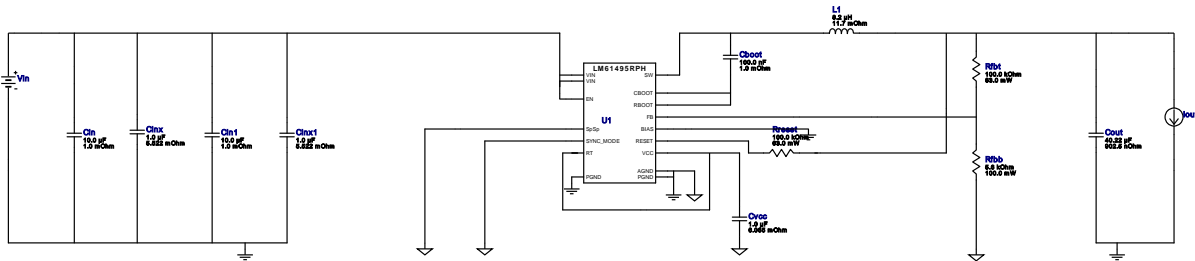


## WEBENCH® Design Report

Design : 21 LM61495RPHR  
LM61495RPHR 20V-24V to 19.00V @ 10A



### Design Alerts

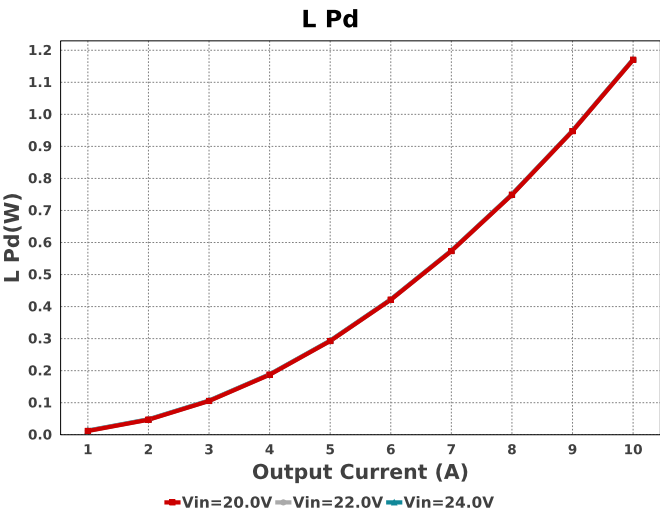
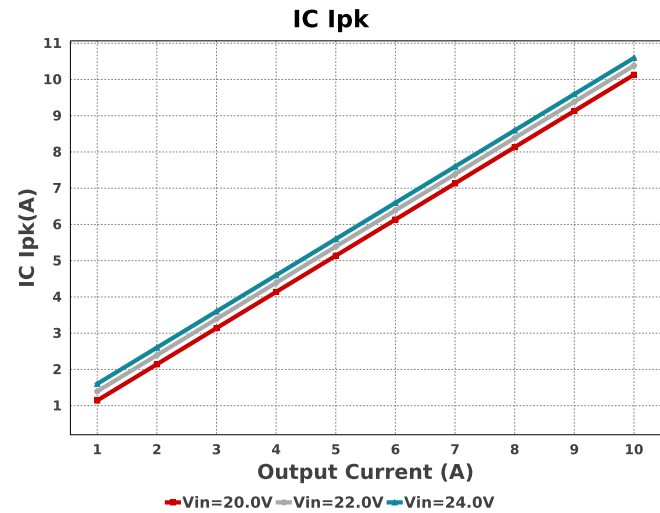
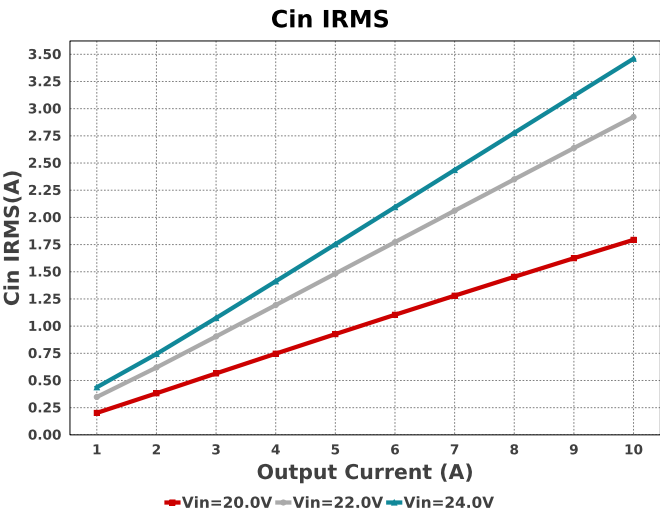
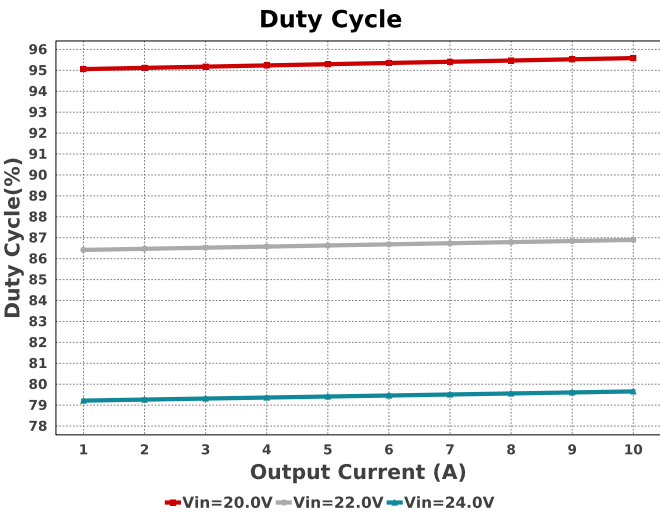
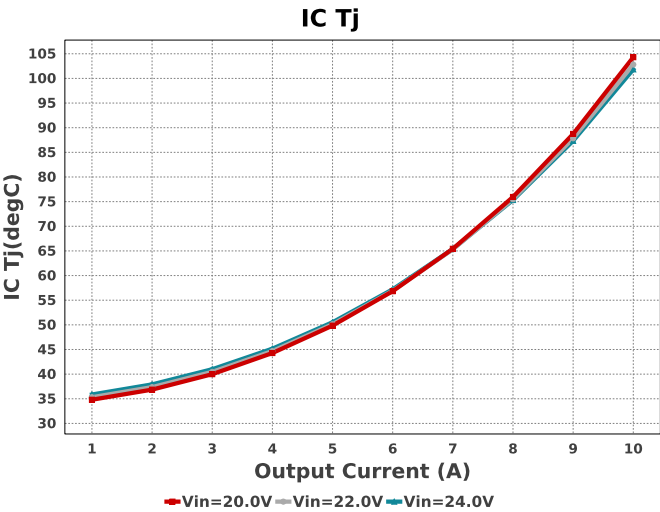
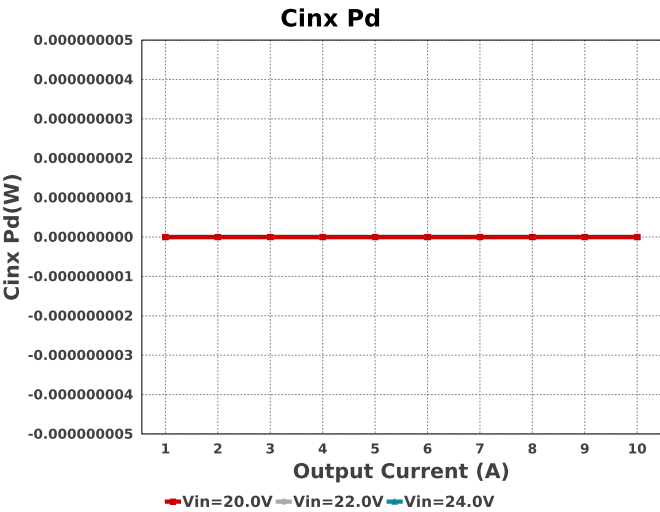
#### Component Selection Information

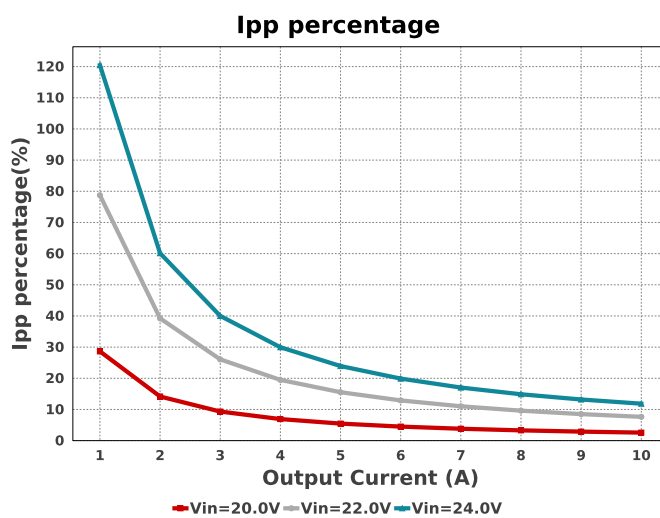
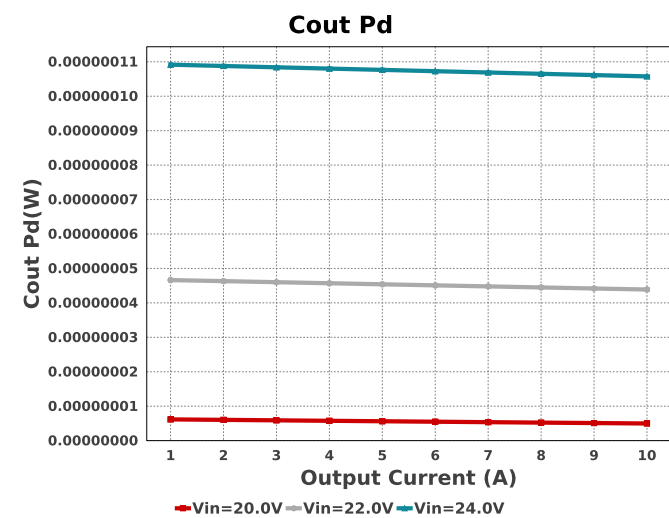
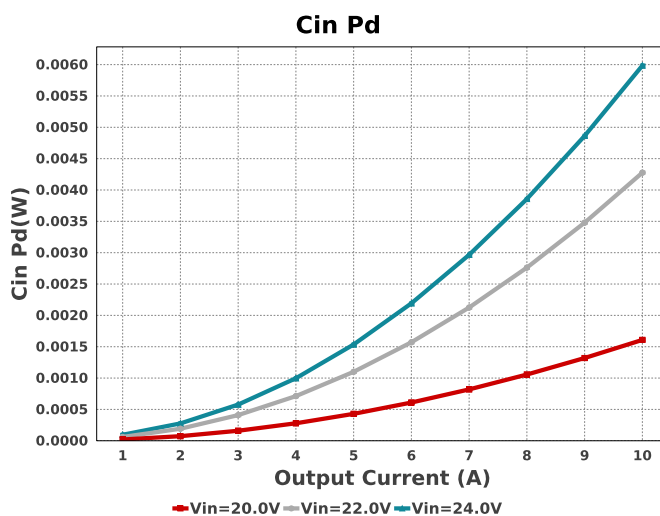
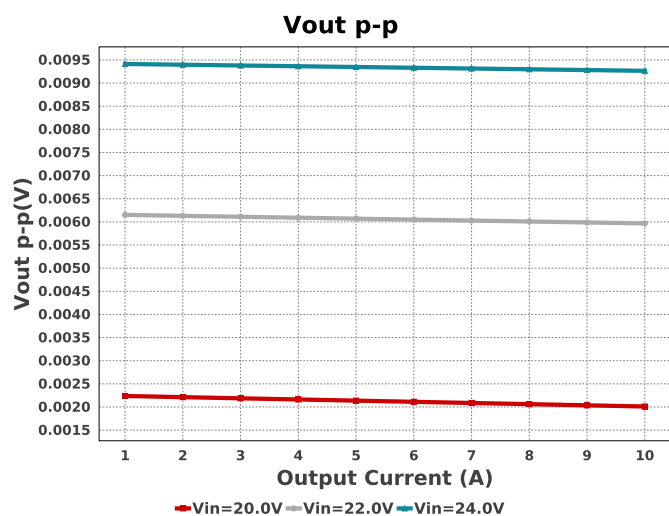
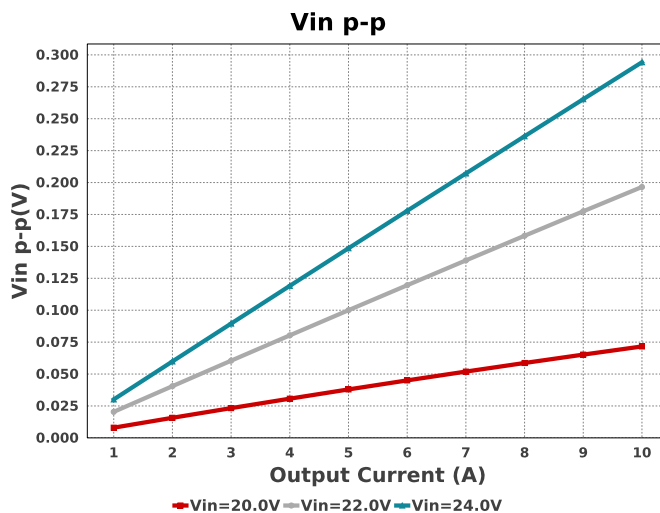
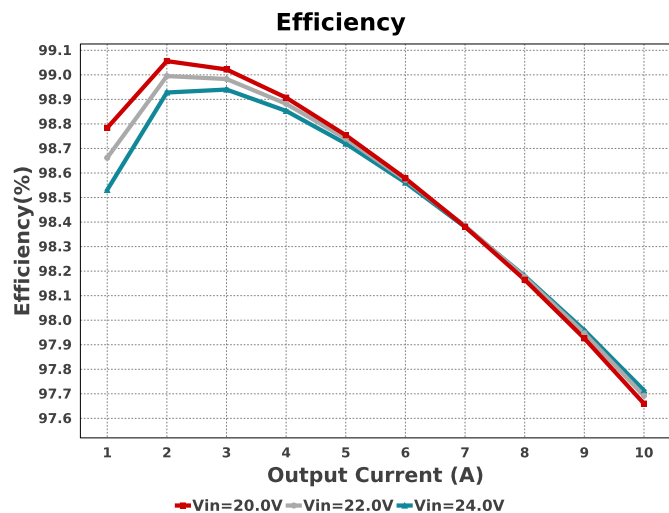
This device can work in steady state at Vin = 3V. However, needs a minimum of 3.6V during start up. See datasheet for details.

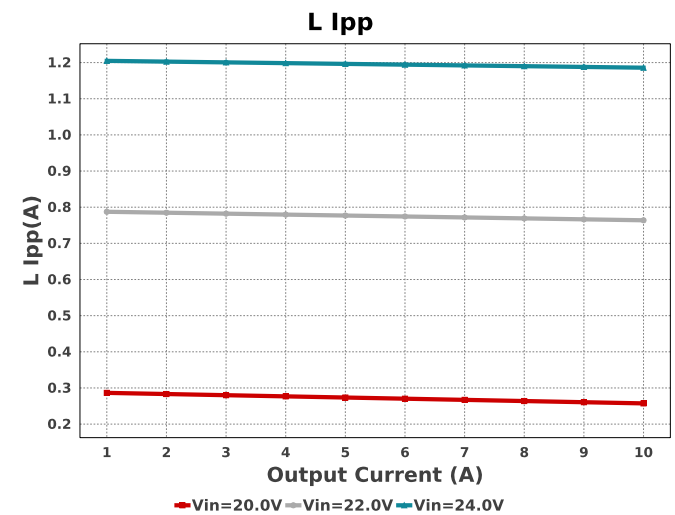
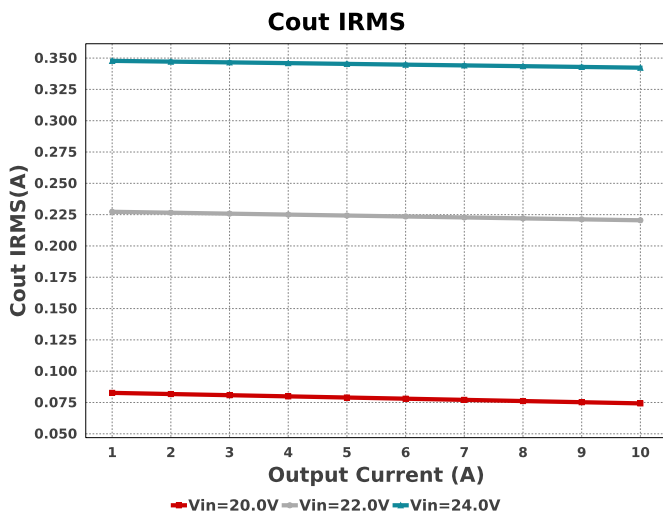
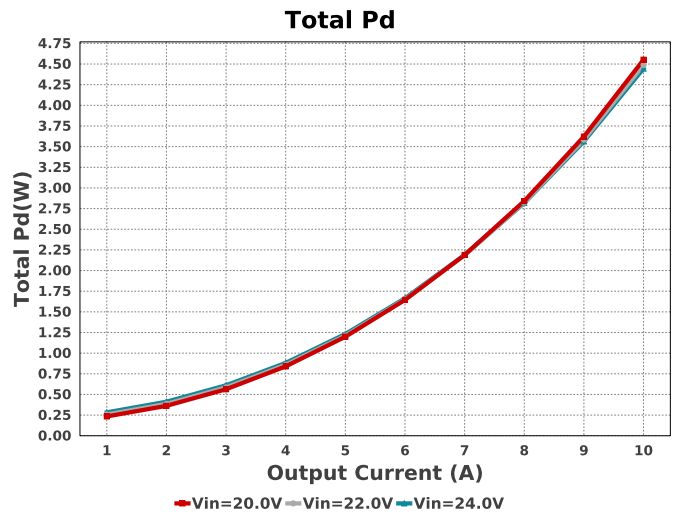
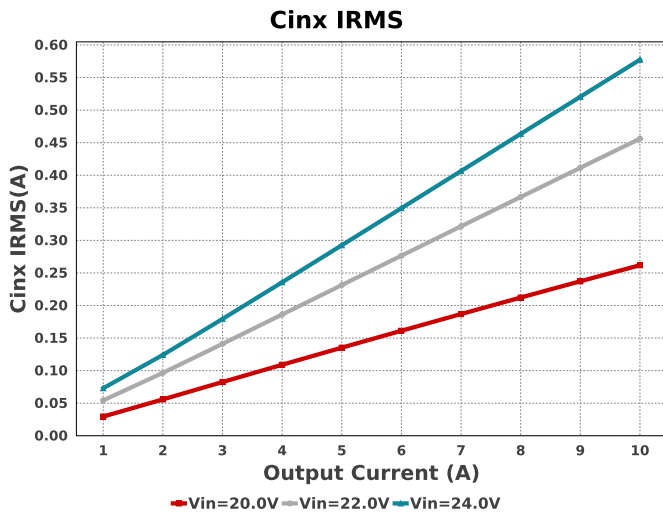
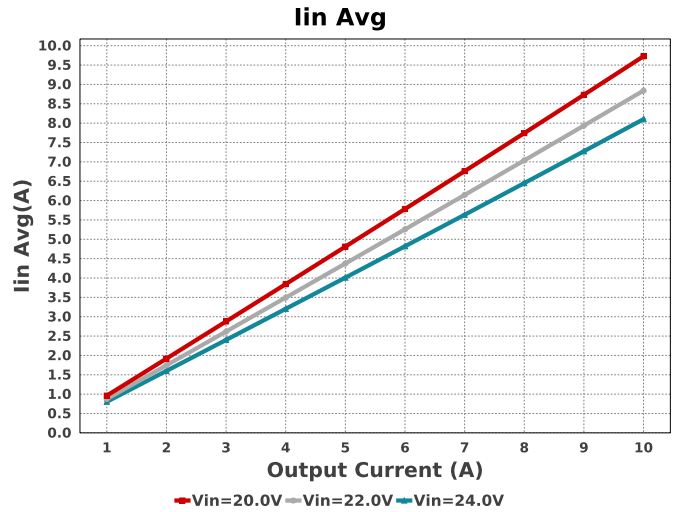
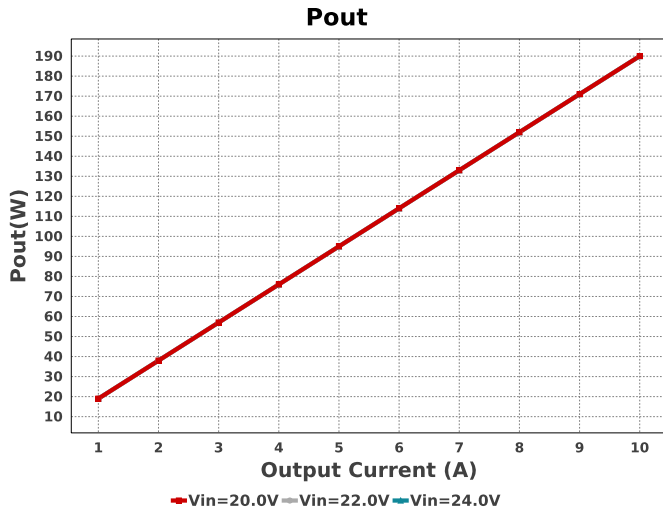
### Electrical BOM

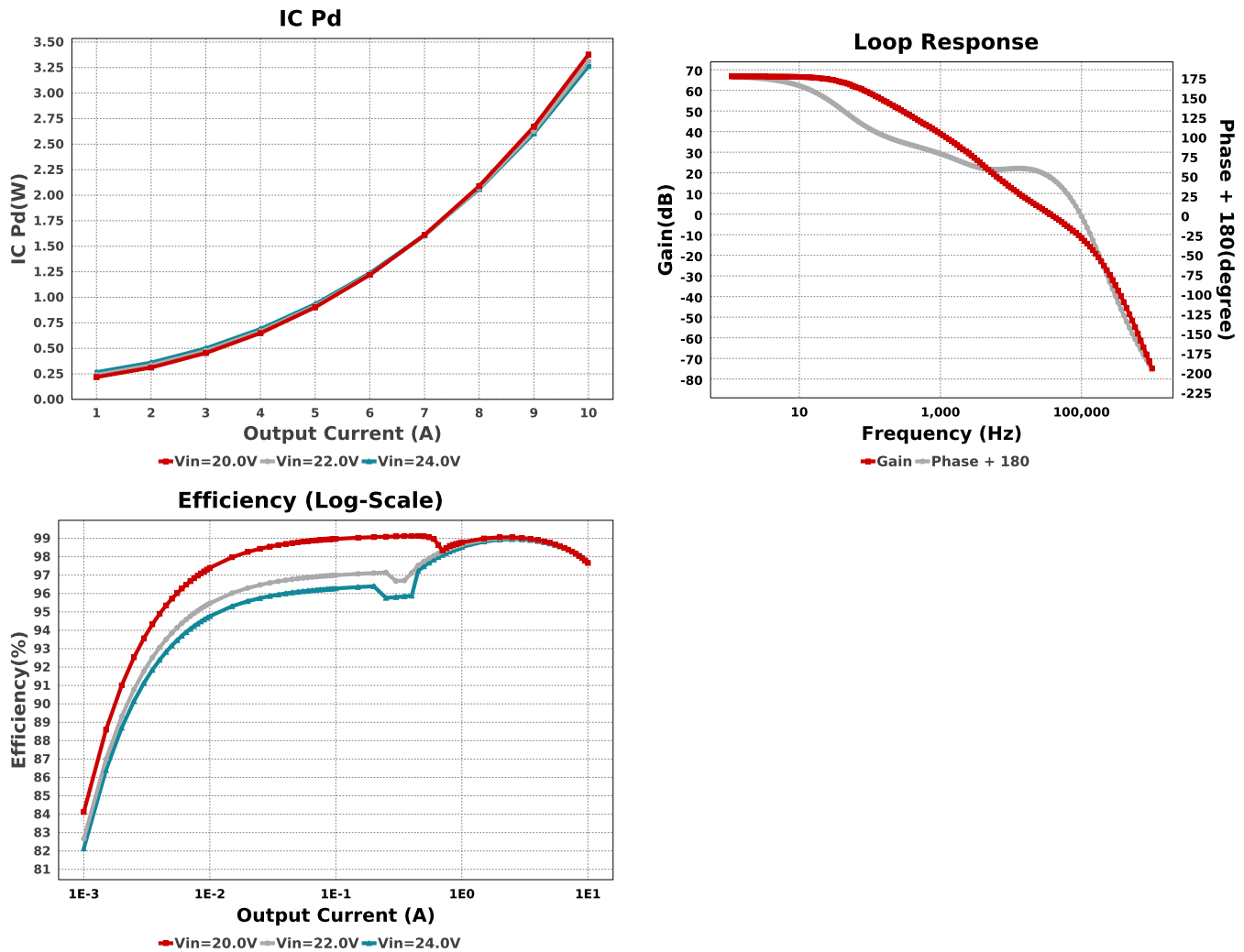
Name	Manufacturer	Part Number	Properties	Qty	Price	Footprint
Cboot	MuRata	GRM155R71A104KA01D Series= X7R	Cap= 100.0 nF ESR= 1.0 mOhm VDC= 10.0 V IRMS= 0.0 A	1	\$0.01	0402 3 mm <sup>2</sup>
Cin	MuRata	GRM32ER71H106KA12L Series= X7R	Cap= 10.0 uF ESR= 1.0 mOhm VDC= 50.0 V IRMS= 6.0 A	1	\$0.47	1210_270 15 mm <sup>2</sup>
Cin1	MuRata	GRM32ER71H106KA12L Series= X7R	Cap= 10.0 uF ESR= 1.0 mOhm VDC= 50.0 V IRMS= 6.0 A	1	\$0.47	1210_270 15 mm <sup>2</sup>
Cinx	TDK	C1608X5R1H105K080AB Series= X5R	Cap= 1.0 uF ESR= 5.522 mOhm VDC= 50.0 V IRMS= 2.2162 A	1	\$0.03	0603 5 mm <sup>2</sup>
Cinx1	TDK	C1608X5R1H105K080AB Series= X5R	Cap= 1.0 uF ESR= 5.522 mOhm VDC= 50.0 V IRMS= 2.2162 A	1	\$0.03	0603 5 mm <sup>2</sup>
Cout	CUSTOM	CUSTOM Series= ?	Cap= 40.22 uF ESR= 902.5 nOhm VDC= 28.5 V IRMS= 489.03 mA	1	NA	CUSTOM 0 mm <sup>2</sup>
Cvcc	MuRata	GRM188R60J105KA01D Series= X5R	Cap= 1.0 uF ESR= 6.065 mOhm VDC= 6.3 V IRMS= 1.36934 A	1	\$0.01	0603 5 mm <sup>2</sup>
L1	Coilcraft	XAL1010-822MEB	L= 8.2 uH 11.7 mOhm	1	\$1.71	XAL1010 160 mm <sup>2</sup>
Rfbb	Yageo	RC0603FR-075K6L Series= ?	Res= 5.6 kOhm Power= 100.0 mW Tolerance= 1.0%	1	\$0.01	0603 5 mm <sup>2</sup>

Name	Manufacturer	Part Number	Properties	Qty	Price	Footprint
Rfbt	Vishay-Dale	CRCW0402100KFKED Series= CRCW..e3	Res= 100.0 kOhm Power= 63.0 mW Tolerance= 1.0%	1	\$0.01	0402 3 mm <sup>2</sup>
Rreset	Vishay-Dale	CRCW0402100KFKED Series= CRCW..e3	Res= 100.0 kOhm Power= 63.0 mW Tolerance= 1.0%	1	\$0.01	0402 3 mm <sup>2</sup>
U1	Texas Instruments	LM61495RPHR	Switcher	1	\$2.11	RPH0016A 25 mm <sup>2</sup>









## Operating Values

#	Name	Value	Category	Description
1.	Cin IRMS	3.46 A	Capacitor	Input capacitor RMS ripple current
2.	Cin Pd	5.985 mW	Capacitor	Input capacitor power dissipation
3.	Cinx IRMS	577.422 mA	Capacitor	Bulk capacitor RMS ripple current
4.	Cinx Pd	0.0 W	Capacitor	Bulk capacitor power dissipation
5.	Cout IRMS	342.324 mA	Capacitor	Output capacitor RMS ripple current
6.	Cout Pd	105.76 nW	Capacitor	Output capacitor power dissipation
7.	IC Ipk	10.593 A	IC	Peak switch current in IC
8.	IC Pd	3.265 W	IC	IC power dissipation
9.	IC Tj	101.83 degC	IC	IC junction temperature
10.	ICThetaJA Effective	22.0 degC/W	IC	Effective IC Junction-to-Ambient Thermal Resistance
11.	Iin Avg	8.102 A	IC	Average input current
12.	Ipp percentage	11.858 %	Inductor	Inductor ripple current percentage (with respect to average inductor current)
13.	L Ipp	1.186 A	Inductor	Peak-to-peak inductor ripple current
14.	L Pd	1.171 W	Inductor	Inductor power dissipation
15.	Cin Pd	5.985 mW	Power	Input capacitor power dissipation
16.	Cinx Pd	0.0 W	Power	Bulk capacitor power dissipation
17.	Cout Pd	105.76 nW	Power	Output capacitor power dissipation
18.	IC Pd	3.265 W	Power	IC power dissipation
19.	L Pd	1.171 W	Power	Inductor power dissipation
20.	Total Pd	4.445 W	Power	Total Power Dissipation
21.	BOM Count	12	System	Total Design BOM count
22.	Cross Freq	35.656 kHz	System	Bode plot crossover frequency
23.	Duty Cycle	79.655 %	System	Duty cycle
24.	Efficiency	97.714 %	System	Steady state efficiency
25.	FootPrint	281.0 mm <sup>2</sup>	System	Total Foot Print Area of BOM components

#	Name	Value	Category	Description
26.	Frequency	400.0 kHz	System Information	Switching frequency
27.	Gain Marg	-11.762 dB	System Information	Bode Plot Gain Margin
28.	Iout	10.0 A	System Information	Iout operating point
29.	Low Freq Gain	66.745 dB	System Information	Gain at 1Hz
30.	Mode	CCM	System Information	Conduction Mode
31.	Phase Marg	50.419 deg	System Information	Bode Plot Phase Margin
32.	Pout	190.0 W	System Information	Total output power
33.	Total BOM	NA	System Information	Total BOM Cost
34.	Vin	24.0 V	System Information	Vin operating point
35.	Vin p-p	294.233 mV	System Information	Peak-to-peak input voltage
36.	Vout	19.0 V	System Information	Operational Output Voltage
37.	Vout Actual	18.857 V	System Information	Vout Actual calculated based on selected voltage divider resistors
38.	Vout Tolerance	2.932 %	System Information	Vout Tolerance based on IC Tolerance (no load) and voltage divider resistors if applicable
39.	Vout p-p	9.214 mV	System Information	Peak-to-peak output ripple voltage

## Design Inputs

Name	Value	Description
Iout	10.0	Maximum Output Current
VinMax	24.0	Maximum input voltage
VinMin	20.0	Minimum input voltage
Vout	19.0	Output Voltage
base_pn	LM61495	Base Product Number
source	DC	Input Source Type
Ta	30.0	Ambient temperature

## WEBENCH® Assembly

### Component Testing

Some published data on components in datasheets such as Capacitor ESR and Inductor DC resistance is based on conservative values that will guarantee that the components always exceed the specification. For design purposes it is usually better to work with typical values. Since this data is not always available it is a good practice to measure the Capacitance and ESR values of  $C_{in}$  and  $C_{out}$ , and the inductance and DC resistance of  $L1$  before assembly of the board. Any large discrepancies in values should be electrically simulated in WEBENCH to check for instabilities and thermally simulated in WebTHERM to make sure critical temperatures are not exceeded.

### Soldering Component to Board

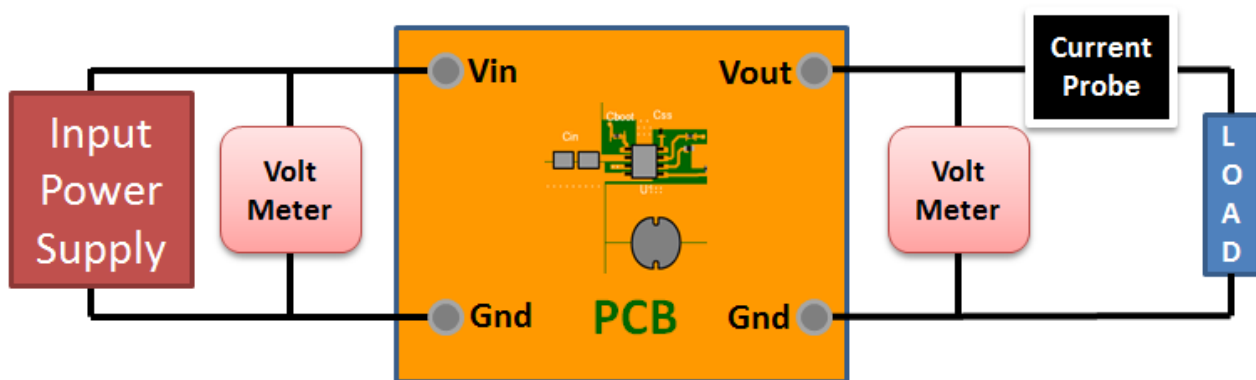
If board assembly is done in house it is best to tack down one terminal of a component on the board then solder the other terminal. For surface mount parts with large tabs, such as the DPAK, the tab on the back of the package should be pre-tinned with solder, then tacked into place by one of the pins. To solder the tab down to the board place the iron down on the board while resting against the tab, heating both surfaces simultaneously. Apply light pressure to the top of the plastic case until the solder flows around the part and the part is flush with the PCB. If the solder is not flowing around the board you may need a higher wattage iron (generally 25W to 30W is enough).

### Initial Startup of Circuit

It is best to initially power up the board by setting the input supply voltage to the lowest operating input voltage 20.0V and set the input supply's current limit to zero. With the input supply off connect up the input supply to  $V_{in}$  and GND. Connect a digital volt meter and a load if needed to set the minimum load of the design from  $V_{out}$  and GND. Turn on the input supply and slowly turn up the current limit on the input supply. If the voltage starts to rise on the input supply continue increasing the input supply current limit while watching the output voltage. If the current increases on the input supply, but the voltage remains near zero, then there may be a short or a component misplaced on the board. Power down the board and visually inspect for solder bridges and recheck the diode and capacitor polarities. Once the power supply circuit is operational then more extensive testing may include full load testing, transient load and line tests to compare with simulation results.

### Load Testing

The setup is the same as the initial startup, except that an additional digital voltmeter is connected between  $V_{in}$  and GND, a load is connected between  $V_{out}$  and GND and a current meter is connected in series between  $V_{out}$  and the load. The load must be able to handle at least rated output power + 50% ( 7.5 watts for this design). Ideally the load is supplied in the form of a variable load test unit. It can also be done in the form of suitably large power resistors. When using an oscilloscope to measure waveforms on the prototype board, the ground leads of the oscilloscope probes should be as short as possible and the area of the loop formed by the ground lead should be kept to a minimum. This will help reduce ground lead inductance and eliminate EMI noise that is not actually present in the circuit.



### Design Assistance

1. The LM61495 is qualified for Automotive applications. All passives and other components selected in this design may not be qualified for Automotive applications. This device can work in steady state at  $V_{in} = 3V$ . However, needs a minimum of 3.6V during start up. See datasheet for details The user is required to verify that all components in the design meet the qualification and safety requirements for their specific application
2. Master key : 0103A7E0E30D0DC8[v1]
3. **LM61495** Product Folder : <http://www.ti.com/product/LM61495> : contains the data sheet and other resources.

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