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32 // Startup clock system with max DCO setting ~8MHz
33 CSCTL0_H = CSKEY >> 8; // Unlock clock registers (contrôle d'accées aux résistres)
34 CSCTL1 = DCOFSEL_3 | DCORSEL; // Set DCO to 8MHz
35 CSCTL2 = SELA_VLOCLK | SELS_DCOCLK | SELM_DCOCLK;
36 CSCTL3 = DIVA_1 | DIVS_1 | DIVM_1; // Set all dividers
37 CSCTL0_H = 0; // Lock CS registers
38
39 // Configure USCI_A0 for UART mode
40 UCA0CTLW0 = UCSWRST; // Put eUSCI in reset
41 UCA0CTLW0 |= UCSSSEL_SMCLK; // CLK = SMCLK
42 // Baud Rate calculation
43 // 8000000/(16*9600) = 52.083
44 // Fractional portion = 0.083
45 // User's Guide Table 21-4: UCBR5x = 0x04
46 // UCBRFx = int ( (52.083-52)*16) = 1
47 UCA0BR0 = 52; // 8000000/16/9600
48 UCA0BR1 = 0x00;
49 UCA0MCTLW |= UCOS16 | UCBRF_1;
50 UCA0CTLW0 &= ~UCSWRST; // Initialize eUSCI
51 UCA0IE |= UCRXIE; // Enable USCI_A0 RX interrupt
52
53 __bis_SR_register(LPM3_bits | GIE); // Enter LPM3, interrupts enabled
54 __no_operation(); // For debugger
55 //}
56
57 /* #if defined(__TI_COMPILER_VERSION__) || defined(__IAR_SYSTEMS_ICC__)
58 #pragma vector=USCI_A0_VECTOR
59 __interrupt void USCI_A0_ISR(void)
60 #elif defined(__GNUC__)
61 void __attribute__((interrupt(USCI_A0_VECTOR))) USCI_A0_ISR (void)
62 #else
63 #error Compiler not supported!
64 #endif
65 {
66     switch(__even_in_range(UCA0IV, USCI_UART_UCTXCFIFG))
67     {
68         case USCI_NONE: break;
69         case USCI_UART_UCRXIFG:
70             while(!(UCA0IFG&UCTXIFG));
71             UCA0TXBUF = UCA0RXBUF;
72             __no_operation();
73             break;
74         case USCI_UART_UCTXIFG: break;
75         case USCI_UART_UCSTIFG: break;
76         case USCI_UART_UCTXCFIFG: break;
77     }
78 */

```