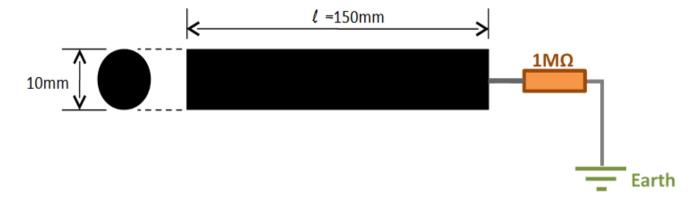




#### Construction

- The slug/probe is tied to ground through a 1M ohm resistor
  - Shown here is an example using a conductive rubber

Cylindrical shaped conductive rubber with a length of 150mm and diameter of 10mm can be used as a test finger. The rubber must have resistivity of  $\rho \approx 1.0\Omega/mm$ .



From Azoteq document AZD078 Test Finger Specification

## **Stainless Steel Finger**

• 10mm stainless steel rod polished on the end

