## v4 Power + EPO BoardNon UPS Lidar loads Beacon Load and top Board outline switch lights board with $CS_NonUPS$ the Indicators control, Main +vePower with Comms Power current brick Lite battery Current sensing -ve Connector for Power with sensing 24Vsteering through this path Non UPS and CAN CAN Comms 16Amps Loads with Comms for Auto Aux battery +ve CAN Comms each port unhitch $24V_Brick$ 12V, 6Ah -ve Buck CS\_UPS Boost Current sensing UPS Power with Connector for through this path v4 control CAN Comms loads $24V_Brick$ UPS Loads Aux battery Charging with CAN Load $CS_NonUPS$ Comms Circuit v4 brake switch $CS\_UPS$ board with Aux battery Comms Headers for v4the SPI, UART compute control, MCU and I2C ${\bf Connector}$ current STM32for EPO sensing buttons CAN Port and CAN Comms for each port USB Port To the other boards Inrush Current protection Circuit EPO Power ON buttons Coil Coil button (A2) $\widehat{A1}$ (A2) $\overline{A1}$ Contactor 2 for Contactor 1 for Motor Board level Controller and electronics Motor loads