Processor SDK Linux Automotive Data Sheet



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All performance numbers provided in this document are gathered using DRA75x Evaluation Module with A15 running at 1500Mhz and DDR3 configured at 532MHz and DRA72x Evaluation module with A15 running at 1500Mhz and DDR3 configured at 666Mhz

About This Manual

This document provides a feature overview and performance data for each of the device drivers which are part of the **Processor SDK Linux Automotive Release** package. This document should be used in conjunction with the release notes provided with the Processor SDK Linux Automotive package for information on specific issues present with drivers included in a particular release.

U-Boot Overview

Boot Modes Supported

Green colored box in the table below means that the particular boot mode is supported on the device in the release.

DRA7xx Supported Boot Modes

Boot Mode	DRA7xx Evaluation Module (EVM)
QSPI Flash	Yes
MMC/SD	Yes
eMMC Boot	Yes
UART Boot	No
NOR Flash	No
EMAC Boot	No
USB Boot	No

Note: These are supported boot modes in Processor SDK Linux Automotive software, the actual hardware may support many more boot modes than shown here. Please refer to hardware documentation for list of all supported boot modes.

U-Boot Features Supported

U-Boot is the defacto bootloader for Linux kernel on ARM. The following features of U-Boot are supported in this release.

U-Boot supported feature table

Feature	DRA7xx (Evaluation Module)
Ethernet Download (TFTP)	Yes
MMC/SD	Yes
QSPI Flash	Yes
eMMC	Yes
UART	No

Memory Section Details

MMC/SD bootmode 1st Stage Memory Section on DRA7xx

Memory Section	Size(in bytes)
.text	62700
rodata	37310
.data	5462
.bss	200188

■ MMC/SD bootmode u-boot 1st Stage (MLO) size: 106720 bytes

MMC/SD bootmode 2nd Stage Memory Section on DRA7xx

Memory Section	Size(in bytes)
.text	267424
.rodata	105836
.data	13536
.bss	324060

MMC/SD bootmode u-boot 2nd Stage (u-boot.img) size: 831664 bytes

Linux Kernel

Kernel Virtual Memory Layout (DRA75x)

The default DRA7xx kernel configuration, uses following Virtual Memory laout:

```
.....
[0.000000] Memory: 1309568K/1564672K available (6619K kernel code, 371K rwdata, 2560K rodata, 336K init, 290K bss, 25728K reserved, 229376K cma-reserved, 716800K highmem)
[0.000000] Virtual kernel memory layout:
[0.000000] vector : 0xffff0000 - 0xffff1000
[0.000000] fixmap : 0xffc00000 - 0xfff00000
                                             (3072 kB)
[0.000000]
             lowmem
                    : 0xc0000000 -
                                 0xf0000000
                                             ( 768 MB)
[0.000000
                     0xbfe00000 -
                                 0xc0000000
[0.000000]
             modules : 0xbf000000 - 0xbfe00000
                                                14 MB)
                .text : 0xc0008000
0.000000
[0.000000]
                .init : 0xc0900000
                                - 0xc0954000
                                              ( 336 kB)
                .data : 0xc0954000
                                 - 0xc09b0f50
                .bss : 0xc09b2000 - 0xc09fa840
[0.000000]
                                             ( 291 kB)
```

Kernel Virtual Memory Layout (DRA72x)

The default DRA72x kernel configuration, uses following Virtual Memory layout:

```
0.000000] Memory: 1821272K/2072576K available (6619K kernel code, 371K rwdata, 2560K rodata, 336K init, 290K bss, 30120K reserved, 221184K cma-reserved, 1224704K highmem)
          Virtual kernel memory layout:
vector : 0xffff0000 - 0xffff1000
0.000000
                                                         4 kB)
                         0xffc00000 -
                         0xf0800000 - 0xff800000
0.000000
               vmalloc :
                                                       240 MB)
0.000000
                         0xc0000000 -
                                        0xf0000000
0.000000
               pkmap
                         0xbfe00000 -
                                        0xc0000000
0.000000
                         0xbf000000 -
                                        axhfeaaaaa
                                                        14 MR
0.0000000]
                         0xc0008000 -
                                       0xc08ff044
                                                      (9181 kB)
                 .text :
                 .init
0.000000
                         0xc0900000 -
                                       0xc0954000
0xc09b0f50
                                                       336 kB)
0.000000
                         0xc0954000
0.0000001
                  .hss :
                         0xc09b2000 - 0xc09fa840
                                                      ( 291 kB)
```

Kernel Virtual Memory Layout (DRA71x)

The default DRA71x kernel configuration, uses following Virtual Memory layout:

```
[0.000000] Memory: 1821268K/2072576K available (6619K kernel code, 371K rwdata, 2560K rodata, 336K init, 290K bss, 30124K reserved, 221184K cma-reserved, 1224704K highmem)
             Memory: 1821208K/20/25/6K aVailable (t
Virtual kernel memory layout:
vector : 0xffff0000 - 0xffff1000
fixmap : 0xffc00000 - 0xfff00000
vmalloc : 0xf0800000 - 0xff800000
[0.000000]
                                                                      4 kB)
[0.000000]
10.000000
                                                                  ( 240 MB)
[0.000000]
                             : 0xc0000000 -
                                                0xf0000000
[0.000000]
                             : 0xbfe00000 -
                   pkmap
                                                0xc0000000
                                                                     2 MB)
                                                                    14 MR)
0.000000
                   modules : 0xbf000000 -
                                                axhfeaaaaa
[0.000000]
                     .text : 0xc0008000
                                                0xc08ff044
                                                                  (9181 kB)
[0.000000]
[0.000000]
                                                                   336 kB)
372 kB)
                      .init : 0xc0900000 -
                                                0xc0954000
[0.000000]
                       .hss : 0xc09h2000 - 0xc09fa840
                                                                  ( 291 kB)
```

Kernel Virtual Memory Layout (DRA76x)

The default DRA76x kernel configuration, uses following Virtual Memory layout:

```
[ 0.000000] Memory: 3896972K/4174848K available (6611K kernel code, 319K rwdata, 2452K rodata, 340K init, 290K bss, 48500K reserved, 229376K cma-reserved, 3322880K highmem)
[ 0.000000] Virtual kernel memory layout:
[ 0.000000] vector : 0xffff0000 - 0xffff1000 ( 4 kB)
[ 0.000000] fixmap : 0xffc00000 - 0xfff00000 (3072 kB)
[ 0.000000] vmalloc : 0xf0800000 - 0xff800000 ( 240 MB)
```

```
0.000000
                          0xc0000000
                                         0xf0000000
               pkmap
modules
9 999999
                          0xbfe00000
                                         0xc0000000
0.000000
                                         0xbfe00000
                          0xbf000000
                  .text : .init :
0.000000
                          0xc0008000
                                         0xc08e202c
                                                        (9065 kB)
0.000000
                  .data :
                          0xc0938000 -
                                         0xc0987ce0
                                                         320 kB)
0.000000]
                  .bss : 0xc0989000 -
                                         0xc09d1800
```

Carveout size and location

Below table lists the size and memory of areas that are set aside from the Linux memory map for use by remotecores. This information is taken from \$PSDKLA/board-support/linux/arch/arm/boot/dts/dra7-evm.dts.

Remotecore	Start Address	Carveout size(MB)
IPU2	0x95800000	56
DSP1	0x99000000	64
IPU1	0x9d000000	32
DSP2(only DRA75X)	0x9f000000	8

There is also an additional carveout set aside for use by the CMEM allocator. This memory region can be used to transfer data between remotecores and MPU without doing a data copy. This information is taken from \$PSDKLA/board-support/linux/arch/arm/boot/dts/dra7xx-jamr3.dtsi.

Purpose	Start Address	Carveout size(MB)
CMEM	0x95400000	4

Linux Kernel Drivers

This section provides brief overview of the device drivers supported in the Linux Kernel of the release package.

Device Driver List

The following table list the various device drivers supported and the device they are supported on. On detailed information on specific features or limitations of a pariticular driver, refer to the chapter catering to that driver in this document.

Peripheral Driver Support

Peripheral	Description	Linux driver type	DMA usage
Audio (McASP)	Audio Record and Playback	ALSA SoC	sDMA / eDMA
Ethernet	Ethernet Network driver	Netdev	Internal DMA
USB1 DWC3(DRD)-SS/HS/FS/LS	DWC3 Device & xhci host controller driver	USB HCD/DCD	USB Internal DMA
USB2 DWC3(DRD)-HS/FS/LS	DWC3 Device & xhci host controller driver	USB HCD/DCD	USB Internal DMA
QSPI Flash/Controller Driver	Flash storage system	MTD Block	EDMA(for read)
eMMC/SD/MMC	Interface to MultiMedia Secure Digital cards	Block	SDMA
UART	Serial Communication Interface	Character	Supported
I2C	Inter-IC Communication	Character	Not Supported
DSS	Display Subsystem driver	Platform driver	Internal DMA
VIP	Video IP driver	V4L2 Capture	VPDMA
VPE	Video Processing Engine driver	V4L2 Mem to Mem	VPDMA
CPUFreq	Supports multiple SoC operating levels for MPU(OPPs)	NA	None
RTC	Realtime clock	Character	None

ALSA SoC Audio Driver

This section an overview of the ALSA SoC audio driver features along with the throughput and CPU load numbers.

Introduction

DRA7xx Audio driver complies to the Advanced Linux Sound Architecture (ALSA) System on Chip (SoC) framework (ASoC).

The ASoC framework splits an embedded audio system into three components:

- Codec driver: The codec driver is generic and hardware independent code that configures the audio codec to provide audio capture and playback. It should contain no code that is specific to the target platform or machine.
- Platform driver: The platform driver can be divided into audio DMA and SoC Digital Audio Interface (DAI) configuration and control. The platform driver only targets the SoC CPU and must have no board specific code.
- Machine driver: The ASoC machine (or board) driver is the code that glues together the platform and codec drivers. It can contain codec and platform specific code. It registers the audio subsystem with the kernel as a platform device.

Driver Features

The driver supports the following features:

- 1. Supports AIC3106 audio codec in ALSA SoC framework.
- 2. Sample rate support 44.1kHz for both capture and playback.
- 3. Supports audio in stereo mode
- 4. Supports simultaneous playback and record (full-duplex mode).
- 5. Supports mixer interface for the audio codec

Features Not Supported

- 1. OSS based applications, which use ALSA-OSS emulation layer, are not supported.
- 2. Synthesizer and midi interfaces are not supported.

Constraints

Supported System Calls

Refer ALSA project - the C library reference [1] (http://www.alsa-project.org/alsa-doc/alsa-lib/) for API calls.

Performance and Benchmarks

- 1. Access type RW_INTERLEAVED
- 2. Channels 2
- 3. Format S16 LE
- 4. Period size 64

ALSA Playback performance

	Processor SDK Linux Automotive 3.04									
	DRA7	1x	DRA72x		DRA74x		DRA76x			
Sampling Rate (bytes)	Throughput (bits /sec)	CPU Load (%)	Throughput (bits/sec)	CPU Load (%)	Throughput (bits/sec)	CPU Load (%)	Throughput (bits/sec)	CPU Load (%)		
8000	352800.0	0.32	352790.0	0.26	352793.0	0.08	352800.0	0.12		
11025	352800.0	0.28	352790.0	0.25	352793.0	0.1	352800.0	0.13		
16000	352800.0	0.28	352790.0	0.27	352793.0	0.08	352800.0	0.14		
22050	705599.0	0.45	705580.0	0.37	705586.0	0.15	705599.0	0.21		
24000	705599.0	0.49	705580.0	0.5	705586.0	0.13	705599.0	0.16		
32000	705599.0	0.47	705580.0	0.37	705586.0	0.15	705599.0	0.18		
44100	1411198.0	0.85	1411160.0	0.6	1411172.0	0.26	1411198.0	0.29		
48000	1411198.0	0.87	1411160.0	0.6	1411172.0	0.31	1411198.0	0.3		
88200	2822393.0	1.77	2822318.0	1.14	2822342.0	0.55	2822394.0	0.67		
96000	2822393.0	1.46	2822318.0	1.07	2822342.0	0.53	2822394.0	0.62		

ALSA Playback performance

Sampling Rate (bytes)	Processor SDK Linux Automotive 3.04								
	DRA71x		DRA72x		DRA74x		DRA76x		
	Throughput (bits /sec)	CPU Load (%)	Throughput (bits/sec)	CPU Load (%)	Throughput (bits/sec)	CPU Load (%)	Throughput (bits/sec)	CPU Load (%)	
8000	352942.0	0.3	352933.0	0.19	352935.0	0.08	352942.0	0.12	

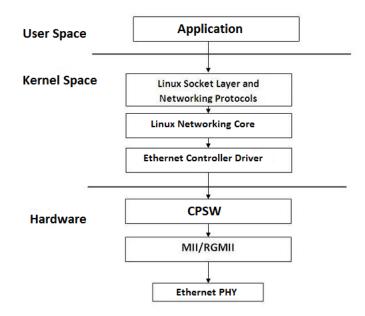
11025	352942.0	0.3	352933.0	1.62	352935.0	0.06	352942.0	0.12
16000	352942.0	0.25	352932.0	0.16	352935.0	0.07	352942.0	0.1
22050	705884.0	0.4	705865.0	0.29	705871.0	0.15	705884.0	0.16
24000	705884.0	0.48	705865.0	0.33	705871.0	0.11	705884.0	0.17
32000	705884.0	0.43	705865.0	0.35	705871.0	0.16	705884.0	0.17
44100	1411767.0	0.78	1411729.0	0.52	1411741.0	0.21	1411767.0	0.31
48000	1411767.0	0.67	1411729.0	0.7	1411741.0	0.2	1411767.0	0.28
88200	2823531.0	1.36	2823457.0	1.1	2823481.0	0.41	2823533.0	0.43
96000	2823531.5	1.39	2823457.0	1.28	2823481.0	0.43	2823533.0	0.67

Ethernet Driver

This section provides an overview of the Ethernet driver features along with throughput and CPU load numbers. Ethernet driver follows standard Linux network interface architecture.

Introduction

The Ethernet driver supports the Linux netdev interface.



Driver Features

The driver supports the following features:

- 1. 10/100/1000 Mbps mode of operation.
- 2. Auto negotiation.
- 3. Full duplex and half duplex mode of operation.
- 4. Linux NAPI support
- 5. Support for MII and RGMII interfaces to PHY
- 6. Operation of both external ports as independent network interfaces on DRA75x

* Enable CONFIG_ETHERNET through menuconfig (Menu Config->Device Drivers->Network device support & Menu config-> Networking support)

Features Not Supported

On DRA72x only the first port instance on the EVM base board is supported. The second port instance is not supported

Supported System Calls

Supports the socket() and related system calls in accordance with Linux architecture.

Performance and Benchmarks

Setup: Device under test connected to Linux PC through gigabit switch.

DRA75x		DRA72x		DRA71x		
Revision Frequency		Revision	Frequency	Revision	Frequency	
DRA752 ES2.0 Rev-G3	@1.5Gh	DRA722-GP ES2.0 Rev-C	@1.5Gh	DRA71 EVM ES2.0 REV A.1	@1Gh	

TCP Performance

Ethernet performance table

	Processor SDK Linux Automotive 3.04											
		DRA71x				DRA72x				DRA74x		
TCP Window Size(Kbytes)	Bandwidth (without interrupt pacing, in Mbits/sec)	CPU Load (without interrupt pacing, in %)	Bandwidth (with interrupt pacing, in Mbits/sec)	CPU Load (with interrupt pacing, in %)	Bandwidth (without interrupt pacing, in Mbits/sec)	CPU Load (without interrupt pacing, in %)	Bandwidth (with interrupt pacing, in Mbits/sec)	CPU Load (with interrupt pacing, in %)	Bandwidth (without interrupt pacing, in Mbits/sec)	CPU Load (without interrupt pacing, in %)	Bandwidth (with interrupt pacing, in Mbits/sec)	CPU Load (with interrupt pacing, in %)
8	274.4	77.48	268.8	62.12	292.8	61.19	278.4	51.65	352.0	49.53	380.0	55.09
16	362.4	99.91	279.76	100.0	434.4	84.37	548.8	89.12	507.2	63.69	656.0	80.54
32	389.6	99.96	312.48	99.98	613.6	99.98	666.4	99.44	378.4	50.14	867.2	93.57
64	388.0	99.98	334.4	99.98	632.0	100.0	739.2	99.8	384.0	50.29	948.8	97.62
128	363.2	100.0	384.8	100.0	600.0	100.0	772.0	99.87	791.2	84.68	1006.4	98.64
256	388.8	100.0	472.0	99.95	635.2	100.0	848.0	98.54	390.4	50.57	784.0	68.24

Note: Throughput reported is cumulative throughput of Tx+Rx collected from concurrent bi-directional test

The performance numbers were captured using the iperf tool. Usage details are mentioned below:

- iperf version 2.0.5
- On PC Host invoke iperf in the server mode.

On the DUT iperf is invoked in client mode (bi-directional traffic for 60 seconds).

iperf -c <server ip> -w <window size> -d -t 60

Interrupt pacing feature enabled with pacing interval set to 125usecs.

ethtool -C eth0 rx-usecs 125

DUT is connected to a gigabit network.

OMAPDRM/OMAPDSS (Display Subsystem Driver)

Introduction

The OMAPDRM internally uses OMAPDSS driver interface for configuration of panel drivers and the encoder interface(DPI/HDMI).

Menuconfig Option

Enable CONFIG DRM OMAP through (Menuconfig->Device Drivers->Graphics support)

. Enable CONFIG OMAP2 DSS DRA7XX DPI, CONFIG OMAP5 DSS HDMI, CONFIG OMAP5 DSS HDMI DDC through (Menuconfig->Device Drivers->Graphics support->OMAP2+ Display Subsystem support)

Enable CONFIG PANEL TFCS9700 through (Menuconfig->Device Drivers->Graphics support->OMAP2+ Display Subsystem support->OMAP2/3 Display Device Drivers)

Source Location

omapdss

drivers/video/fbdev/omap2/dss/

display drivers

drivers/video/fbdev/omap2/displays-new

omapdrm

drivers/gpu/drm/omapdrm/

Driver Features

OMAPDRM Display controller (DISPC)

DRM Plane Features:

- One Graphics (GFX) and Three Video pipelines (VID1, VID2, and VID3)
- Z-order, Alpha blending (Global, pre-multipled), Scaler and CSC

DRM CRTC Features:

- One TV and three LCD Overlay Managers
- Supports 1080p at 60Hz for all CRTCs

OMAPDRM Interfaces

HDMI Interface

- HDMI protocol engine
- HDMI 1.4 support

RGB Interface

Supports 24bit LCD Fixed Resolution Panels

Features Not Supported

- Rotation/Tiler 2D
- Default BG color, Transparency and color Keys

Constraints

- Number of CRTCs must be passed either through bootargs or kernel config, which limits number of free DRM planes.
- When DSS Writeback pipeline is used to perform scaling, some formats have limitations on scaling ratios as shown below.

Format	Max Horz. Downscale	Max Vert Downscale
YUYV	2	4
UYVY	2	4
NV12	2	2

Supported System Calls

All libdrm APIs are supported.

QSPI Driver

Introduction

This chapter describes the QSPI platform driver & flash driver features and performance numbers (throughput and CPU load).

QSPI Platform driver feature

QSPI is a serial driver. Supports 4-Pin single read, 4-Pin single write & 6-Pin quad read. It implements only SPI_CORE mode & no support for memory mapped interface. Clock phase & polarity configured to mode-3 & functional clock programmed at 48MHz. There is no support for DMA data transfer.

The pointer to TI qspi hardware driver is drivers/spi/spi-ti-qspi.c

* Enable CONFIG_SPI_TI_QSPI through menuconfig (Menuconfig->Device Drivers->SPI support->DRA7xxx QSPI controller support)

QSPI Flash driver feature

Spansioin S25FL256S serial flash used on DRA7xx evm. The property of the flash are

- 256 Mbits (32 Mbytes)
- 256 or 512 Byte Page Programming buffer options

- 64KB erase sector size
- Normal, Fast, Dual & Quad

Linux mtd m25p80 used as serial flash device driver for s25FL256S. The driver layer exports API for device info read, sector erase, chip erase, data read & write. It creates the device node for user space access (example, /dev/mtd0)

The pointer to mtd m25p8o flash device driver is drivers/mtd/devices/m25p8o.c

* Enable CONFIG_MTD_M25P80 through menuconfig (Menuconfig->Device Drivers->Memory Technology Device(MTD) support ->Self-contained
MTD device drivers->Support most SPI Flash chips)

JFFS2 Filesystem Support

QSPI flash driver is mtd based block driver. Support to mount JFFS2 filesystem on /dev/mtdo. Validated to mount JFFS2 filesystem & performed basic file IO operations.

There is an exception on remounting the filesystem. It is known limitation in this release.

Erase the flash to mount JFF52 filesystem

\$flash_eraseall -j /dev/mtd0

Mount the serial flash
\$mount -t jffs2 /dev/mtdblock01 /mnt/nor

Create a new file
\$echo NewFileCreated > /mnt/nor/testfile.txt

Read the file
\$cat /mnt/nor/testfile.txt

Delete the file
\$rm /mnt/nor/testfile.txt

Performance Benchmark

Not available for this release.

MMC/SD Driver

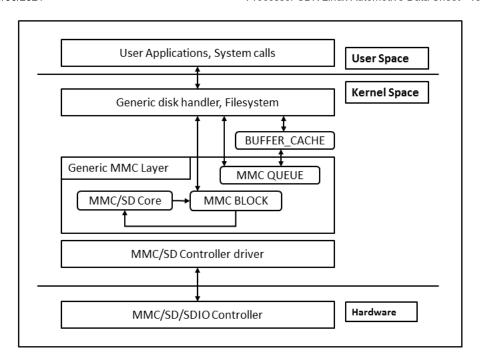
This chapter provides details on MMC/SD driver along with throughput and CPU load numbers.

Introduction

The MMC controller provides an interface to external MMC cards. The MMC driver is implemented as a block driver. Block device nodes(such as /dev/mmcblockp1, /dev/mmcblockp2) are created for user space access.

Compliance with standards:

Full compliance with SD command/response sets as defined in the SD Physical Layer specification v3.01
Full compliance with SD Host Controller Standard Specification sets as defined in the SD card specification Part A2 v3.00
Full compliance with MMC/eMMC command/response sets as defined in the JC64 MMC/eMMC standard specification, v4.5.



Driver Features

The driver supports the following features:

- 1. MMC/SD native protocol command/response set
- 2. Single/multiple block data transfers
- 3. Linux file system and generic MMC layer abstract details of block devices (MMC)
- 4. High-speed (SDv1.1) and High Capacity (SDv2.0) cards
- 5. Support for 4 bit modes
- 6. Support for card detect and Write protect features
- 7. DMA and polled mode for data transfer operations

Features Not Supported

- 1. SPI mode of operation
- 2. PIO mode of operation
- 3. Write protection is not supported on the J6 EVM

Constraints

1. MMC/SD cards should not be removed when the card is mounted. If done so, data integrity cannot be guaranteed.

Supported System Calls

open(),close(),read(),write()

Performance and Benchmarks

IMPORTANT

The performance numbers can be severely affected if the media is mounted in sync mode. Hot plug scripts in the filesystem mount removable media in sync mode to ensure data integrity. For performance sensitive applications, umount the auto-mounted filesystem and re-mount in async mode.

*Note: On DRA6x-EVM, UHS mode is not supported hence the card is used in high speed mode Refer to release notes for defect details.

EXT4 file system

MMC-SD EXT4 write Performance

		Processor SDK Linux Automotive 3.04									
	DRA7	DRA71x		DRA72x		4x	DRA76x				
Buffer size (bytes)	Write Throughput (Mbytes/sec)	Write CPU Load (%)	Write Throughput (Mbytes/sec)	Write CPU Load (%)	Write Throughput (Mbytes/sec)	Write CPU Load (%)	Write Throughput (Mbytes/sec)	Write CPU Load (%)			

102400	40.7	36.69	46.2	29.65	42.27	12.79	20.58	5.94
262144	40.94	38.19	54.99	35.08	41.25	14.48	20.11	5.65
524288	41.03	37.85	60.29	37.57	42.78	16.37	19.98	6.48
1048576	40.55	38.28	57.79	35.96	42.53	17.12	20.33	6.82
5242880	40.83	38.67	54.74	33.69	42.81	15.7	20.46	5.18

MMC-SD EXT4 read Performance

			Process	inux Automotive	ux Automotive 3.04				
	DRA7	DRA71x		DRA72x		4x	DRA76x		
Buffer size (bytes)	Read Throughput (Mbytes/sec)	Read CPU Load (%)	Read Throughput (Mbytes/sec)	Read CPU Load (%)	Read Throughput (Mbytes/sec)	Read CPU Load (%)	Read Throughput (Mbytes/sec)	Read CPU Load (%)	
102400	75.85	21.21	70.55	14.58	75.32	9.85	22.0	3.09	
262144	75.28	23.13	70.71	15.75	76.16	9.56	21.95	2.88	
524288	75.21	26.09	70.28	14.58	76.16	10.95	22.09	2.99	
1048576	75.99	19.84	70.52	18.12	75.8	48.7	22.05	2.99	
5242880	74.81	25.55	70.57	14.79	76.33	11.15	22.03	2.88	

The performance numbers were captured using the following:

- SD Card Sandisk Ultra 16G Class 10 [UHS-1] SDHC card
- File System: ext4
- Partition was mounted with async option

VFAT file system

MMC-SD VFAT write Performance

		Processor SDK Linux Automotive 3.04								
	DRA7	DRA71x		DRA72x		4x	DRA76x			
Buffer size (bytes)	Write Throughput (Mbytes/sec)	Write CPU Load (%)	Write Throughput (Mbytes/sec)	Write CPU Load (%)	Write Throughput (Mbytes/sec)	Write CPU Load (%)	Write Throughput (Mbytes/sec)	Write CPU Load (%)		
102400	30.79	31.66	26.61	21.28	32.16	41.64	17.7	7.21		
262144	31.04	31.95	43.34	34.3	32.91	13.74	18.42	7.07		
524288	31.33	32.54	48.74	36.79	32.64	13.82	18.52	7.26		
1048576	31.35	31.71	45.35	33.92	33.14	14.15	19.06	6.94		
5242880	31.34	31.12	43.85	33.33	32.73	13.17	18.51	8.05		

MMC-SD VFAT read Performance

Read Read Read Read CPU Load (%) Read Throughput (Mbytes/sec) Read CPU Load (%) Read Throughput (Mbytes/sec) Read CPU Load (%) Read Throughput (Mbytes/sec) Read CPU Load (%) Read CPU Load (%) Read Throughput (Mbytes/sec) Read CPU Load (%) CPU Load (%) Read CPU Load (%) CPU				IIVIO-OD V	I AT TEAU T CITO	mance					
Read Throughput (Mbytes/sec) Read CPU Load (%) Read Throughput (Mbytes/sec) Read Throughput (Mbytes/sec) Read CPU Load (%) Read Throughput (Mbytes/sec) Read				Processor SDK Linux Automotive 3.04							
Read Throughput (Mbytes/sec) CPU Load (%) Read Throughput (Mbytes/sec)			DRA7	DRA71x		DRA72x		4x	DRA7	6x	
262144 73.68 24.09 65.07 17.61 72.89 10.92 21.02 524288 74.07 26.95 64.49 18.52 71.75 10.45 20.79 1048576 72.56 24.29 65.34 15.03 72.14 11.15 21.12	Buffer size	e (bytes)	Throughput	CPU Load	Throughput	CPU Load	Throughput	CPU Load	Read Throughput (Mbytes/sec)	Read CPU Load (%)	
524288 74.07 26.95 64.49 18.52 71.75 10.45 20.79 1048576 72.56 24.29 65.34 15.03 72.14 11.15 21.12	1024	.00	73.96	24.46	65.39	12.67	70.27	33.22	21.0	3.06	
1048576 72.56 24.29 65.34 15.03 72.14 11.15 21.12	2621	44	73.68	24.09	65.07	17.61	72.89	10.92	21.02	2.77	
	5242	88	74.07	26.95	64.49	18.52	71.75	10.45	20.79	3.53	
52/2000 72.60 27.14 66.06 16.0 71.42 11.20 21.15	1048	576	72.56	24.29	65.34	15.03	72.14	11.15	21.12	2.98	
5242000 12.09 21.14 00.00 10.0 11.45 11.30 21.15	52428	880	72.69	27.14	66.06	16.0	71.43	11.38	21.15	2.88	

EMMC Performance and Benchmarks

IMPORTANT

The performance numbers can be severely affected if the media is mounted in sync mode. Hot plug scripts in the filesystem mount removable media in sync mode to ensure data integrity. For performance sensitive applications, umount the auto-mounted filesystem and re-mount in async mode.

VFAT file system

EMMC VFAT write Performance

		PSDKLA_3.04										
	DRA7	1x	x DRA72x		DRA74x		DRA7	6x				
Buffer size (bytes)	Write Throughput (Mbytes/sec)	Write CPU Load (%)	Write Throughput (Mbytes/sec)	Write CPU Load (%)	Write Throughput (Mbytes/sec)	Write CPU Load (%)	Write Throughput (Mbytes/sec)	Write CPU Load (%)				
102400	10.74	11.41	10.89	7.87	12.14	5.07	11.75	4.49				
262144	10.72	12.05	11.27	8.34	12.2	5.85	11.79	5.34				
524288	10.72	12.14	11.75	7.87	11.79	5.05	11.62	4.39				
1048576	10.72	12.14	11.74	8.49	12.08	5.03	11.79	4.58				
5242880	10.75	12.08	11.79	8.52	12.19	5.26	11.79	4.69				

EMMC VFAT read Performance

			. , oaa . oo							
		PSDKLA_3.04								
	DRA7	1x	DRA72x		DRA74x		DRA7	6x		
Buffer size (bytes)	Read Throughput (Mbytes/sec)	Read CPU Load (%)	Read Throughput (Mbytes/sec)	Read CPU Load (%)	Read Throughput (Mbytes/sec)	Read CPU Load (%)	Read Throughput (Mbytes/sec)	Read CPU Load (%)		
102400	92.75	31.07	105.64	24.47	95.2	14.42	94.44	13.82		
262144	92.87	37.61	106.5	26.04	96.11	14.95	93.12	13.96		
524288	92.92	38.05	105.88	29.29	98.8	16.36	93.64	14.22		
1048576	92.77	34.86	105.73	29.17	97.19	16.04	90.14	13.66		
5242880	92.95	35.19	105.71	23.6	97.24	13.04	94.28	12.62		

The performance numbers were captured using the following:

- File System: vfat
- Partition was mounted with async option

EXT4 file system

EMMC EXT4 write Performance

		PSDKLA_3.04							
	DRA7	1x	DRA72x		DRA7	4x	DRA76x		
Buffer size (bytes)	Write Throughput (Mbytes/sec)	Write CPU Load (%)	Write Throughput (Mbytes/sec)	Write CPU Load (%)	Write Throughput (Mbytes/sec)	Write CPU Load (%)	Write Throughput (Mbytes/sec)	Write CPU Load (%)	
102400	11.19	10.21	12.16	6.44	12.62	4.19	12.26	3.76	
262144	12.03	11.29	12.21	7.67	12.66	3.91	12.28	3.64	
524288	12.06	10.45	12.23	6.47	12.49	4.14	12.27	3.3	
1048576	12.1	10.58	12.27	7.83	12.0	3.53	12.48	4.11	
5242880	12.06	10.33	12.22	6.58	12.64	4.08	12.5	3.89	

EMMC EXT4 read Performance

		PSDKLA_3.04								
	DRA7	DRA71x		DRA72x		DRA74x		6x		
Buffer size (bytes)	Read Throughput (Mbytes/sec)	Read CPU Load (%)	Read Throughput (Mbytes/sec)	Read CPU Load (%)	Read Throughput (Mbytes/sec)	Read CPU Load (%)	Read Throughput (Mbytes/sec)	Read CPU Load (%)		
102400	98.36	25.0	85.18	18.33	98.68	14.22	86.08	9.83		
262144	98.29	28.71	97.44	23.58	83.92	12.5	99.22	12.92		
524288	84.58	24.14	84.79	21.95	97.73	12.21	99.36	14.29		
1048576	84.35	26.05	97.61	22.33	97.9	11.9	87.08	10.87		
5242880	84.57	26.27	85.12	21.67	98.91	12.25	99.63	14.08		

The performance numbers were captured using the following:

■ File System: ext4

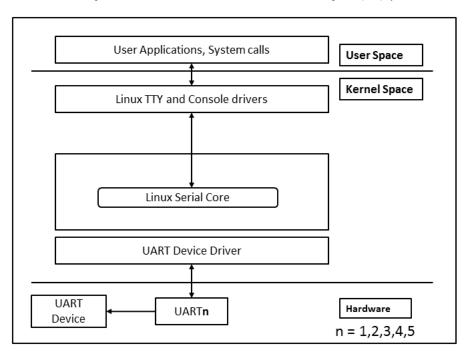
Partition was mounted with async option

UART Driver

This chapter provides details on UART driver.

Introduction

The UART driver is implemented as a serial driver, and can be accessed from user space as /dev/ttyOX(X=0-5)



Driver Features

Both Peripheral mode and DMA mode are supported

Features Not Supported

- Hardware Flow Control due to board limitation
- UART DMA mode supported but not validated at baud rates greater than 115200 due to HW limitation mentioned above (Flow control).
- Baud rate of 12 Mbps was not validated.

Supported System Calls

open(),close(),read(),write(),ioctl()

Supported IOCTLs

Ì	Constant	Description
	TIOCGSERIAL	Gets device parameters from the UART (example, port type, port num, baud rate, base divisor, and so on.
	TIOCSSERIAL	Sets UART device parameters (example, port type, port num, baud rate, base divisor, and so on)

Performance and Benchmarks

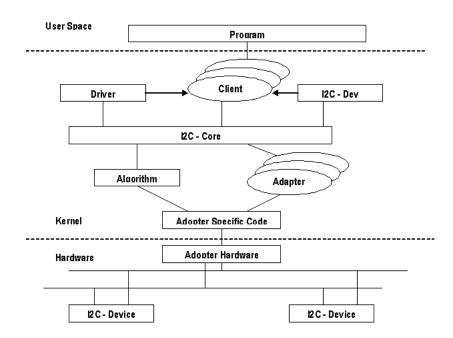
Performance and Benchmarks not available in this release.

I2C Driver

This chapter provides details on I2C driver.

Introduction

The I2C peripheral is compliant with the Philips Semiconductor I2C-bus specification version 2.1. The I2C driver is implemented as a serial driver. The I2C driver can be accessed from the user space as /dev/i2c/o.



Driver Features

The driver supports the following features:

- 1. 7-bit addressing mode
- 2. Fast mode
- 3. Interrupt mode

Features Not Supported

- 1. 7-bit and 10-bit addressing combined format is not supported
- 2. DMA mode is not supported

Supported System Calls

open(),close(),read(),write(),ioctl()

Supported IOCTLs

Constant	Description					
I2C_SLAVE_FORCE	Changes slave address. Slave address is 7 or 10 bits. This changes the address, even if it is already considered.					
I2C_FUNCS	Gets the adapter functionality					
I2C_RDWR	Combined R/W transfer (one stop only)					

Performance and Benchmarks

Performance and Benchmarks not available in this release.

VIP Driver

Introduction

The Video Input Port (VIP) is a V4L2 based video capture driver.

Driver Features

- V4L2 Single planar ioctls supported.
- Supports MMAP and DMABUF buffering methods
- Inline Scaling support
- Multi instance capture support
- Simultaneous capture from multiple ports
- Configurable video interfaces via endpoint nodes in DT
- Supports descrete/embedded sync, 8/16/24 bit bus, YUYV and RGB format cameras
- Capture upto 60 fields/frames per second
- · Selection of muxed cameras through device tree
- Multi channel CVBS camera capture

Features Not Supported

Following features are not supported at this point of time.

- Inline Color Space Conversion support
- Multi planar buffer support
- Runtime selection of cameras
- Media controller framework

Supported System Calls

- Standard V4L2 streaming ioctls
- Format negotiation with subdevice
- Frame size enumration ioctls
- · Control ioctls as implemented by subdev
- No custom ioctls needed

Performance Benchmarks

The following performance benchmarks were measured on DRA7xx

- IRQ latency
 - The average IRQ latency of the interrupts to the VIP driver is measured as the time difference between a VPDMA list post and VIP ISR callback
 - A zero sized list post would generate IRQ immediately
 - When measured across 1002 samples, the average interrupt latency is 15.94 us
 - Peak IRQ latency is 138 us
 - For all the following latencies, IRQ latency is not considered
- Capture latency
 - average capture latency is the time taken by the driver to make the buffer available for the userspace
 - It is calculated as the time difference between the IRQ and the time where DQBUF ioctl returns
 - This would vary based on the size of the captured buffer
- Capture display latency
 - Average capture display latency is the time difference between the time a buffer was captured and the time when it was given for display
 - This is the total latency between end of the capture frame and start of display frame

Following table shows latencies for different capture sizes with around 10000 frames

Capture display performance on DRA7xx

Capture size	Capture latency (J6)	Capture latency (J6Eco)	Capture latency (J6Entry)
720x240 60fps (Analog decoder TVP5158)	48us	51us	102us
1280x720 30fps (Digital OV camera)	59us	65us	116us

- multi instance capture latency
 - Following table shows latencies for for multi instance capture scenario
 - Here, five different VIP ports are used to capture from LVDS cameras
 - All the captures are at 1280x720 YUYV format at 30fps

VIP driver Capture latency multi-instance

vir driver capture latericy multi-mistance									
Capture thread	Average capture latency								
LVDS cam1	35us								
LVDS cam2	32us								

LVDS cam3	51us
LVDS cam4	36us

CAL Driver

Introduction

The Camera Adaptor Layer (CAL) is a V4L2 based video capture driver used with CSI cameras.

Driver Features

- V4L2 Single planar ioctls supported.
- Supports MMAP and DMABUF buffering methods
- Simultaneous capture from two phy0(4lane) and phy1(2lane)
- Configurable video interfaces via endpoint nodes in DT Supports CSI bindings

Features Not Supported

Following features are not supported at this point of time.

- Multi planar buffer support
- Media controller framework
- Multi channel capture from muxed CSI input

Supported System Calls

- Standard V4L2 Capture ioctls
- No custom ioctls needed

Performance Benchmarks

The following performance benchmarks were measured on DRA7xx

Following table shows latencies using CSI video capture with around 10000 frames

Capture display performance on DRA7xx

Capture size	Capture latency (J6eco)
1280x720 30fps (4 lane CSI capture)	78us

VPE Driver

Introduction

 $Video\ processing\ Engine (VPE)\ is\ a\ V4L2\ Mem\ to\ Mem\ driver.\ It\ supports\ video\ operations\ such\ as\ scaling,\ colour\ space\ conversion\ and\ deinterlacing.$

Driver Features

Video processing Engine(VPE) supports following formats for scaling, csc and deinterlacing:

- Supported Input formats: NV12, YUYV, UYVY
- Supported Output formats: NV12, YUYV, UYVY, RGB24, BGR24, ARGB24, ABGR24
- Inline Scaling supports
- Horizontal up-scaling up to 8x and Downscaling up to 4x using Pre-decimation filter.
- Vertical up-scaling up to 8x and Polyphase down-scaling up to 4x followed by RAV scaling.
- V4L2 M2M Multiplanar ioctl() supported.
- Multiple V4L2 device context supported.

Features Not Supported

- Following formats are not supported: YUV444, YVYU, VYUY, NV16, NV61, NV21, 16bit and Lower RGB formats are not supported.
- Passing of custom scaler and CSC coeffficients through user spcase are not supported.

- Only Linear scaling is supported without peaking and trimming.
- Deinterlacer does not support film mode detection.

Constraints

VPE functional clock is restricted to 266Mhz due to HW constraints.

Supported System Calls

Standard v4l2 m2m ioctls

Performance benchmarks

- Frames per second (FPS)
 - FPS is the total number of frames processed by VPE per second
 - FPS for a mem2mem device like VPE depends on the size of the data that is being processed.
 - As VPE performs deinterlacing, scaling, color space conversion on the fly, FPS value for any of these combination should be same.
 - Following tables shows the fps values for multiple operations measured when VPE is running at 266Mhz

J6 VPE performance measures

Operation	Time for 1000 frames	Frames per second	Hardware utilization
DEI 1920 540 yuyv to 1920 1080 yuyv 1	7.93 s	126.10	98.30%
DEI + SC 1920 540 yuyv to 1280 720 yuyv 1	7.93 s	126.10	98.30%
DEI + SC + CSC 1920 540 yuyv to 1280 720 rgb24 1	7.94 s	125.94	98.17%
SC 1280 720 yuyv to 1920 1080 yuyv 0	7.89 s	126.74	98.80%
CSC 1920 1080 yuyv to 1920 1080 rgb24 0	7.92 s	126.26	98.42%
CSC + SC 320 240 yuyv to 640 480 nv12 0	1.20 s	833.33	96.24%
DEI + SC 720 240 nv12 to 1280 720 yuyv 1	3.56 s	280.89	97.31%
DEI + CSC 720 240 yuyv to 720 480 yuyv 1	1.36 s	735.29	95.53%

J6eco VPE performance measures

Operation	Time for 1000 frames	Frames per second	Hardware utilization
DEI 1920 540 yuyv to 1920 1080 yuyv 1	7.94 s	125.94	98.17%
SC 1280 720 yuyv to 1920 1080 yuyv 0	7.89 s	126.74	98.80%
CSC 1920 1080 yuyv to 1920 1080 rgb24 0	7.92 s	126.26	98.42%
CSC + SC 320 240 yuyv to 640 480 nv12 0	1.20 s	833.33	96.24%
DEI + SC 720 240 nv12 to 1280 720 yuyv 1	3.56 s	280.89	97.31%
DEI + CSC 720 240 yuyv to 720 480 yuyv 1	1.37 s	729.92	94.83%

J6entry VPE performance measures

Joently VF L performance measures										
Operation	Time for 1000 frames	Hardware utilization								
DEI 1920 540 yuyv to 1920 1080 yuyv 1	7.95 s	125.78	98.05%							
SC 1280 720 yuyv to 1920 1080 yuyv 0	7.90 s	126.58	98.67%							
CSC 1920 1080 yuyv to 1920 1080 rgb24 0	7.93 s	126.10	98.30%							
CSC + SC 320 240 yuyv to 640 480 nv12 0	1.21 s	826.44	95.44%							

DEI + SC 720 240 nv12 to 1280 720 yuyv 1	3.56 s	280.89	97.31%
DEI + CSC 720 240 yuyv to 720 480 yuyv 1	1.37 s	729.92	94.83%

J6Plus VPE performance measures

Operation	Time for 1000 frames	Frames per second	Hardware utilization
DEI 1920 540 yuyv to 1920 1080 yuyv 1	7.92 s	126.26	98.42%
SC 1280 720 yuyv to 1920 1080 yuyv 0	7.89 s	126.74	98.80%
CSC 1920 1080 yuyv to 1920 1080 rgb24 0	7.91 s	126.42	98.55%
CSC + SC 320 240 yuyv to 640 480 nv12 0	1.20 s	833.33	96.24%
DEI + SC 720 240 nv12 to 1280 720 yuyv 1	3.55 s	281.69	97.59%
DEI + CSC 720 240 yuyv to 720 480 yuyv 1	1.37 s	729.92	94.83%

USB Driver

This section gives an overview of the USB DWC3(XHCI) controller driver features supported/not supported, constraints and performance numbers.

DWC3(XHCI) USB controller

The DWC3 (XHCI) based controller supports following features

- USB1: SuperSpeed (SS) USB 3.0 Dual-Role-Device (DRD) subsystem with integrated SS (USB3.0) PHY and HS/FS (USB2.0) PHY
- USB2: High-Speed (HS) USB 2.0 Dual-Role-Device (DRD) subsystem with integrated HS/FS PHY

Features Not Supported

OTG support (HNP/SRP)

Features Supported

- USB Host mode.
- USB Peripheral mode
- USB DRD mode (Dual Role Device)

USB Configuration

For USB configuration selection please refer to USB General Guide Linux (http://processors.wiki.ti.com/index.php/USB_General_Guide_Linux_v3.8#Linux_USB_Stack_Architecture)

Driver Features

The driver supports the following features

DRD (Dual Role Device) support

The DRD (Dual role device) support enable the each instance of controller to configure either as "Host" or "Device" mode. Refer to User's Guide for more details how to configure the controller into DRD mode.

Host mode support

Host Mode

Host Mode Feature	Supported
HUB class support	Yes
Human Interface Class (HID)	Yes
Mass Storage Class (MSC)	Yes
USB Video Class (UVC)	Yes
USB Audio Class (UAC)	Yes

USB Mass Storage Class Host Driver

Constraint

None

Supported System Calls

open(), close(), read(), write(), ioctl()

Supported IOCTLS

None

Performance Benchmarks

Setup: Western Digital Ultra Superspeed HDD (500GB) connected to usb1 or usb2 port. SS - SuperSpeed, HS - Highspeed.

Note: The performance number is limited by the USB HDD used. The high performance device (SSD based USB3.0) would give better performance numbers.

USB - ext2 File System Performance

USB EXT2 write Performance

	3.04												
		DRA75x DRA72x					DRA	\71x					
Buffer	USB1 S	S	USB2 H	S	USB1 SS		USB2 H	S	USB1 S	S	USB2 HS		USB1
size (bytes)	Write Throughput (Mbytes/sec)	Write CPU Load (%)	Write Throughput (Mbytes/sec										
102400	35.62	14.78	32.78	12.78	35.65	29.27	32.91	27.51	34.64	35.22	32.03	31.56	34.53
262144	74.27	28.68	34.17	13.04	72.02	59.31	33.55	27.42	70.93	71.23	32.65	30.49	75.49
524288	74.87	27.99	33.67	13.14	73.70	58.87	33.91	27.81	69.78	70.14	31.94	31.17	71.49
1048576	73.14	28.89	34.16	12.92	72.02	59.31	33.67	29.49	70.93	72.55	32.66	31.17	76.71
5242880	73.70	27.99	34.27	12.98	72.59	60.14	33.78	28.38	70.93	70.14	32.30	33.02	72.59

USB EXT2 read Performance

	3.04															
		DRA	\75x		DRA72x DRA71x											
Buffer	USB1 S	S	USB2 H	S	USB1 S	USB1 SS		S	USB1 S	S	USB2 HS		USB1			
size (bytes)	Read Throughput (Mbytes/sec)	Read CPU Load (%)	Read Throughput (Mbytes/sec													
102400	102.70	15.30	36.34	10.43	102.70	41.49	36.72	13.33	102.69	43.18	36.56	15.07	104.98			
262144	104.97	17.03	36.25	5.61	106.14	40.00	36.22	11.28	106.14	47.78	36.03	11.28	98.42			
524288	95.76	16.00	36.31	6.24	106.14	45.65	36.73	14.02	106.14	45.35	36.17	13.64	99.05			
1048576	104.72	17.13	36.41	7.27	106.14	43.18	37.17	16.12	106.14	48.86	36.67	14.34	100.24			
5242880	104.97	21.51	36.96	7.41	102.37	40.00	36.39	15.83	106.14	49.45	35.64	20.14	98.98			

USB - VFAT File System Performance

USB VFAT write Performance

							COD VIAI W	iito i o	Hommanice				
Buffer	3.04												
	DRA75x				DRA72x			DRA71x					
	USB1 SS		USB2 HS		USB1 SS USB2 H		USB2 H	S	S USB1 SS		USB2 HS		USB1
size (bytes)	Write Throughput (Mbytes/sec)	I (DI I	Write Throughput (Mbytes/sec)	Write CPU Load (%)	Throughput	Write CPU Load (%)	Write Throughput (Mbytes/sec)	Write CPU Load (%)	Write Throughput (Mbytes/sec)	Write CPU Load (%)	Write Throughput (Mbytes/sec)	Write CPU Load (%)	Write Throughput (Mbytes/sec

102400	52.15	22.11	26.40	12.76	50.16	47.76	24.82	24.57	48.36	53.77	25.35	27.00	51.72
262144	48.72	21.72	25.56	12.53	49.11	46.92	25.59	27.41	46.25	50.46	24.62	26.46	51.37
524288	48.81	22.01	25.67	11.67	49.99	45.69	25.21	23.10	47.16	51.63	24.75	26.16	50.86
1048576	50.79	22.19	26.48	13.23	50.35	48.53	25.23	26.65	47.91	51.20	24.19	26.19	49.60
5242880	50.70	21.61	25.61	11.29	50.35	48.53	26.74	27.58	47.34	51.17	24.77	25.31	50.86

USB	VFAT	read	Performance

								3.	04				
		DRA	∖75 x		DRA72x			DRA71x					
Buffer	USB1 SS		USB2 HS		USB1 S	USB1 SS		USB2 HS		S	USB2 HS		USB1
size (bytes)	Read Throughput (Mbytes/sec)	Read CPU Load (%)	Read Throughput (Mbytes/sec										
102400	98.95	19.90	33.12	5.75	98.92	43.33	33.70	8.7	99.79	50.53	32.98	18.06	98.79
262144	102.48	19.57	33.74	5.53	99.97	50.00	32.89	15.91	102.38	50.57	32.99	13.56	102.36
524288	102.61	21.39	33.96	6.90	98.23	42.22	33.54	17.38	102.75	48.81	32.99	20.31	102.32
1048576	102.46	20.00	34.15	4.35	98.26	44.09	33.58	20.25	102.40	53.33	33.58	21.45	102.59
5242880	94.71	15.38	33.25	4.30	97.71	47.47	33.70	16.11	99.78	52.17	32.58	11.64	102.54

USB Peripheral mode Support

NCM Gadget Support

The NCM(Network control Model) gadget driver that is used to send standard Ethernet frames using USB. The driver will create an Ethernet device by the name usbo.

Driver Features

Supports default DMA mode.

Features Not Supported

None

Constraint

None

Supported System Calls

open(), close(), read(), write(), ioctl()

Supported IOCTLS

None

Performance Benchmarks

Performance benchmarks were collected using the Iperf tool and default options were used to collect the throughput numbers.

USB NCM Gadget Performance

Setup : EVM as client and Linux Host PC as server command at EVM: iperf -c command at EVM: iperf -c command at Host: iperf -s

USB NCM Gadget Performance values - Client

TCP Window	DRA75X	DRA72X	DRA71X	DRA76X
Size(in KBytes)	Mbps	Mbps	Mbps	Mbps
16	103.6	100.2	95.9	105.0
32	221.5	208.8	201.2	222.1
64	300.0	292.0	284.0	311.0
128	286.0	285.0	284.0	295.0

- DRA75X: The cpu load is 12%, 21%, 32%, 31% for 16K, 32K, 64K, 128K window size respectively.
- DRA72X: The cpu load is 19%, 37%, 49%, 58% for 16K, 32K, 64K, 128K window size respectively.

- DRA71X: The cpu load is 21%, 45%, 61%, 59% for 16K, 32K, 64K, 128K window size respectively
- DRA76X: The cpu load is 13%, 21%, 33%, 32% for 16K, 32K, 64K, 128K window size respectively.

SATA Driver

The SATA controller compliance to Serial ATA Standard specification (revision 2.6) and Serial ATA Advanced Host Controller Interface Specification (AHCI) revision 1.1. The AHCI based SATA host controller supports both Gen1/2 speeds, 1.5-Gbps (SATA-1) and 3Gbps (SATA-2)

■ Please refer Technical Reference Module for more information.

Registers as a SCSI controller with the Linux SCSI Subsystem. SATA devices get registered as SCSI devices and can be accessed as "/dev/sd{*}" devices.

The driver supports the following features:

- 1 SATA HDD
- 2. CD/DVD support

* Enable CONFIG_ISO9660_FS through menuconfig (Menuconfig->File Systems->CD-ROM/DVD Filesytem->"ISO 9660 CDROM file system support")
* Enable CONFIG_BLK_DEV_SR through menuconfig (Menuconfig->Device Drivers->Scsi Device Support->"SCSI CD ROM support")

3. Port Multiplier support

* Enable CONFIG_SATA_PMP through menuconfig (Menuconfig->Device Drivers->Serial ATA and Paralle ATA drivers->SATA Port Multiplier support)

Features Not Supported

None.

Constraints

Supported System Calls

All Linux ATA/SCSI system calls related to SATA

Supported IOCTLs

Supports IOCTLS available in Linux SCSI and ATA frameworks and which are applicable for SATA. Refer kernel source or documentation for details.

Performance and Benchmarks

Western Digital 500GB (3Gbps)SATA (16M cache) HDD is used to measure the performance data

SATA - ext4 -File System Performance

■ Note: SATA is not supported on DRA71x.

SATA EXT4 write Performance

		P	rocessor SDK Linux	Automotive 3	3.04	
Buffer size (bytes)	DRA72	DRA72x		х	DRA76x	
241101 0120 (27100)	Write Throughput (Mbytes/sec)	Write CPU Load (%)	Write Throughput (Mbytes/sec)	Write CPU Load (%)	Write Throughput (Mbytes/sec)	Write CPU Load (%)
102400	109.37	38.78	109.28	17.44	109.65	15.0
262144	109.01	38.28	107.58	16.43	109.17	13.88
524288	106.77	39.02	108.32	18.74	108.42	13.76
1048576	112.83	37.46	109.36	17.89	109.75	13.62
5242880	110.94	35.48	107.22	17.98	109.27	14.46

SATA EXT4 read Performance

		Processor SDK Linux Automotive 3.04									
Buffer size (bytes)	DRA72	DRA72x		×	DRA76x						
Daniel 0.20 (8) (00)	Read Throughput (Mbytes/sec)	Read CPU Load (%)	Read Throughput (Mbytes/sec)	Read CPU Load (%)	Read Throughput (Mbytes/sec)	Read CPU Load (%)					
102400	108.67	23.35	118.52	12.97	118.93	10.59					
262144	107.05	24.15	120.02	12.87	118.96	10.01					
524288	112.57	26.58	111.19	12.68	116.69	9.88					
1048576	114.42	27.76	115.05	12.53	115.66	10.66					
5242880	112.22	26.85	113.19	13.34	113.37	11.5					

SATA - VFAT File System Performance

■ Note: SATA is not supported on DRA71x

SATA VFAT write Performance

	9 , 11,	T VI AI WIILE	o i i o i i i i i i i i i i i i i i i i								
Buffer size (bytes)		Processor SDK Linux Automotive 3.04									
	DRA72	2x	DRA74	х	DRA76x						
	Write Throughput (Mbytes/sec)	Write CPU Load (%)	Write Throughput (Mbytes/sec)	Write CPU Load (%)	Write Throughput (Mbytes/sec)	Write CPU Load (%)					
102400	70.81	45.82	70.77	30.48	81.45	26.05					
262144	70.66	46.07	69.56	29.92	81.42	25.33					
524288	70.06	45.1	70.05	29.94	81.62	25.69					
1048576	70.09	45.34	69.97	29.45	82.45	26.03					
5242880	69.61	44.71	70.86	30.01	82.18	26.2					

SATA VFAT read Performance

		Processor SDK Linux Automotive 3.04									
Buffer size (bytes)	DRA72	x	DRA74	x	DRA76x						
24.101 0120 (2)100)	Read Throughput (Mbytes/sec)	Read CPU Load (%)	Read Throughput (Mbytes/sec)	Read CPU Load (%)	Read Throughput (Mbytes/sec)	Read CPU Load (%)					
102400	122.44	26.95	126.28	14.33	126.35	11.59					
262144	124.02	29.07	126.25	15.15	126.18	11.09					
524288	123.44	30.4	126.18	14.88	126.5	12.08					
1048576	121.5	29.71	126.03	15.01	126.04	11.89					
5242880	124.18	32.25	126.01	15.39	125.99	10.88					

Power Management

Introduction

DRA7xx provides a rich set of power management features. The features include Clock control at module level, multiple power and voltage domains etc. It also provides the typical power consumption observed for different scenarios.

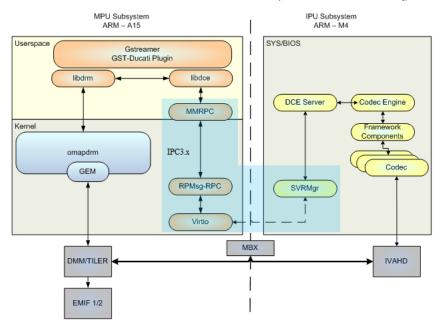
Lock Frequency of various PLLs

IP	DRA75x Frequency (MHz)	DRA72x Frequency (MHz)	DRA71x Frequency (MHz)	DRA76x Frequency (MHz)
MPU	As per OPP (1000/1176/1500)	As per OPP (1000/1176/1500)	As per OPP (600/800/1000)	As per OPP (1000/1176/1500/1800)
IPU	212.8	212.8	212.8	212.8
DSP	700	700	600	700
IVA	532	532	532	532
SGX	425	425	425	425
L3	266	266	266	266
DDR	532	667	667	667

Multimedia

Introduction

Multimedia consist of hardware accelerated video decoder(IVAHD). IVAHD subsystem is used for video decoding/encoding through libdce interface.



Supported Codecs

MJPEG decoder - version 01.00.16.01 H264 decoder - version 02.00.21.01 MPEG4 decoder - version 01.00.15.01 VC1 decoder - version 01.00.02.05 MPEG2 decoder - version 01.00.17.01 MPEG4 Encoder - Version 01.00.02.01 H264 Encoder - Version 02.00.09.01 MJPEG Encoder - Version 01.00.17.01

Supported Playback Application

GStreamer version 1.6 with following display sinks:

- waylandsink
- kmssink

Viddec3test: application that demonstrates viddec3 API usage for video decode and display (using KMS).

Features Not Supported

- viddec3test doesn't support mpeg1 video playback
- viddec3test doesn't support h264 level 5 streams

Constraints

- Dual decode with two h264 1080p streams with atleast one of them as level 5 stream is not supported
- Pipelines mentioned in http://processors.wiki.ti.com/index.php/DRA7xx_Processor_SDK_Linux_Automotive_Software_Developers_Guide are only supported

Performance Benchmarks

IVAHD decode performance on DRA75x

	H	264	MP	EG4	MP	EG2	
Stream Resolution	IVAHD FPS at load(in %)	Application FPS	IVAHD FPS at load(in %)	Application FPS	IVAHD FPS at load(in %)	Application FPS	Opp Frequency IVAHD at 532MHz IPU at 212MHz
720p	65.30 at 34%	184.54	59.28 at 29%	223.88	58.74 at 34%	160.56	
1080p	56.34 at 67%	86.82	57.26 at 58%	108.88	54.79 at 59%	113.26	IPU at 212MHz

IVAHD encode performance on DRA75x

Stream	H:	264	MP	EG4	Opp Frequency	
Resolution	IVAHD FPS at load(in %)	Application FPS	IVAHD FPS at load(in %)	Application FPS		
720p	58.32 at 40%	156.06	55.25 at 41%	145.10	IVAHD at 532MHz	
1080p	28.87 at 39%	75.94	27.54 at 41%	69.81	IPU at 212MHz	

IVAHD decode performance on DRA72x

TOTAL DI GOOGGO POLICIMICATO CHI DIGITALI									
Ct	H264		MPEG4		MPEG2				
Stream Resolution	IVAHD FPS at load(in %)	Application FPS	IVAHD FPS at load(in %)	Application FPS	IVAHD FPS at load(in %)	Application FPS	Opp Frequency		
720p	60 at 36%	183.53	59.95 at 30%	212.44	58.76 at 34%	223.35	IVAHD at 532MHz		
1080p	58.52 at 69%	87.37	58.92 at 60%	110.29	56.78 at 65%	105.16	IPU at 212MHz		

IVAHD encode performance on DRA72x

	H	264	MP	EG4		
Stream Resolution	IVAHD FPS at load(in %)	Application FPS	IVAHD FPS at load(in %)	Application FPS	Opp Frequency	
720p	55.73 at 38%	173.28	56.73 at 39%	165.60	IVAHD at 532MHz	
1080p	28.32 at 38%	84.12	26.5 at 40%	81.61	IPU at 212MHz	

IVAHD decode performance on DRA71x

	H264		MPEG4		MPEG2			
Stream Resolution	IVAHD FPS at load(in %)	Application FPS	IVAHD FPS at load(in %)	Application FPS	IVAHD FPS at load(in %)	Application FPS	Opp Frequency	
720p	57.8 at 37%	136.60	59.41 at 30%	168.24	57.90 at 31%	171.88	IVAHD at 532MHz	
1080p	52.51 at 62%	65.81	57.92 at 58%	88.41	53.14 at 60%	87.01	IPU at 212MHz	

IVAHD encode performance on DRA71x

	H	264	MP	EG4	
Stream Resolution	IVAHD FPS at load(in %)	Application FPS	IVAHD FPS at load(in %)	Application FPS	Opp Frequency
720p	53.13 at 37%	113.12	53.25 at 36%	103.47	IVAHD at 532MHz
1080p	25.32 at 35%	54.51	25.31 at 37%	50.78	IPU at 212MHz

IVAHD decode performance on DRA76x

IVARD decode performance on DRA76x									
	H264		MPEG4		MPEG2				
Stream Resolution	IVAHD FPS at load(in %)	Application FPS	IVAHD FPS at load(in %)	Application FPS	IVAHD FPS at load(in %)	Application FPS	Opp Frequency		
720p	58.08 at 33%	-	58.58 at 28%	-	57.55 at 29%	-	IVAHD at 532MHz		
1080p	53.01 at 60%	-	58.50 at 55%	-	52.53 at 57%	-	IPU at 212MHz		

IVAHD encode performance on DRA76x

107412 Onesde performance on 2144 ex								
	H	264	MP	EG4				
Stream Resolution	IVAHD FPS at load(in %)	Application FPS	IVAHD FPS at load(in %)	Application FPS	Opp Frequency			
720p	66.14 at 47%	-	65.34 at 47%	-	IVAHD at 532MHz			
1080p	33.29 at 45%	-	32.9 at 47%	-	IPU at 212MHz			

Performance is calculated using the gstreamer video decoder application with the following command:

 ${\tt gst-launch-1.0\ playbin\ uri=file://<Path\ to\ stream>\ video-sink="kmssink\ sync=false"}$

• Performance is calculated using the gstreamer video encoder application with the following command :

gst-launch-1.0 videotestsrc num-buffers=250 ! 'capture-format' ! <ducati encoder> ! fakesink

Graphics

GC320

Introduction

GC320 is a 2D GPU core from Vivante Technologies. The GC320 2D engine takes surfaces and performs functions like blending, filtering, rotation, overlay, resizing, transparency, and other dynamic effects.

Driver Features

Vivante provides Hardware and Platform independent API for its 2D GPU series. Vivante software includes 2D control mechanisms which allow the user to implement customized applications and drivers using the Vivante 2D –specific API. The API relies on a HAL (Hardware Abstraction Layer) designed to simplify the complexity of graphics software development and hide platform and architecture dependent code. The HAL is portable across different platforms and architectures without changing the core—all platform and architecture dependent code lives within a tiny shell around the core.

Performance Benchmarks

 $GC320\ unified\ driver\ has\ been\ validated\ for\ few\ performance\ benchmarking\ test cases.$

GC320 performance measures

Operation	Source format	Destination Format	Source Resolution	Destination Resolution	DRA75x (MPix/s)	DRA72x (MPix/s)
BitBlit	RGB565	RGB565	640x480	640x480	819.2	620.6
BitBlit	RGB565	RGB565	1280x720	1280x720	930.9	644.4
BitBlit	RGB565	RGB565	1920x1080	1920x1080	917.5	641.9
BitBlit	A8R8B8G8	A8R8B8G8	640x480	640x480	415.1	316.7
BitBlit	A8R8B8G8	A8R8B8G8	1280x720	1280x720	494.1	312.9
BitBlit	A8R8B8G8	A8R8B8G8	1920x1080	1920x1080	503.3	314.4
StretchBlit	RGB565	RGB565	320x240	640x480	333.9	330.3
StretchBlit	RGB565	RGB565	640x360	1280x720	335.7	333.3
StretchBlit	RGB565	RGB565	470x270	1920x1080	338.5	337.7
StretchBlit	A8R8B8G8	A8R8B8G8	320x240	640x480	323.3	318.3
StretchBlit	A8R8B8G8	A8R8B8G8	640x360	1280x720	325.6	320.5
StretchBlit	A8R8B8G8	A8R8B8G8	480x270	1920x1080	330.4	327.3
FilterBlit	RGB565	RGB565	320x240	640x480	230.1	227.5
FilterBlit	RGB565	RGB565	640x360	1280x720	230.6	227.8
FilterBlit	RGB565	RGB565	470x270	1920x1080	241.6	240.2
FilterBlit	A8R8B8G8	A8R8B8G8	320x240	640x480	176.0	171.6
FilterBlit	A8R8B8G8	A8R8B8G8	640x360	1280x720	176.3	172.2

| FilterBlit | A8R8B8G8 | A8R8B8G8 | 480x270 | 1920x1080 | 189.7 | 187.9

SGX544-MP2

Introduction

The SGX544-MP2 is a multicore (dual-core) evolution of the PowerVR® SGX544 GPU from Imagination Technologies. The 3D graphics processing unit (GPU) accelerates 3-dimensional (3D) graphics applications and 2-dimensional (2D) composition operations.

Driver Features

The following specifications are supported on the platform:

- OpenGL ES 1.0
- OpenGL ES 1.1
- OpenGL ES 2.0
- EGL 1.4

Features Not Supported

The following specifications are not supported on the platform:

- OpenVG
- OpenGL ES 3.0

Performance Benchmarks

The following performance benchmarks were measured on DRA7xx EVM with GLBenchmark offscreen tests.

GLBenchmark 2.5 performance on DRA7xx

Benchmark	Test	FPS			
Delicilliark	Number	DRA75x	DRA72x	DRA71x	
GLBenchmark 2.1 Egypt Classic ETC1 - C16Z16 Offscreen	2000010	96	52	45	
GLBenchmark 2.5 Egypt HD ETC1 - C24Z16 Fixed timestep Offscreen	2500015	25	13	11	
GLBenchmark 2.5 Egypt HD ETC1 - C24Z16 Offscreen	2501011	29	15	13	
GLBenchmark 2.5 Egypt HD PVRTC4 - C24Z16 Offscreen	2501111	29	16	13	
GLBenchmark 2.5 Egypt HD ETC1->565 - C24Z16 Offscreen	2501411	29	15	13	

GLBenchmark 2.5 Vertex throughput on DRA7xx

Benchmark	Test	Mtriangles/sec			
Delicilliark	Number	DRA75x	DRA72x	DRA71x	
Triangle throughput: Textured 888 - C24Z16 Offscreen	2500311	46.64	20.25	18.72	

GLBenchmark 2.5 pixel throughput on DRA7xx

Benchmark	Test Number	MTexels/sec			
Belicilliark	rest Number	DRA75x	DRA72x	DRA71x	
Fill rate 888 - C24Z16 Offscreen	2500111	1476.32	775.01	688.72	

Wayland

Introduction

Wayland is a protocol that specifies the communication between the display server (called Wayland compositor) and its clients. The Wayland protocol is essentially only about input handling and buffer management. The handling of the input hardware relies on evdev in Linux, and similar components in other operating systems. The initial implementation, chiefly libwayland-server, libwayland-client, libwayland-EGL and the reference implementation Weston are published under the MIT License.

It is widely regarded as a replacement for the X Window System.

Wayland API documentation

The documentation from the Wayland project can be accessed here [[2] (http://wayland.freedesktop.org/docs/html/)]

Default supported clients

The list of clients and instructions on running them can be referenced from DRA7xx_Processor_SDK_Linux_Automotive_Software_Developers_Guide#Running_weston_clients

Performance Benchmarks

Performance benchmarks have not been run for this release.

Keystone= MAVRK=For C2000=For MSP430=For technical For technical technical OMAPL1=For OMAP35x=For DaVinci=For technical support on support on {{ support on technical technical support on MAVRK technical MultiCore devices, the C2000 support on OMAP please please post support on MSP430 1. switchcategory:MultiCore= support on please post your For technical s please post DaVincoplease please post OMAP please your questions in the your post your please post yo · For technical support on post your post your questions vour C6000 MultiCore questions on questions questions at MultiCore devices, please questions on auestions on auestions on on The **Forum** The OMAP http://e2e.ti.co on The post your questions in the The DaVinci The MSP430 The OMAP MAVRK For questions C2000 Forum. Please post or C6000 MultiCore Forum Forum. Please Forum Please Forum Toolbox related to the comments abo Forum. Please post • For questions related to post only Please post post only Forum. article **Proces BIOS MultiCore** Please post only the BIOS MultiCore SDK comments onlv comments Please post SDK (MCSDK), comments **SDK Linux** only about the comments about the (MCSDK), please use the only please use the comments about the Automotive L **BIOS Forum** article about the article comments **BIOS Forum** Sheet here. about the article about the Processor article Processor Please post only comments related Please article Processor }} to the article **Processor SDK Linux** comments related to **SDK Linux Processor** SDK Linux article Processor SDK Linux Automotive SDK Linux Automotive Processor the SDK Linux Automotive SDK Automotive Data Sheet Automotive Data Sheet here Automotive Data Sheet SDK Linux article Processor Data Sheet Data Sheet here. Automotive here. Linux Automotive Data Data Sheet here. Data Sheet here here. Sheet here. here.



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