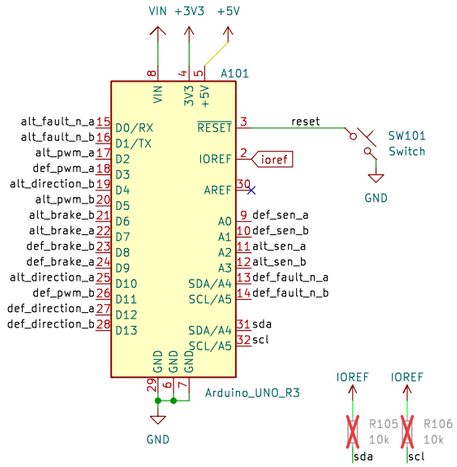
Arduino Header



Standard Motorshield Assignments:
Channel A:

D12 – Direction
D3 – PWM (work duty)
D9 – Brake
A0 – current sensing.

Channel B:

D13 – Direction
D11 – PWM (work duty)
D8 – Brake
A1 – current sensing

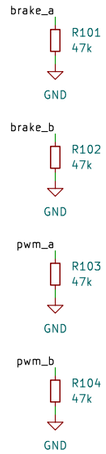
DRV8874 control logic:

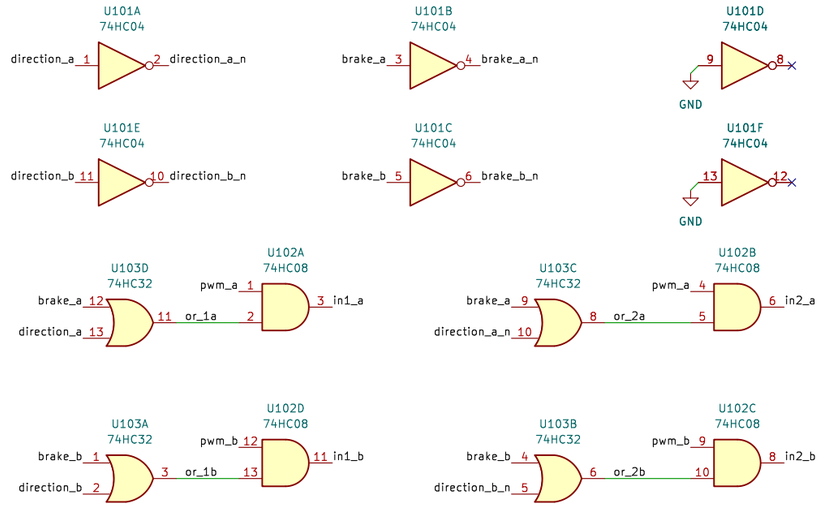
PH/EN Mode (PMODE Low)
nSleep/EN/PH out1/2
0 X X ZZ
1 0 X 00
1 1 0 01
1 1 1 10

nSleep = high / pwm
EN = not brake / pwm
PH = dir

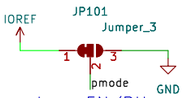
PWM Mode (PMODE High)
nSleep/in1/2 out1/2
0 X X ZZ
1 0 0 ZZ
1 0 1 01
1 1 0 10
1 1 1 00

nSleep = high
in1 = pwm and (dir or brake)
in2 = pwm and (not dir or brake)

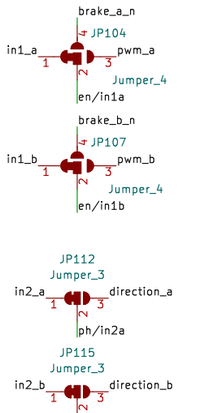




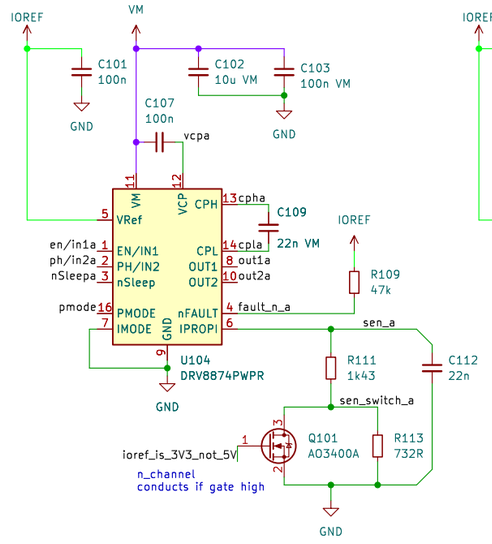
DRV8874 Mode Select

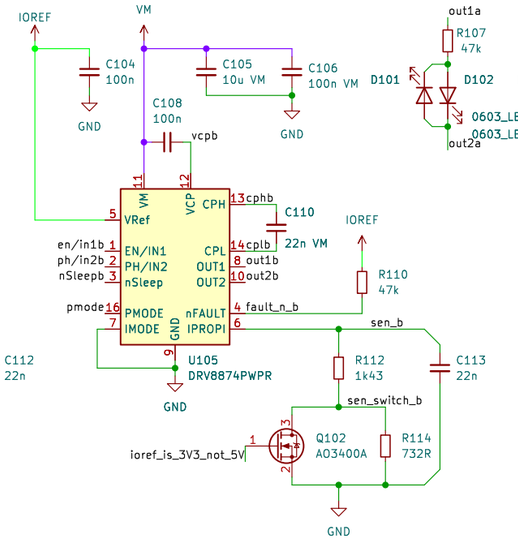


Low: EN/PH
High: PWM
Z: Independent

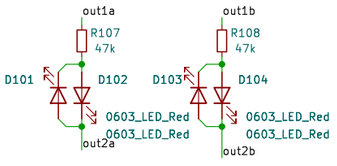


DRV8874 Motor Driver

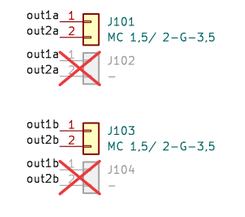




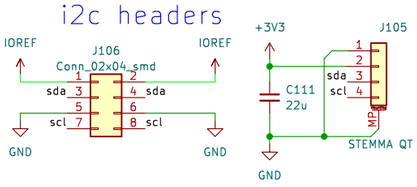
Track LEDs



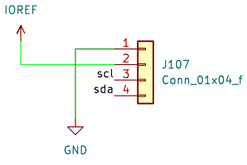
Track Connector



i2c headers

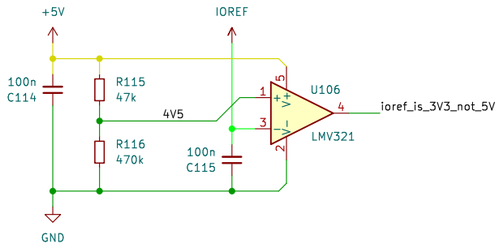


OLED Header



Alternative pinout to allow stacking

OpAmp as IORef Comparator



DRV8874 (max 6A) Current Sensing:
V_prop is limited to VRef inside DRV8874

5V = 0.000455*(1430+732)*A => A=5,08
3,3V = 0.000455* 1430 *A => A=5,07

if subbed with DRV8876 (max 3.5A):
5V = 0.001*(x+y)*A => A=
3,3V = 0.001* x *A => A=

---

candidate values:
2k+1k 3.63/1.65 1%
1k8+(680+220) 4.0/1.83 1%
1k5+(680+100) 4.8/2.2 0.2%
1k43+732(extend.) 5.08 0.1% <-- USED HERE
(1k2+120)+680 5.5/2.5 0.0%
1k2+(470+180) 5.9/2.7 2%
1k2+620(extend.) 5.9/2.7 0.1%
1k1+560 (0603) 6.6/3.0 0.4%

Power Sheet

Engineer: Erwin Peterlin
semify-eda.com

DCC-EX

Sheet: /
File: motor-shield.kicad_sch

Title: EX-Motorshield8874

Size: A3	Date: 2023-02-23	Rev: RevA
KiCad E.D.A. kicad 7.0.5		Id: 1/2